

# Overview of the ACTS project

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for the ACTS Developers

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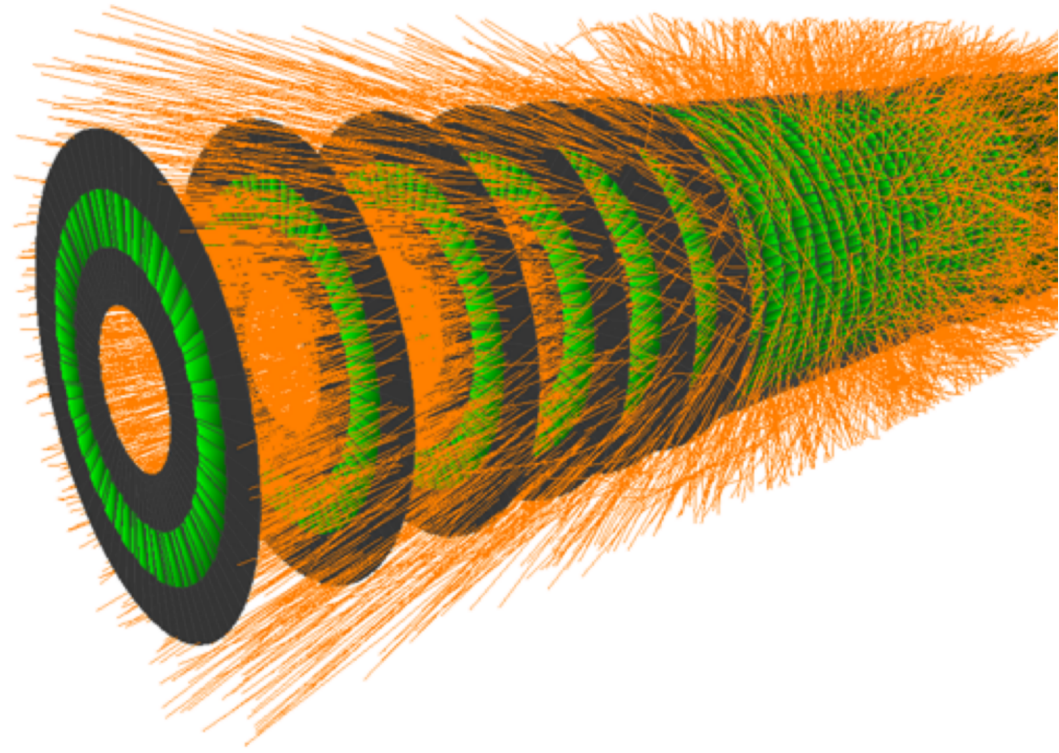
<http://cern.ch/acts>



**UNIVERSITÉ  
DE GENÈVE**

**FACULTÉ DES SCIENCES**

A high level overview



# A Common Tracking Software

You call us,  
we don't call you



A **standalone** C++ software **library** for **tracking**



- Minimal dependencies
- Sharable between experiments
- Not bound to experiment schedule

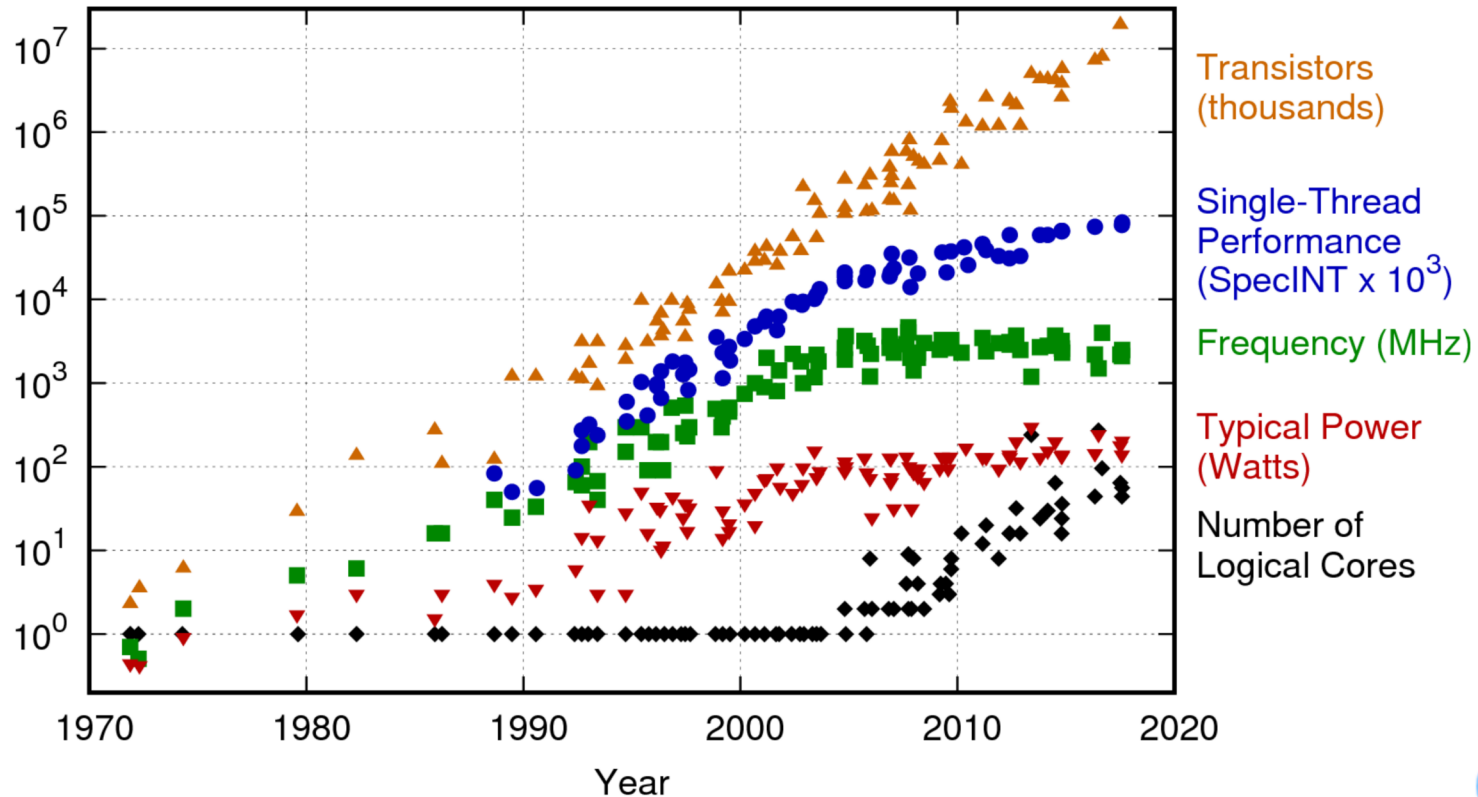


- Geometry & Navigation
- Propagation
- Track finding & fitting
- Vertexing
- ...



# Parallelization is necessary

42 Years of Microprocessor Trend Data



Original data up to the year 2010 collected and plotted by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond, and C. Batten  
New plot and data collected for 2010-2017 by K. Rupp





# Goals and guidelines

Retain/improve physics performance

Increase maintainability

Increase usability

Allow parallelization/  
vectorization

Base on established code (ATLAS), but with simplified design

Use **modern** C++ (14/17), e.g.

- `std::shared_ptr` et. al.
- strict const-correctness
- data is shared<sup>^</sup> mutable

Use Eigen linear algebra library

Unit and regression tests



# Maintainability

## ATLAS Stepper implementation

```
if (Jac) {
    // Jacobian calculation
    //
    double* d2A = &cache.pVector[24];
    double* d3A = &cache.pVector[31];
    double* d4A = &cache.pVector[38];
    double d2A0 = H0[2] * d2A[1] - H0[1] * d2A[2];
    double d2B0 = H0[0] * d2A[2] - H0[2] * d2A[0];
    double d2C0 = H0[1] * d2A[0] - H0[0] * d2A[1];
    double d3A0 = H0[2] * d3A[1] - H0[1] * d3A[2];
    double d3B0 = H0[0] * d3A[2] - H0[2] * d3A[0];
    double d3C0 = H0[1] * d3A[0] - H0[0] * d3A[1];
    double d4A0 = (A0 + H0[2] * d4A[1]) - H0[1] * d4A[2];
    double d4B0 = (B0 + H0[0] * d4A[2]) - H0[2] * d4A[0];
    double d4C0 = (C0 + H0[1] * d4A[0]) - H0[0] * d4A[1];
    double d2A2 = d2A0 + d2A[0];
    double d2B2 = d2B0 + d2A[1];
    double d2C2 = d2C0 + d2A[2];
    double d3A2 = d3A0 + d3A[0];
    double d3B2 = d3B0 + d3A[1];
    double d3C2 = d3C0 + d3A[2];
    double d4A2 = d4A0 + d4A[0];
    double d4B2 = d4B0 + d4A[1];
    double d4C2 = d4C0 + d4A[2];
    double d0 = d4A[0] - A00;
    double d1 = d4A[1] - A11;
    double d2 = d4A[2] - A22;
    double d2A3 = (d2A[0] + d2B2 * H1[2]) - d2C2 * H1[1];
    double d2B3 = (d2A[1] + d2C2 * H1[0]) - d2A2 * H1[2];
}
```

+ >1k more lines

## ACTS Eigen Stepper implementation

```
// use the adjusted step size
const double h = cache.step_size;

// When doing error propagation, update the associated Jacobian matrix
if (cache.cov_transport) {

    ActsMatrixD<7, 7> D = ActsMatrixD<7, 7>::Identity();
    const double conv = units::SI2Nat<units::MOMENTUM>(1);

    // This sets the reference to the sub matrices
    // dFdX is already initialised as (3x3) identity
    auto dFdT = D.block<3, 3>(0, 3);
    auto dFdL = D.block<3, 1>(0, 6);
    // dGdX is already initialised as (3x3) identity
    auto dGdT = D.block<3, 3>(3, 3);
    auto dGdL = D.block<3, 1>(3, 6);

    ActsMatrixD<3, 3> dk1dT = ActsMatrixD<3, 3>::Zero();
    ActsMatrixD<3, 3> dk2dT = ActsMatrixD<3, 3>::Identity();
    ActsMatrixD<3, 3> dk3dT = ActsMatrixD<3, 3>::Identity();
    ActsMatrixD<3, 3> dk4dT = ActsMatrixD<3, 3>::Identity();
}
```

VS



# Testing strategy

Unit tests for Core tools

- Interfaces & invariants

Larger core integration tests

- Tool combinations

Full examples

## Example Unit Test

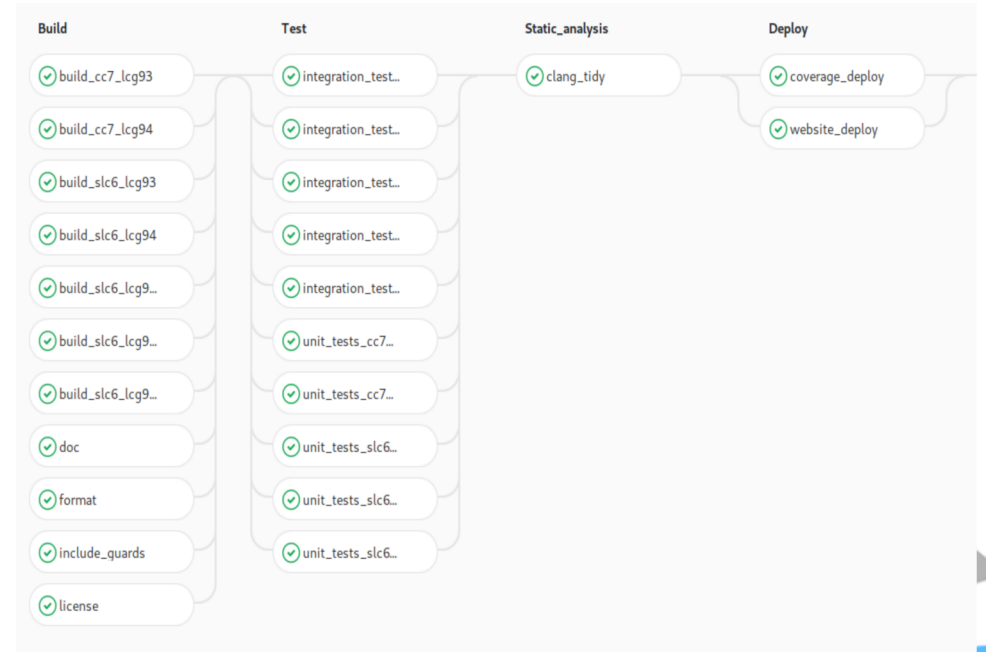
```
31 // Unit tests for RadialBounds constructors
32 BOOST_AUTO_TEST_CASE(RadialBoundsConstruction)
33 {
34     double minRadius(1.0), maxRadius(5.0), halfPhiSector(M_PI / 8.0);
35     // test default construction
36     // RadialBounds defaultConstructedRadialBounds; should be deleted
37     //
38     /// Test construction with radii and default sector
39     BOOST_TEST(RadialBounds(minRadius, maxRadius).type()
40               = SurfaceBounds::Disc);
41     //
42     /// Test construction with radii and sector half angle
43     BOOST_TEST(RadialBounds(minRadius, maxRadius, halfPhiSector).type()
44               = SurfaceBounds::Disc);
45     //
46     /// Copy constructor
47     RadialBounds original(minRadius, maxRadius);
48     RadialBounds copied(original);
49     BOOST_TEST(copied.type() = SurfaceBounds::Disc);
50 }
```

# Continuous integration

Run tests for every change  
(pull request)

- LCG93, LCG94
- SLC6, CentOS7
- GCC, clang

Additional (static) analyses



# Continuous integration / coverage

## GCC Code Coverage Report

Directory: ./

Date: 2019-01-10

Legend: low: < 75.0 % medium: >= 75.0 % high: >= 90.0 %

	Exec	Total	Coverage
Lines:	8684	11314	76.8 %
Branches:	13539	46826	28.9 %

File	Lines	Branches
Core/include/Acts/Detector/DetachedTrackingVolume.hpp	0.0 % 0 / 2	100.0 % 0 / 0
Core/include/Acts/Detector/GlueVolumesDescriptor.hpp	50.0 % 2 / 4	100.0 % 0 / 0
Core/include/Acts/Detector/TrackingGeometry.hpp	100.0 % 1 / 1	100.0 % 0 / 0
Core/include/Acts/Detector/TrackingVolume.hpp	75.0 % 18 / 24	50.0 % 6 / 12
Core/include/Acts/Detector/detail/BoundaryIntersectionSorter.hpp	89.3 % 25 / 28	47.0 % 62 / 132
Core/include/Acts/Detector/detail/DefaultDetectorElementBase.hpp	100.0 % 2 / 2	100.0 % 0 / 0
Core/include/Acts/Detector/detail/TrackingVolume.ipp	100.0 % 31 / 31	57.6 % 132 / 229
Core/include/Acts/EventData/ChargePolicy.hpp	100.0 % 9 / 9	100.0 % 0 / 0
Core/include/Acts/EventData/Measurement.hpp	60.7 % 34 / 56	0.5 % 9 / 1845
Core/include/Acts/EventData/ParameterSet.hpp	100.0 % 82 / 82	7.8 % 92 / 1182
Core/include/Acts/EventData/SingleBoundTrackParameters.hpp	100.0 % 52 / 52	50.0 % 24 / 48
Core/include/Acts/EventData/SingleCurvilinearTrackParameters.hpp	72.1 % 31 / 43	40.6 % 26 / 64
Core/include/Acts/EventData/SingleTrackParameters.hpp	98.0 % 50 / 51	50.0 % 38 / 76
Core/include/Acts/EventData/TrackParametersBase.hpp	66.7 % 6 / 9	100.0 % 0 / 0
Core/include/Acts/EventData/TrackState.hpp	81.5 % 44 / 54	9.1 % 31 / 342
Core/include/Acts/EventData/detail/coordinate_transformations.hpp	100.0 % 28 / 28	55.0 % 33 / 60
Core/include/Acts/EventData/detail/initialize_parameter_set.hpp	100.0 % 14 / 14	50.0 % 6 / 12
Core/include/Acts/EventData/detail/make_projection_matrix.hpp	100.0 % 14 / 14	50.0 % 234 / 468
Core/include/Acts/EventData/detail/residual_calculator.hpp	100.0 % 11 / 11	100.0 % 0 / 0
Core/include/Acts/EventData/detail/surface_getter.hpp	100.0 % 4 / 4	100.0 % 0 / 0
Core/include/Acts/EventData/detail/trackstate_manipulation.hpp	96.9 % 31 / 32	6.1 % 12 / 196
Core/include/Acts/EventData/detail/trackstate_sorters.hpp	100.0 % 4 / 4	50.0 % 1 / 2
Core/include/Acts/Extrapolator/MaterialInteractor.hpp	76.3 % 74 / 97	25.5 % 239 / 936
Core/include/Acts/Extrapolator/Navigator.hpp	91.3 % 407 / 446	42.5 % 2285 / 5378
Core/include/Acts/Extrapolator/SurfaceCollector.hpp	100.0 % 11 / 11	66.7 % 12 / 18
Core/include/Acts/Extrapolator/detail/InteractionFormulas.hpp	68.1 % 94 / 138	43.0 % 37 / 86
Core/include/Acts/Fitter/GainMatrixSmoother.hpp	100.0 % 24 / 24	51.0 % 49 / 96
Core/include/Acts/Fitter/GainMatrixUpdater.hpp	100.0 % 31 / 31	5.0 % 120 / 2402
Core/include/Acts/Fitter/KalmanFitter.hpp	68.6 % 81 / 118	31.9 % 67 / 210
Core/include/Acts/Fitter/detail/VoidKalmanComponents.hpp	100.0 % 4 / 4	100.0 % 0 / 0
Core/include/Acts/Layers/ConeLayer.hpp	100.0 % 7 / 7	50.0 % 3 / 6
Core/include/Acts/Layers/CylindricalLayer.hpp	100.0 % 5 / 5	50.0 % 3 / 6



# Concurrency tests

H. Grasland

Run full example chain parallelized

Check possible bottlenecks

Check access violations bottlenecks

Check serial/parallelized consistency



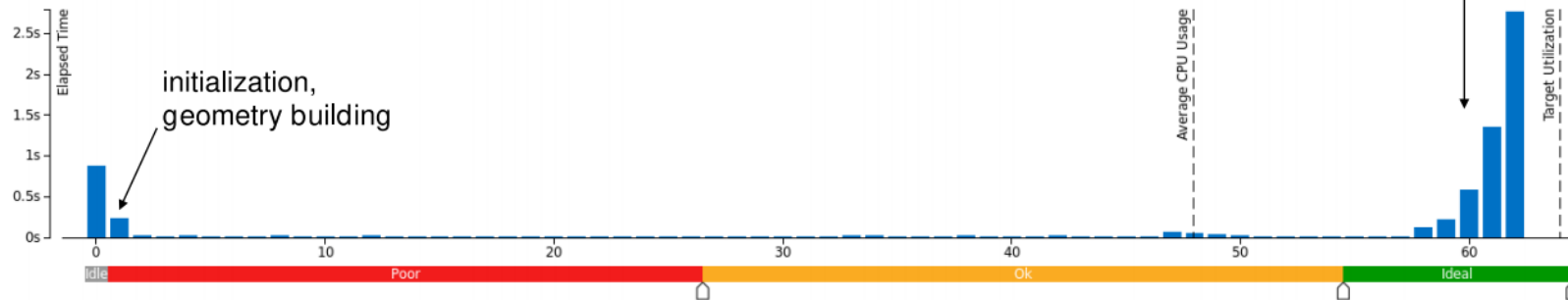
Intel Xeon e5-2698

32 cores

64 threads

## CPU Usage Histogram

This histogram displays a percentage of the wall time the specific number of CPUs were running simultaneously. Spin and Overhead time adds to the Idle CPU usage value.



# Project organization

Hosted on CERN Gitlab

Core library

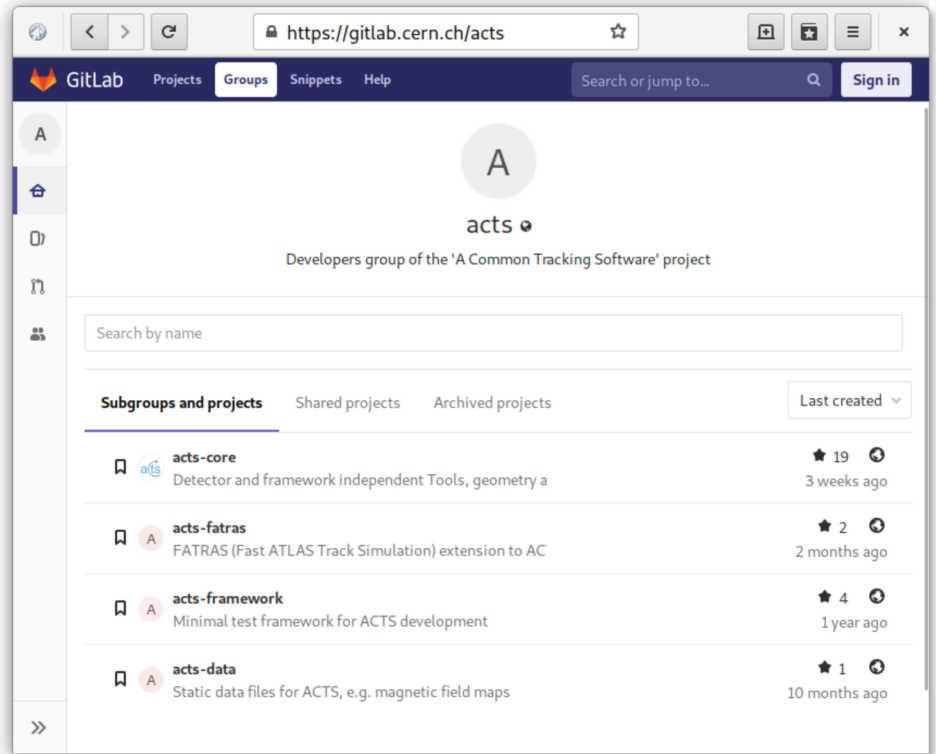
- **This** is what should be used by an experiment

Fast simulation tools

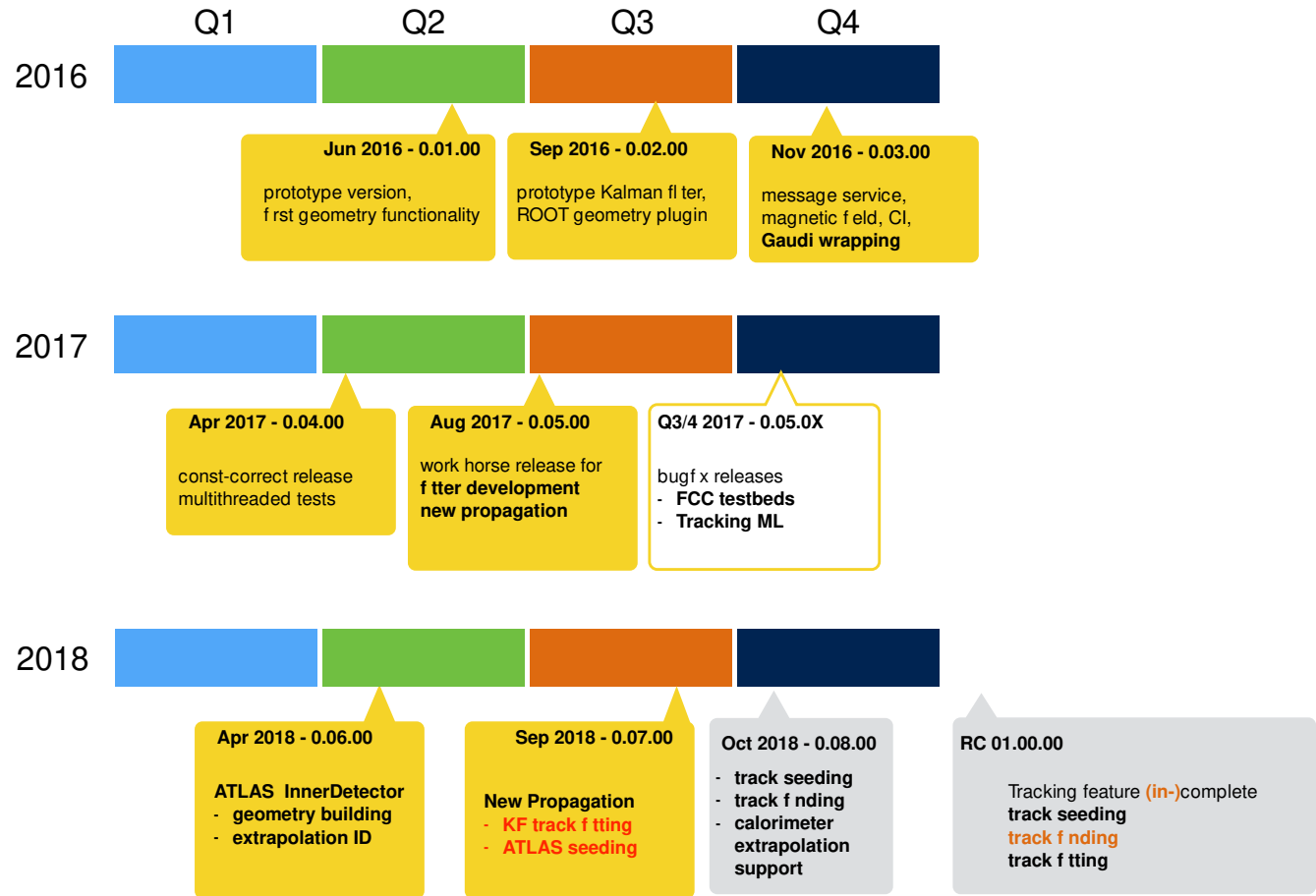
Minimal event framework

Data files for tests

<https://gitlab.cern.ch/acts>

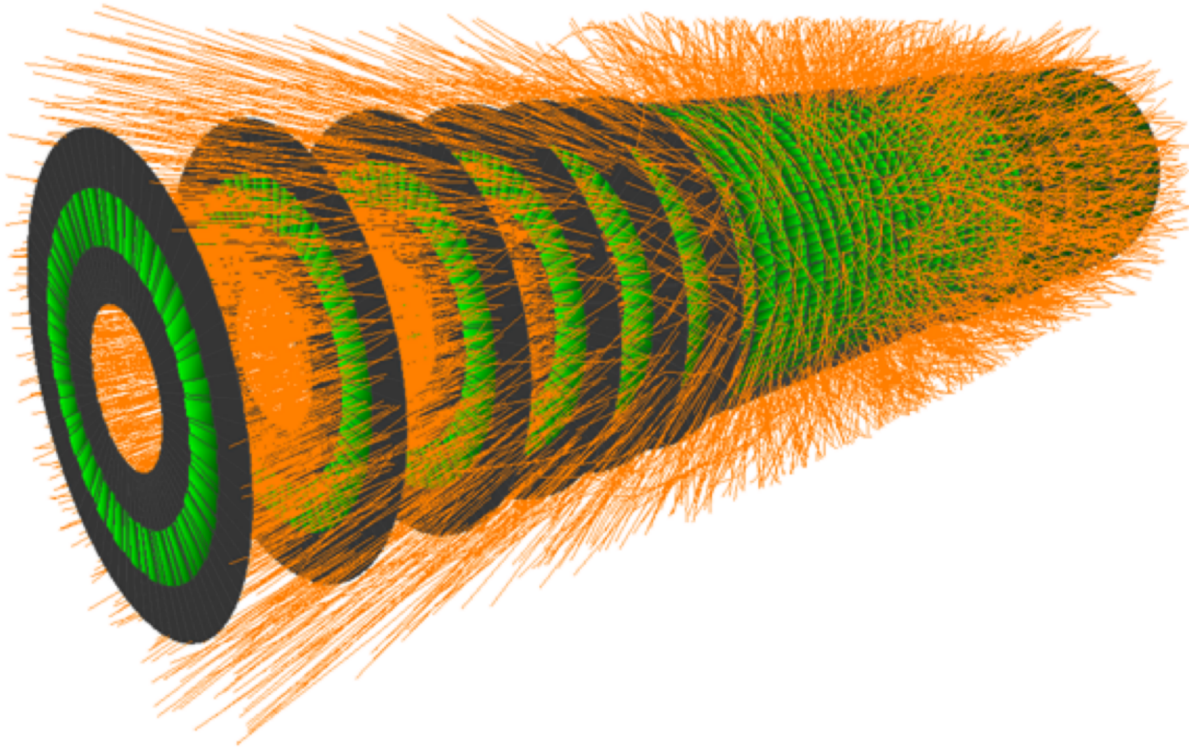


# Timeline





# Application: TrackML Challenged



Native ACTS Geometry

Pixels & strips in barrels & disks

ATLAS magnetic field

Fast simulation w/  
multiple scattering,  
nuclear interactions

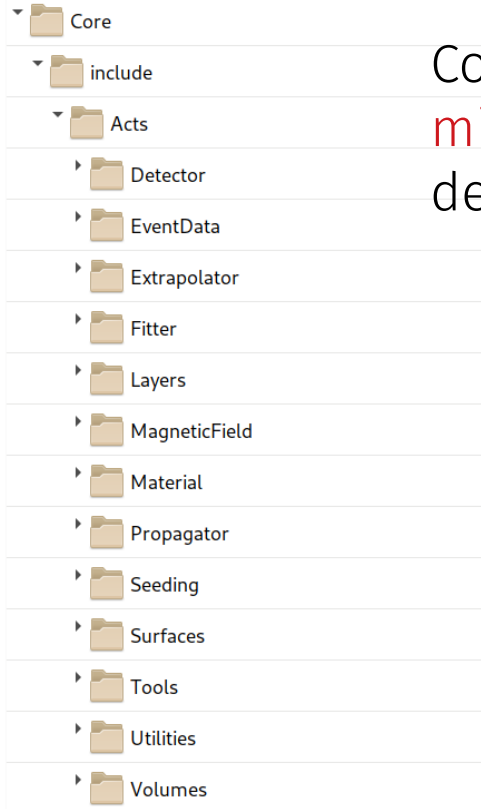
<https://sites.google.com/site/trackmlparticle/>



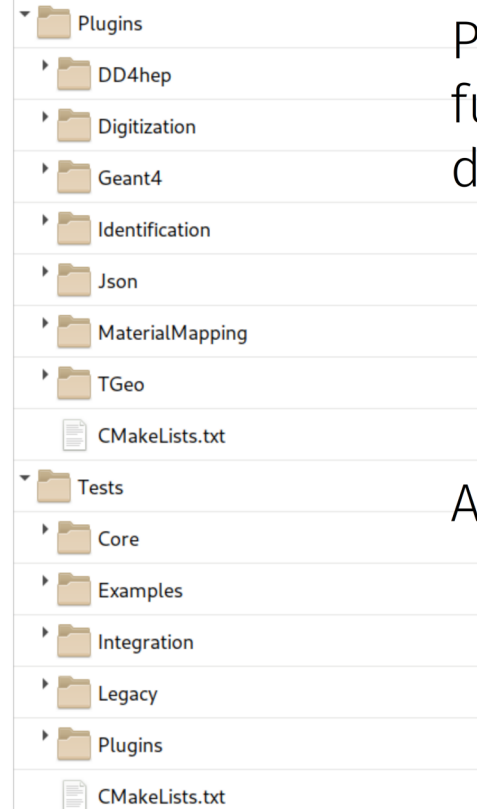
ACTS components



# Structure on disk



Core w/  
**minimal**  
dependencies

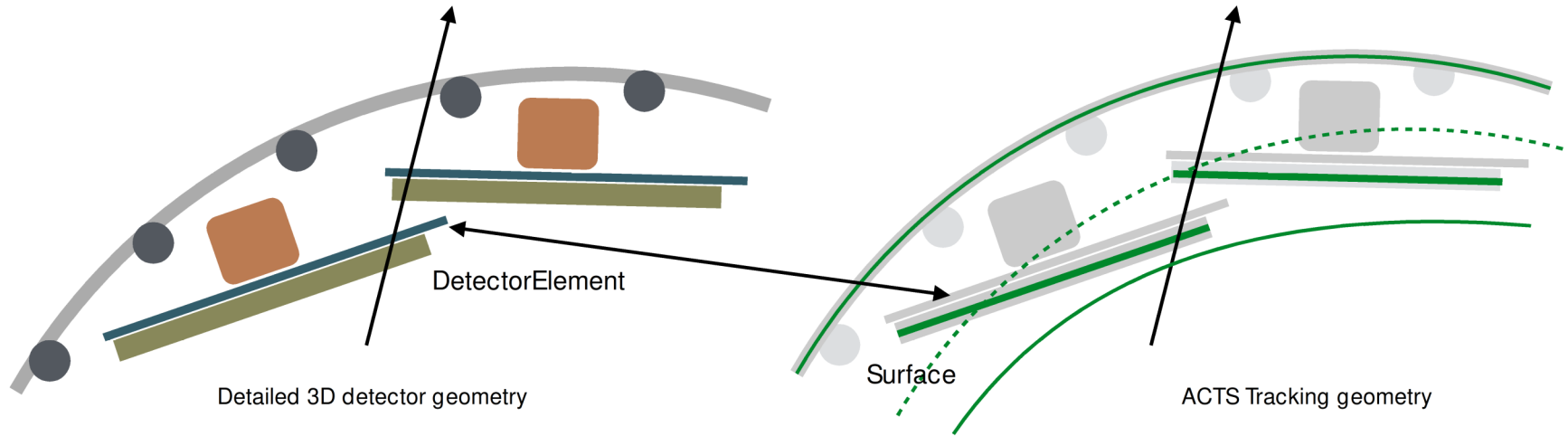


Plugins for optional  
functional w/ extra  
dependencies

Automated tests



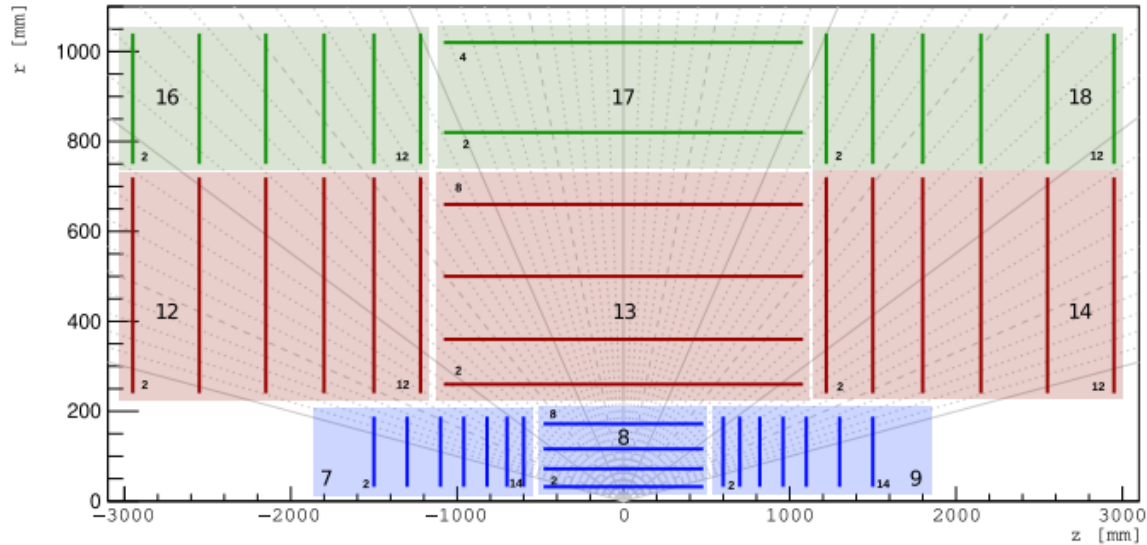
# (Tracking) Geometry



Simplified geometry based on tracking surfaces



# Geometry Layout



Organized by

- Volume
- Layer
- Module

for navigation

Generic example detector (TrackML)



# (Minimal) event data model

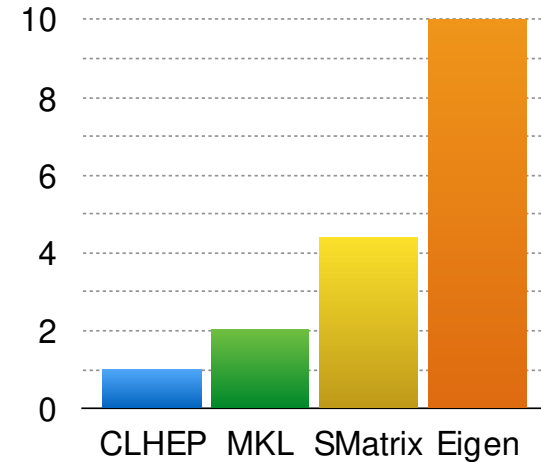
## Tracks

- `Acts::TrackParameter`
- `Acts::SingleBoundParameter`
- `Acts::SingleCurvilinearParameter`

## Measurements

- `Acts::Measurement`
- `Acts::CalibratedMeasurement`

Based on Eigen library

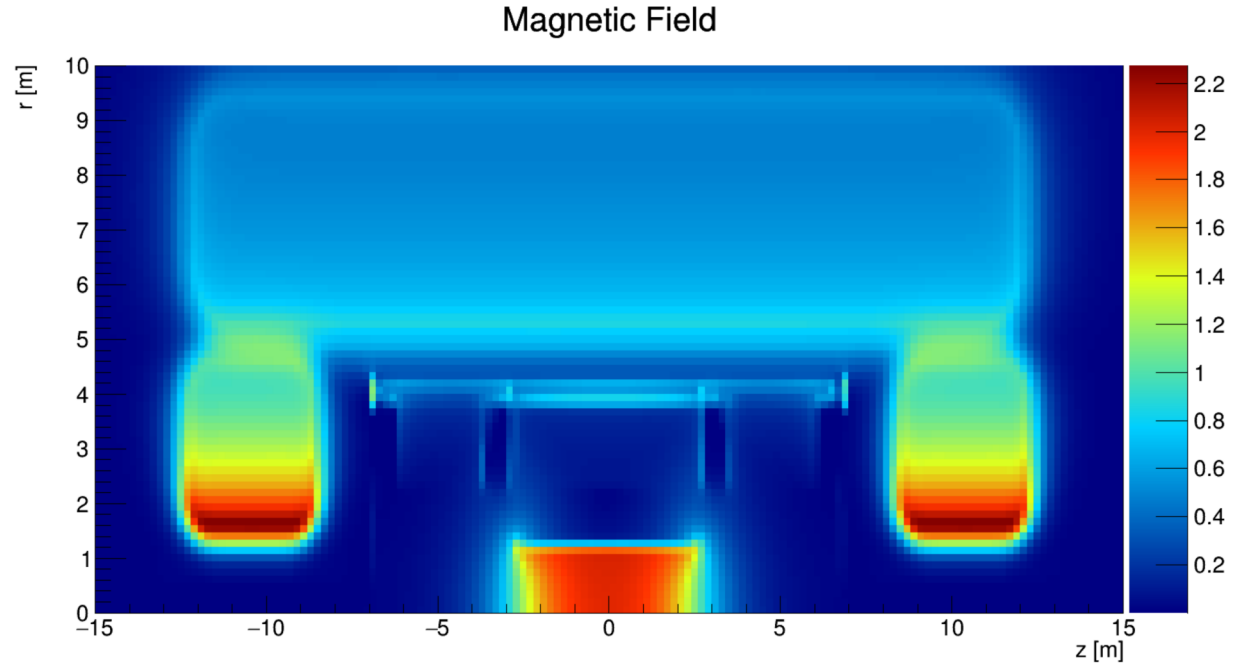
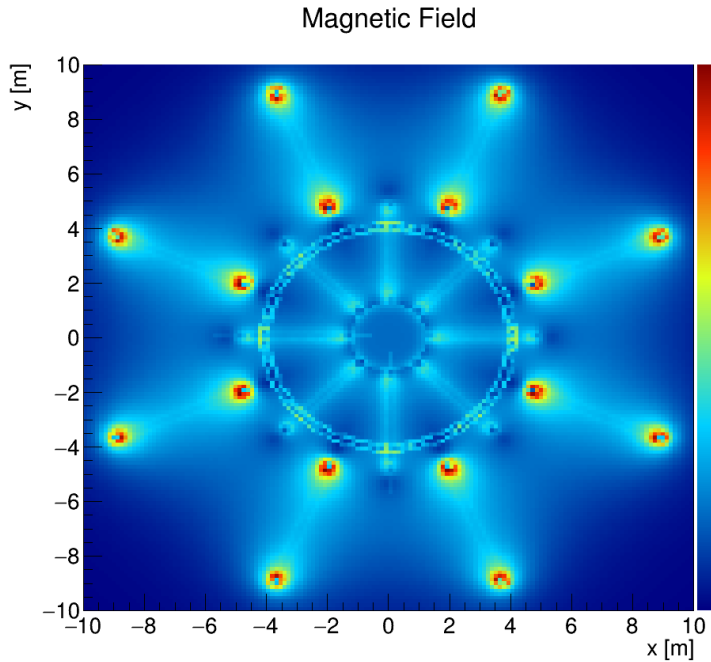


ATLAS LS1 performance comparison  
Speed 5×5 matrix multiplication



# Magnetic fields

Example: ATLAS field



Interpolated field maps  
Different examples available



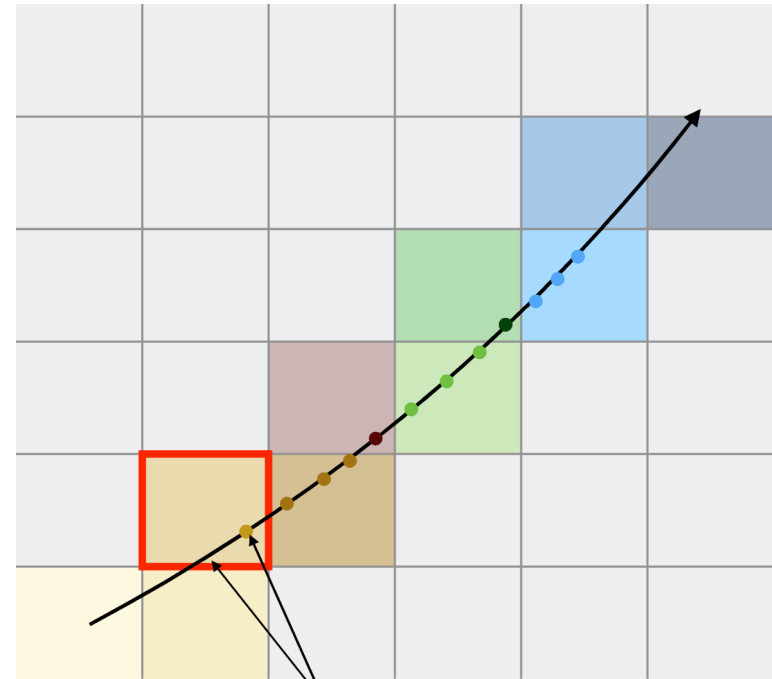
# Magnetic field cell caching

Cache local extrapolation cell

Performance improvements

- 20% in simulation
- Few % in reconstruction

Localizes field access



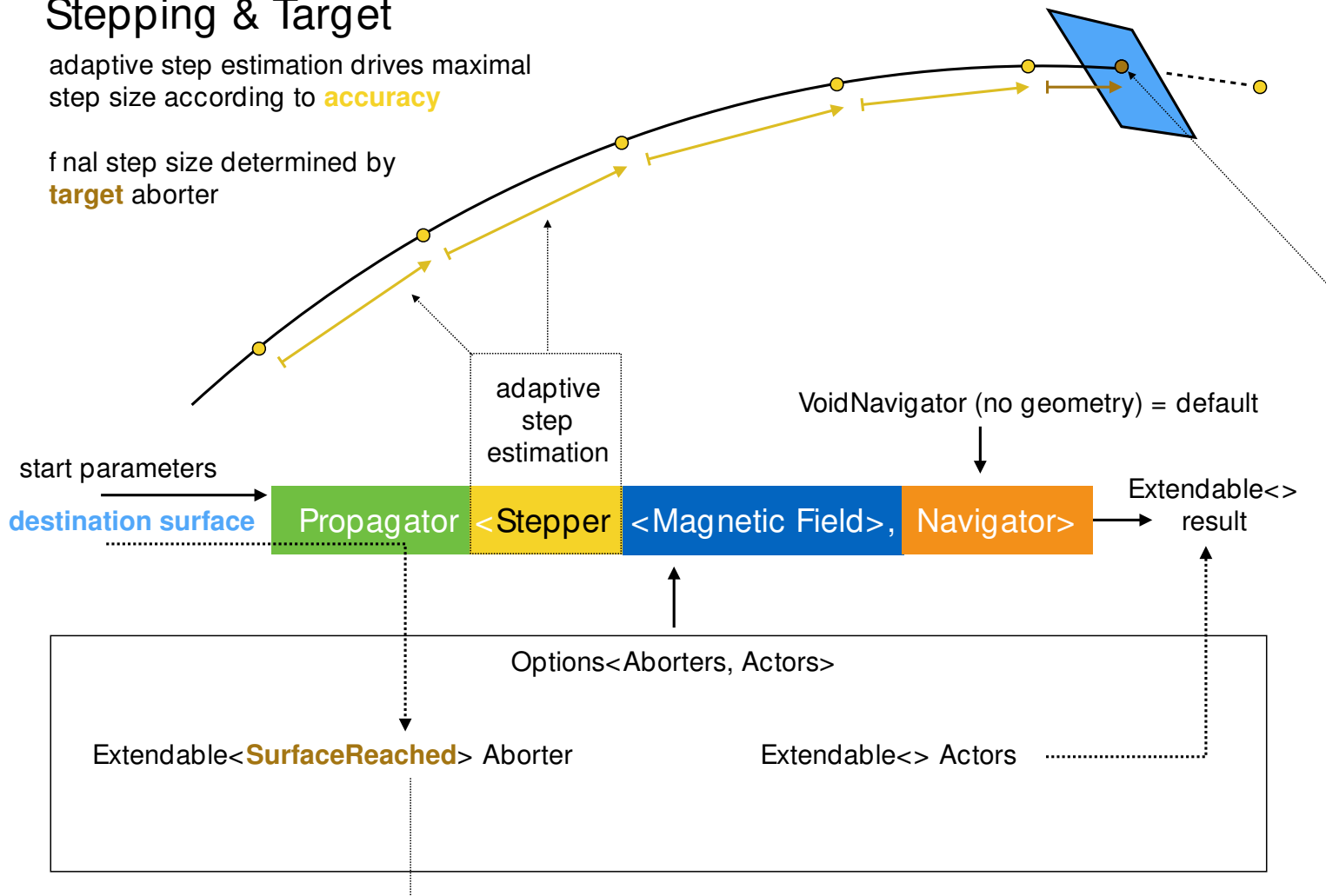
Field look up in Runge-Kutta integration



# Stepping & Target

adaptive step estimation drives maximal step size according to **accuracy**

final step size determined by **target** aborter

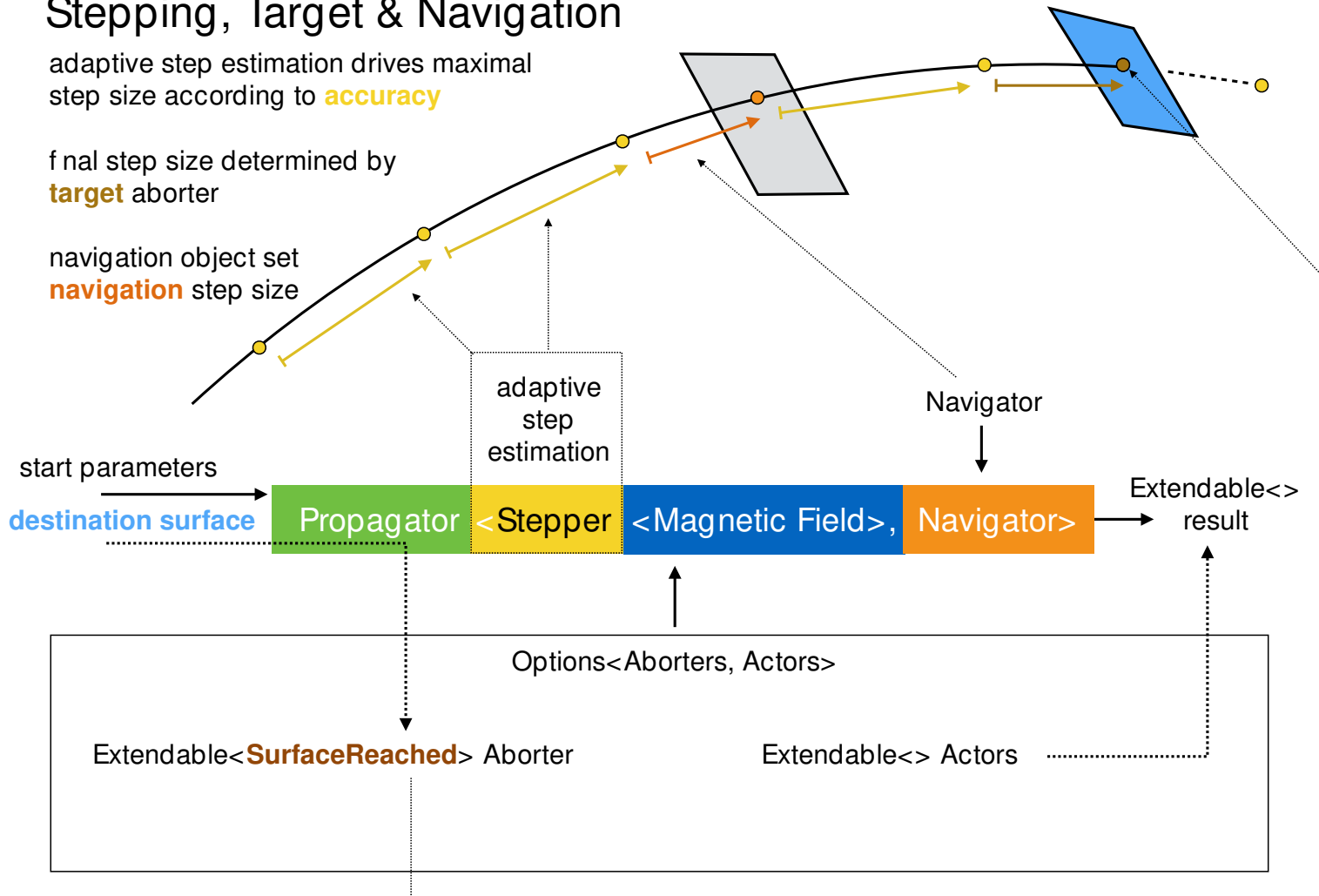


# Stepping, Target & Navigation

adaptive step estimation drives maximal step size according to **accuracy**

final step size determined by **target** aborter

navigation object set **navigation** step size



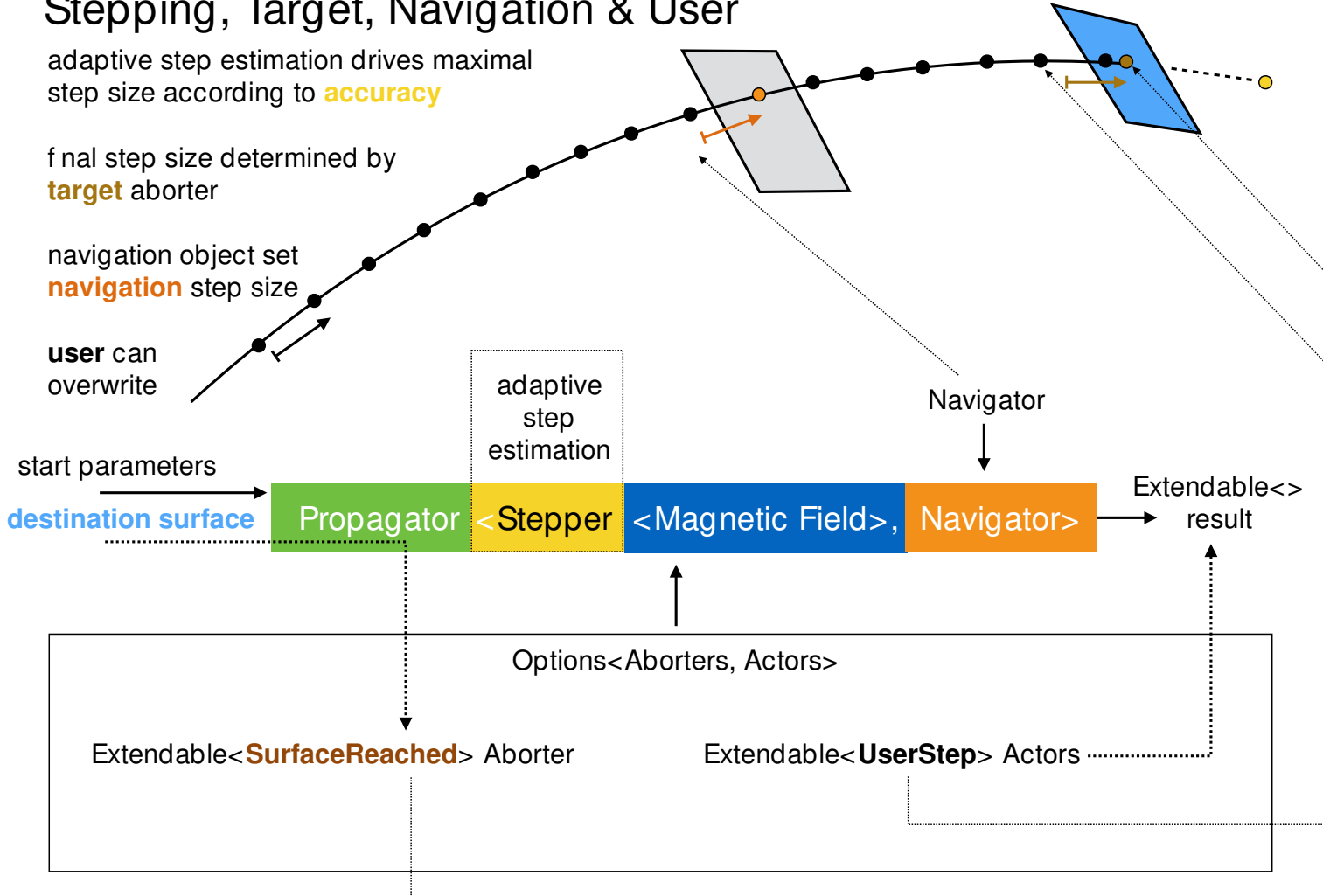
# Stepping, Target, Navigation & User

adaptive step estimation drives maximal step size according to **accuracy**

final step size determined by **target** aborter

navigation object set **navigation** step size

**user** can overwrite



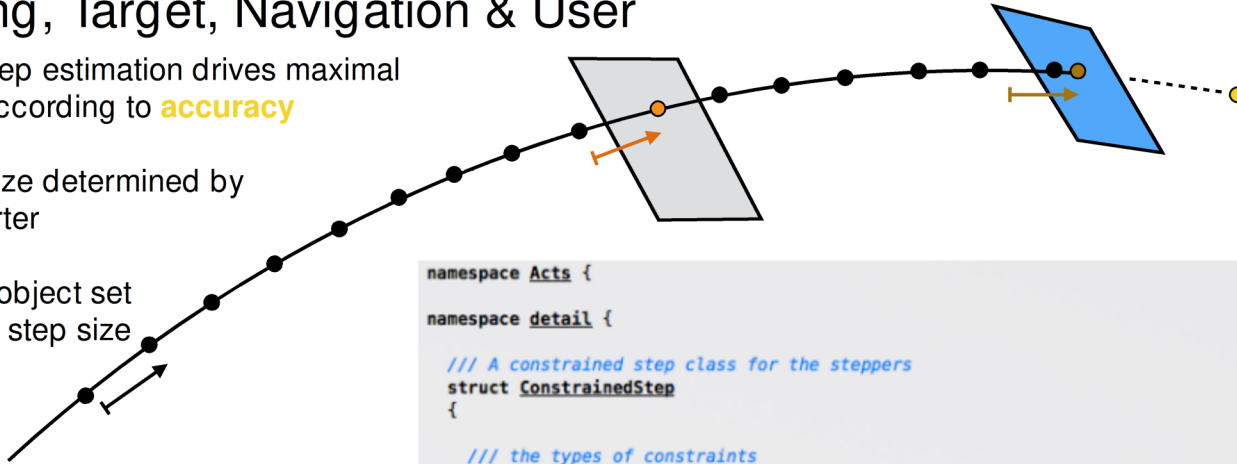
# Stepping, Target, Navigation & User

adaptive step estimation drives maximal step size according to **accuracy**

final step size determined by **target** aborter

navigation object set **navigation** step size

user can overwrite



ConstrainedStep

```
namespace Acts {
namespace detail {
    /// A constrained step class for the steppers
    struct ConstrainedStep
    {
        /// the types of constraints
        /// from accuracy - this can vary up and down given a good step estimator
        /// from actor - this would be a typical navigation step
        /// from aborter - this would be a target condition
        /// from user - this is user given for what reason ever
        enum Type : int { accuracy = 0, actor = 1, aborter = 2, user = 3 };

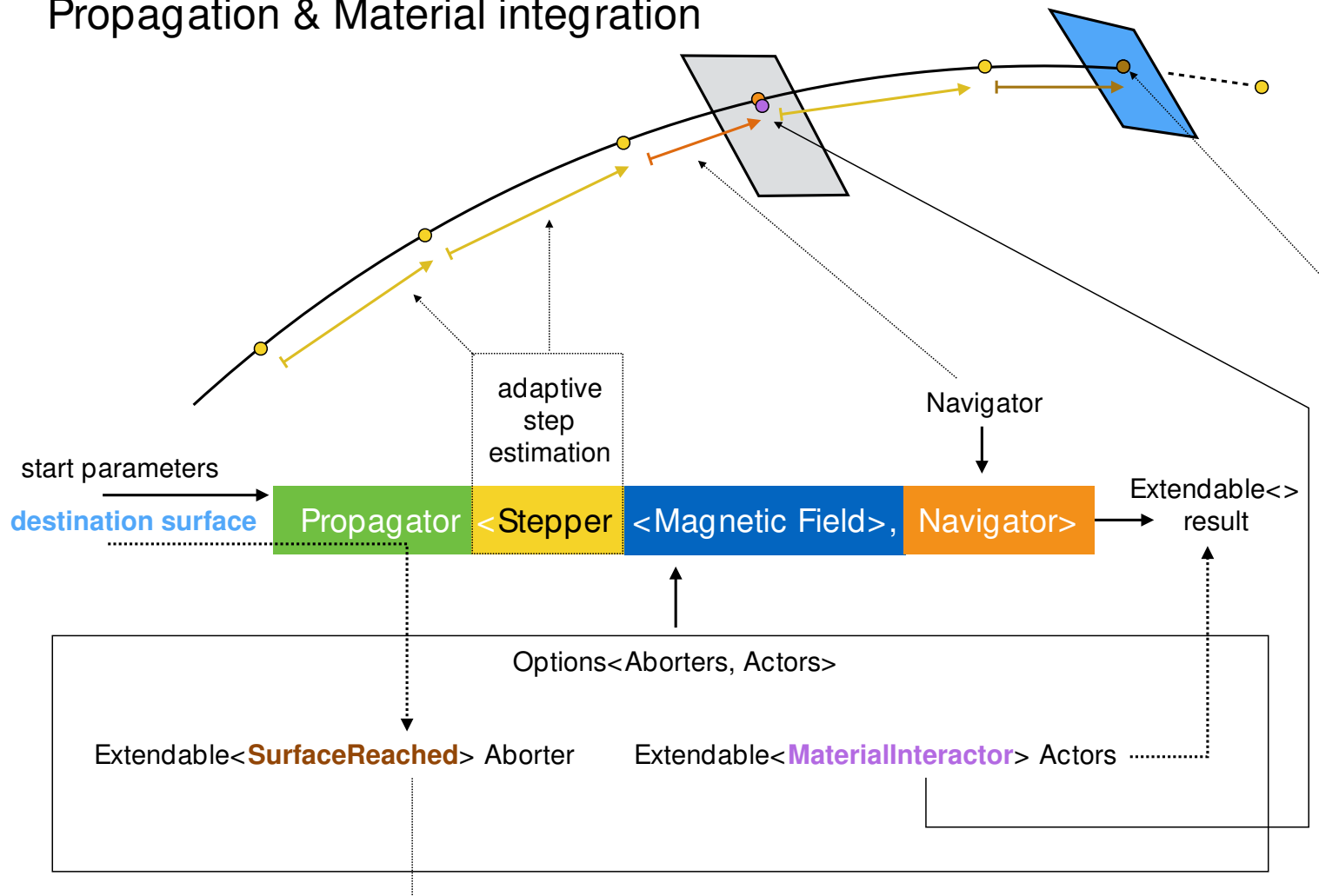
        /// the step size tuple
        std::array<double, 4> values = {{std::numeric_limits<double>::max(),
                                        std::numeric_limits<double>::max(),
                                        std::numeric_limits<double>::max(),
                                        std::numeric_limits<double>::max()}};

        /// The Navigation direction
        NavigationDirection direction = forward;

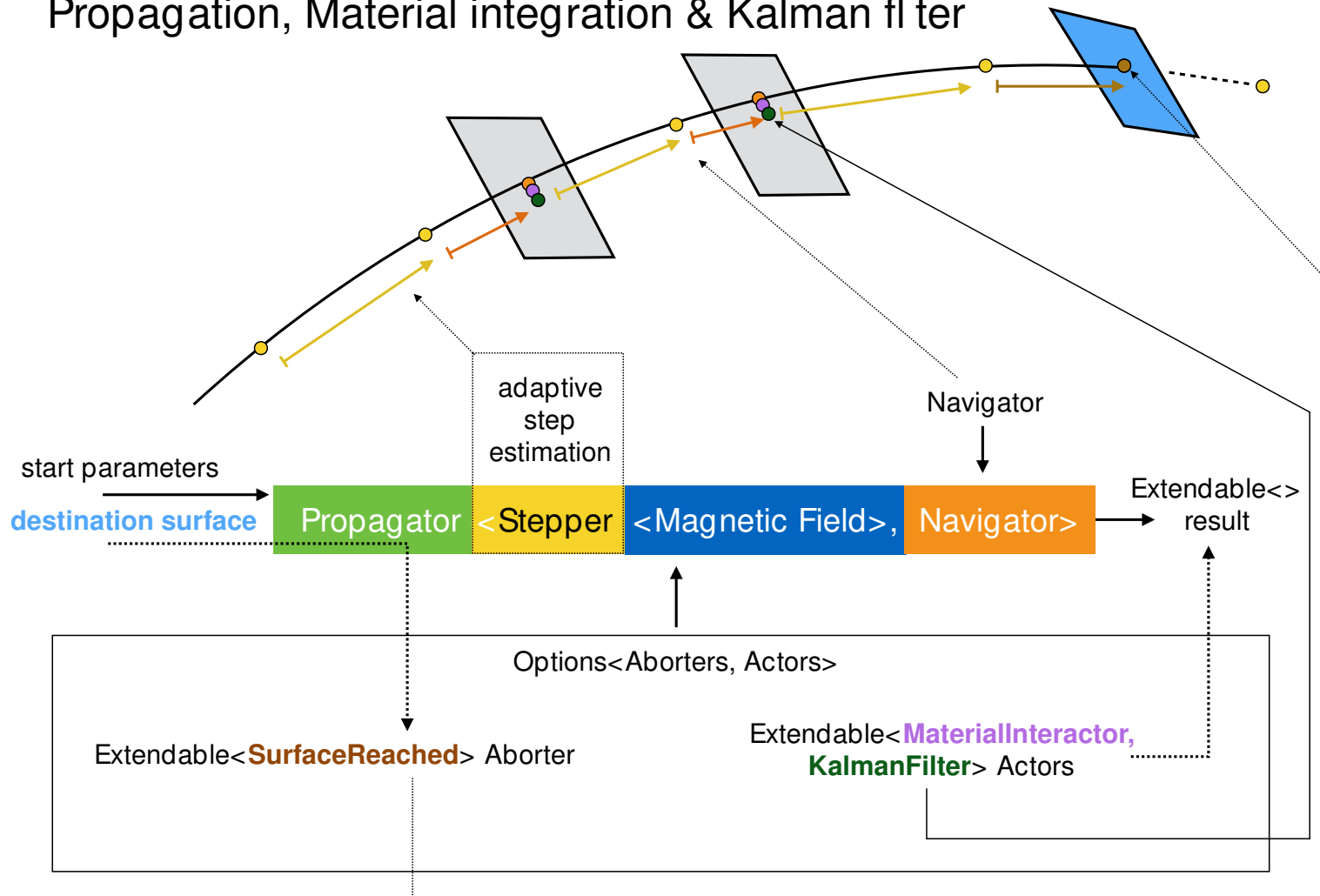
        /// update the step size of a certain type
        /// - for accuracy and navigation that can go either way
        /// - for aborters it can only get (direction)*smaller
        /// @param value is the new value to be updated
        /// @param type is the constraint type
        void
        update(const double& value, Type type)
        {
            if (type != aborter || (direction * values[type] > direction * value))
                values[type] = value;
        }
    }
}
```



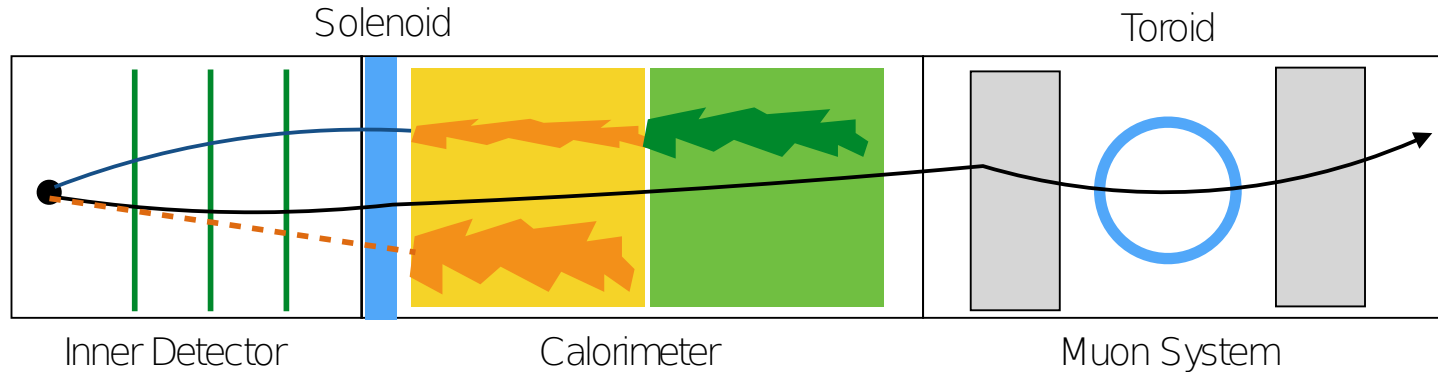
# Propagation & Material integration



# Propagation, Material integration & Kalman filter



# Beyond the (ATLAS) inner tracking detector



Mostly covered

Requires STEP  
propagator  
(prototype in 0.8.0)  
Requires geometry  
support

Not yet covered



# Open questions

## Tools

Non-silicon detectors

Track follower

Global  $\chi^2$  track fitter (ATLAS)

Vertex finder

Vertex fitter (in-progress)

...

## Design

Vectorizable DEM, AoS vs. SoA

Parallelizable conditions handling (Paul)

Detector alignment

Parallelization within ACTS

...





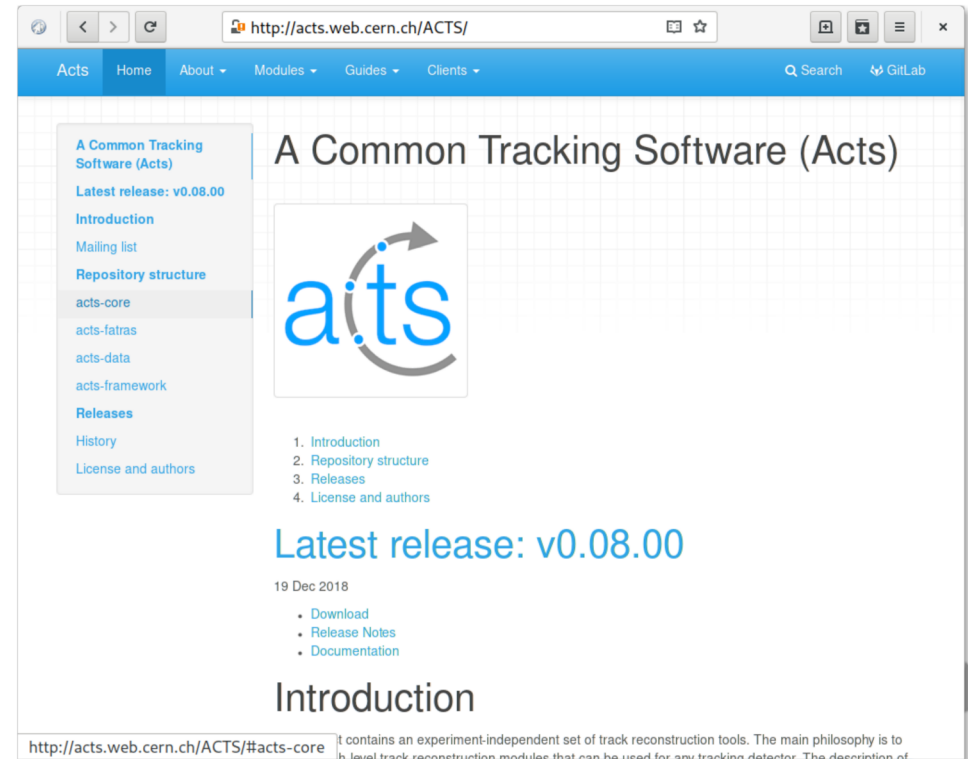
# Summary

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A **standalone** C++ software **library** for **tracking**

- Derived from ATLAS code
- Basic functionality available

Progressing towards full tracking solution

A screenshot of a web browser displaying the ACTS website. The browser's address bar shows the URL 'http://acts.web.cern.ch/ACTS/'. The website has a blue navigation bar with links for 'Acts', 'Home', 'About', 'Modules', 'Guides', and 'Clients'. A search bar and a 'GitLab' icon are also present. The main content area features a grid background. On the left, there is a sidebar menu with links for 'A Common Tracking Software (Acts)', 'Latest release: v0.08.00', 'Introduction', 'Mailing list', 'Repository structure', 'acts-core', 'acts-fatras', 'acts-data', 'acts-framework', 'Releases', 'History', and 'License and authors'. The 'acts-core' link is highlighted. The main content area displays the title 'A Common Tracking Software (Acts)' and a logo for 'aits' (a lowercase 'a' and 'i' in blue, followed by 'ts' in blue, with a grey circular arrow around the 'i'). Below the logo is a numbered list: 1. Introduction, 2. Repository structure, 3. Releases, 4. License and authors. The 'Latest release: v0.08.00' is prominently displayed in blue text, followed by the date '19 Dec 2018' and a list of links: 'Download', 'Release Notes', and 'Documentation'. The word 'Introduction' is also visible. At the bottom of the screenshot, a small text snippet reads: 'http://acts.web.cern.ch/ACTS/#acts-core' followed by 'it contains an experiment-independent set of track reconstruction tools. The main philosophy is to' and 'h-level track reconstruction module that can be used for any tracking detector. The description of'.

<http://cern.ch/acts>

