

ITk Pixel DAQ with YARR-FELIX

Quad module & feedback mechanism

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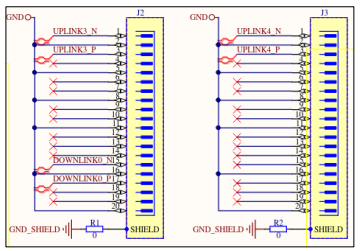
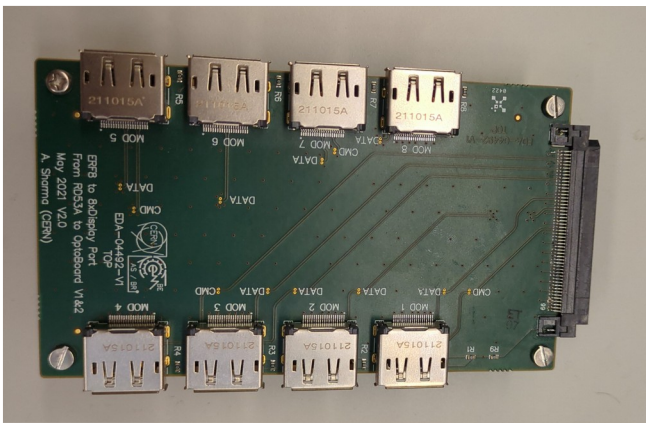
LBL Weekly Instrumentation Meeting
Sep 8th, 2023



Setting up ITkPix Quad v1.1

Old adapter board

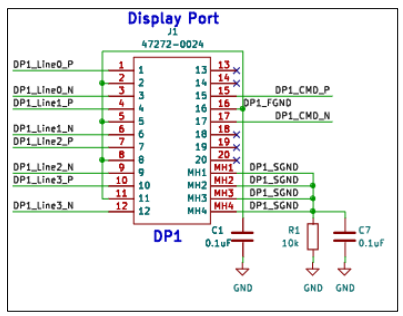
(8DP_to_ERF8_Data_Adapter, A. Sharma)



- Only one uplink per DP.
- Only 4 out of 8 DPs have downlink for sending CMD.
- Works out well for SCC (up to 4).

New adapter board

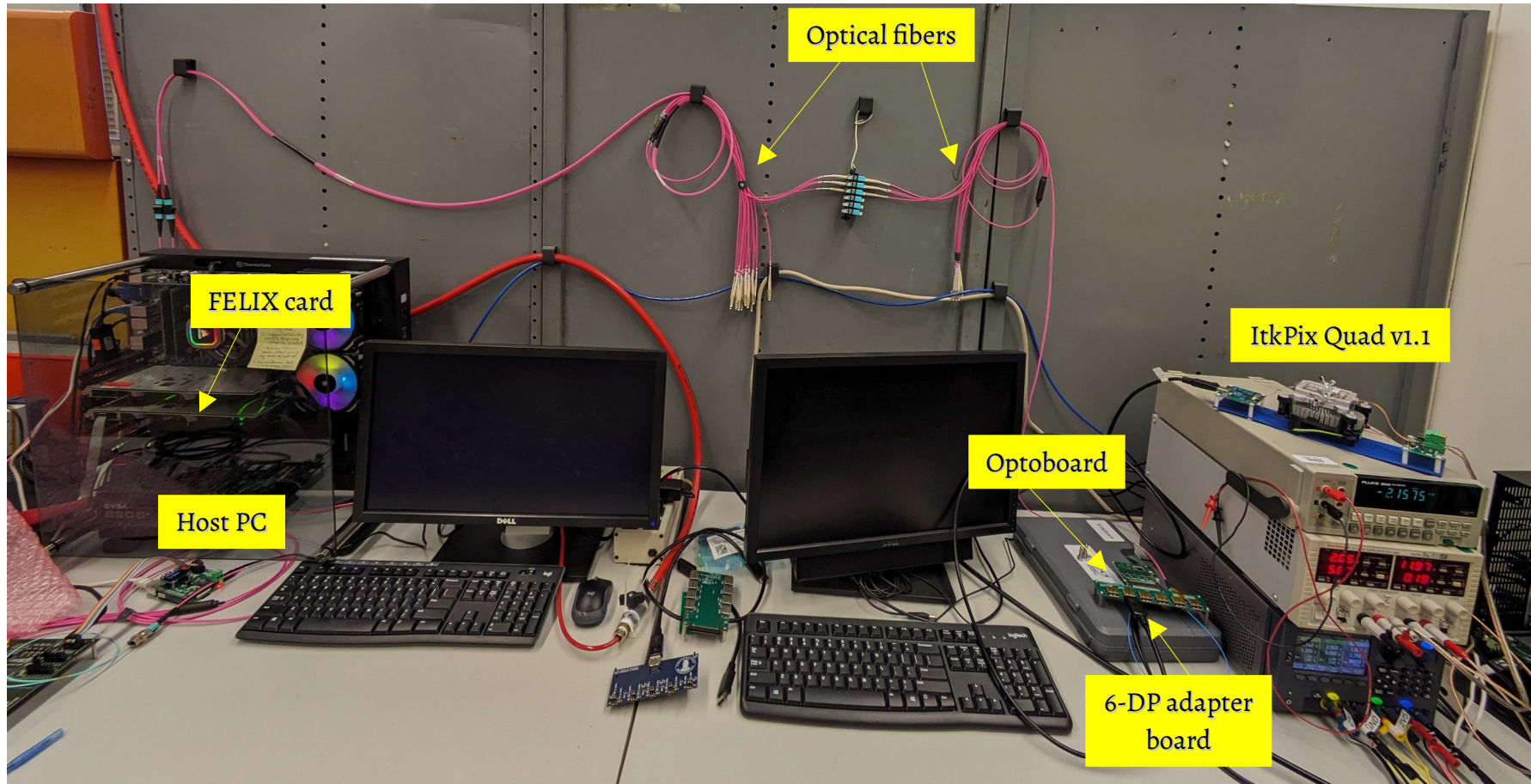
(6DP_to_ERF8_Data_Adapter, Z. Chubinidze)



- Every DP has 4 uplinks, to read out the full quad module.
- Every DP has a downlink for CMD.
- Works for SCC and quad module (max. 6).

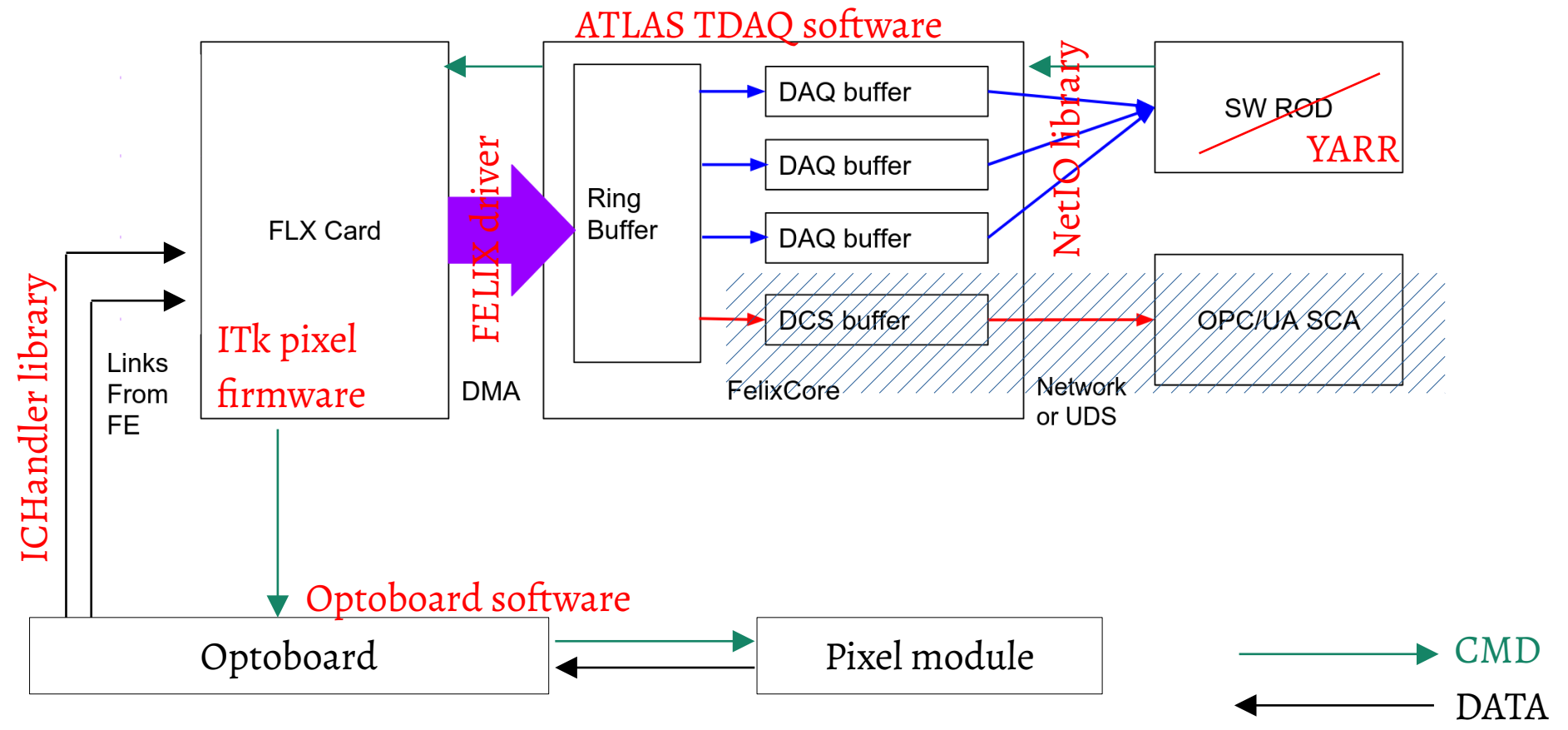
New setup with Quad module

50B-6038

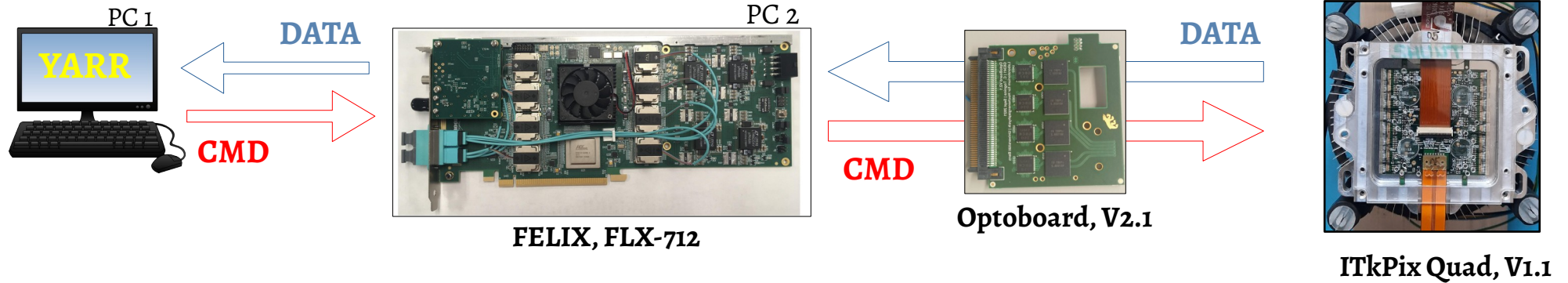


Driver, firmware & software

<https://atlaswiki.lbl.gov/pixels/felixdaq>



Running YARR scans



CMD: Sent from the YARR for:

- Configuring the chip (reset, syncs, configuring the global & pixel registers)
- Setting up pre-scan (writing some more named registers, CMD enable, injection charge etc.)
- Running the scan (masking, injection & trigger)

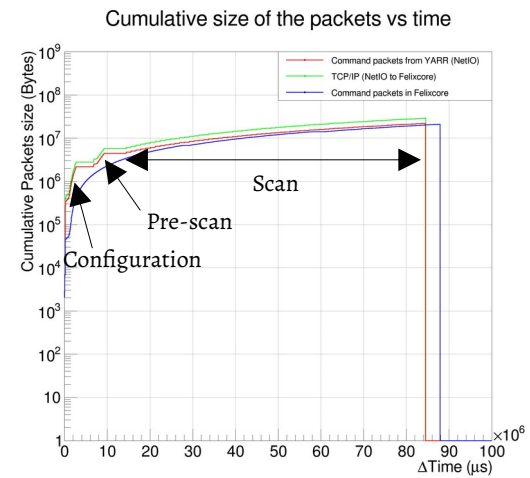
DATA: Hit data arriving from the chip to HW controller and back to YARR:

- Corresponding to every trigger command.
- Can be deterministic i.e. arrives at regular intervals or random i.e. more spread out in time.

Issues with sending commands

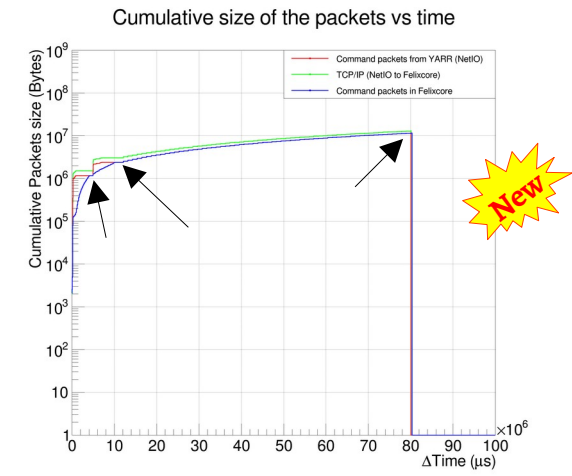
Problem:

- Commands sent out from YARR (NetIO) gets split into many small-sized packets in the network. Hence, FELIX software receives much fewer commands in the equivalent time.
- These smaller-sized commands are then bunched up in the buffers instead of being sent out to the chip immediately. This leads to a delay or mismatch in synchronicity between the YARR scans (setup, injections & triggering) and the chip operations.



Fix:

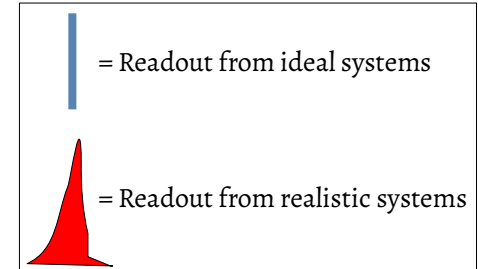
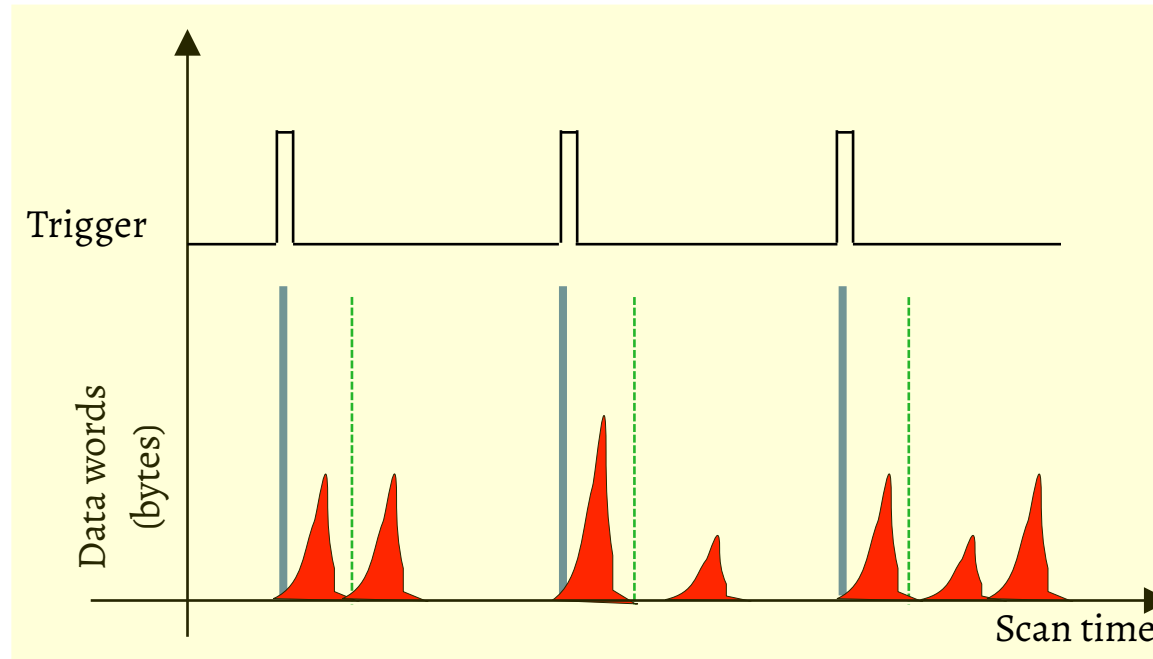
- Aggregating commands in YARR (NetIO) to send out longer packets above a minimum threshold size. These are then forwarded more regularly from FELIX software to the chip.
- Changes already integrated in YARR-devel branch.



Issues with receiving data

Ideal systems: Data arrives at a regular interval and all at once. For ex, PC with spec card controller.

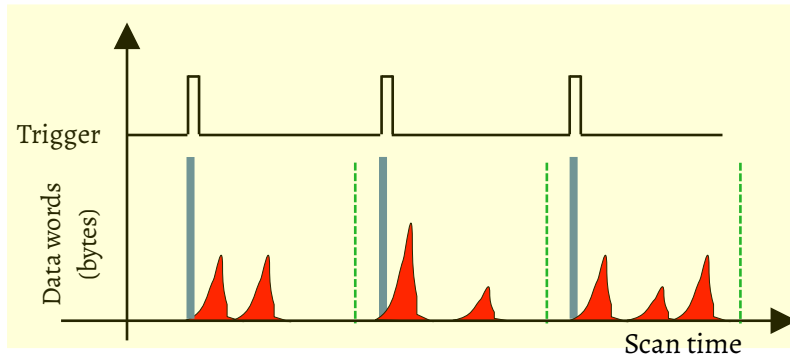
Can choose a safe boundary (**green**) at which we expect all data to have been received from the HW controller (it's latency) for that parameter settings (mask stage, core column loop) before moving on to the next iteration.



Realistic systems: For ex, with FELIX as HW controller and a server-based data readout, data arrival can be very unpredictable. This is due to network latencies and data buffering. Other factors affecting the readout are if server (FELIX software) and client (YARR) are running on different PCs, or non-uniform setups such as longer cables introducing extra delays etc.

Hence, unclear where to set the boundary unanimously. Not good to set to a very large (unknown) value because it will make the scans slow.

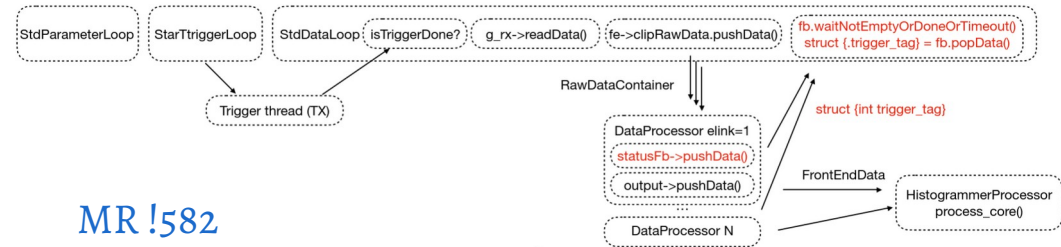
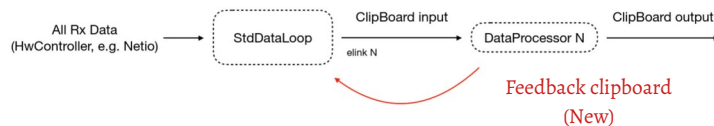
Hence, feedback...



- Setting a **very large time per iteration** of scan up to when we want to keep reading data from the HW controller.
- However, **stop early** if all the data expected from the iteration is already received (the “**feedback**”).
- Hence making the scan results stable, and also a more universal software that can be used across different setups.

The “feedback”

- We know, from the scan configuration, how many triggers are to be sent (trigger count x multiplier). Hence, we should receive those many event headers (trigger tags).
- Counting the number of tags received, and ending the iteration whenever all of them are received. Also, pushing the collected data from every feedback cycle for histogramming and analysis, making the processing faster.



MR !582

- Finally, proceeding onto the next iterations of the scan.

| Chip ser. no. | CML Bias0 | CML Bias1 |
|---------------|-----------|-----------|
| OX14118 | 900 | 0 |
| OX14119 | 800 | 0 |
| OX14128 | 800 | 0 |
| OX14129 | 900 | 0 |

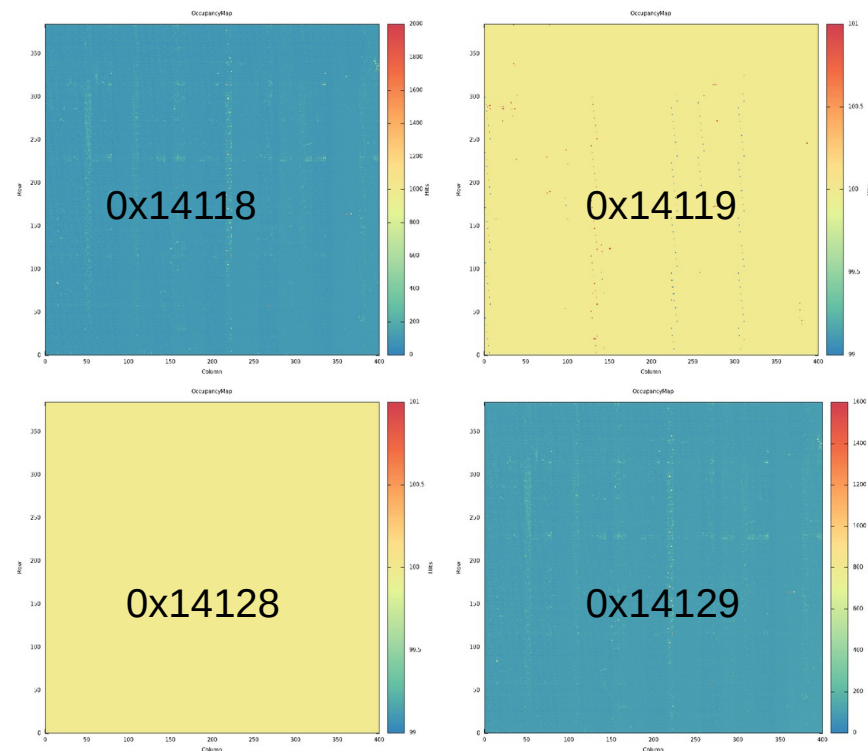
Most optimum values

CML bias scan

- **OX14118:** CML Bias1 > 0 gives much fewer events e.g. 500-1000 (expected 1600) per iteration. Slightly higher no. of events received with CML Bias0 = 900 than 800.
- **OX14119:** No. of failing pixels = 239 (no unfinished stream errors).
- **OX14128:** No. of failing pixels = 0 (no unfinished stream errors).
- **OX14129:** Doesn't see any data words when CML Bias1 > 0. Slightly higher no. of events received with CML Bias0 = 900 than 800.

After some debugging, we found that the pull-down resistor on the data adapter board was the reason behind unsuccessful digital scan.

Digital scan results



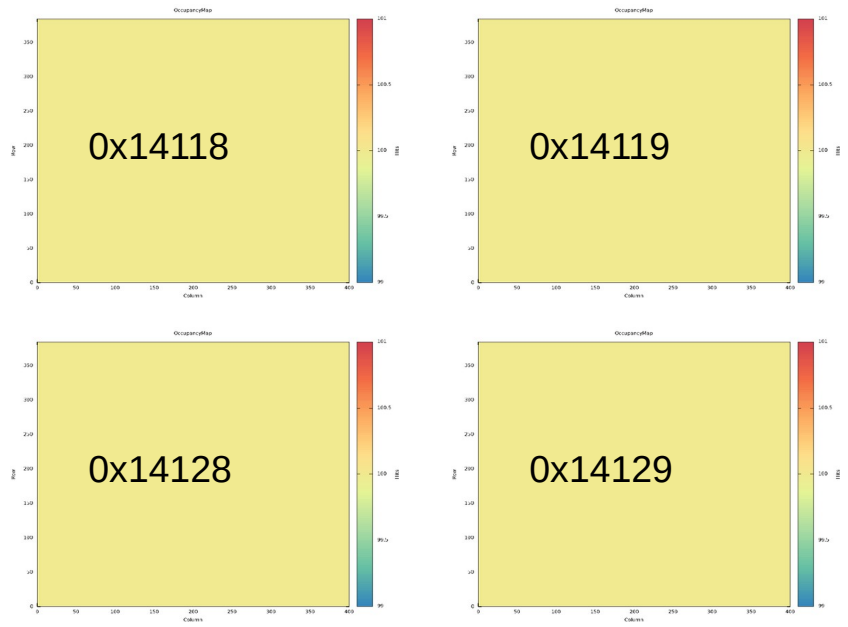
Trigger frequency = 5 KHz

Injections = 100

Trigger multiplier = 16

Scan results (1/2)

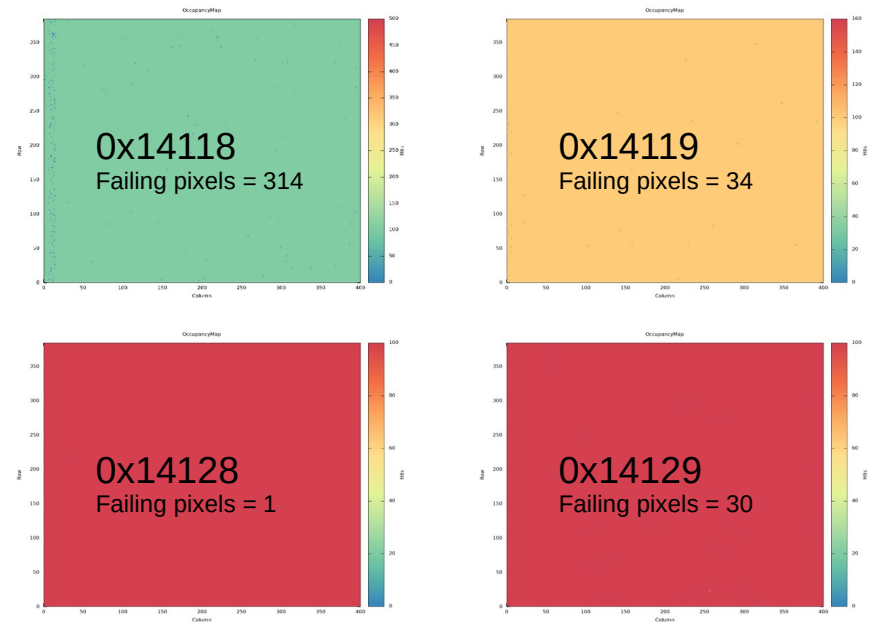
Digital Scan



User time: 46.5 s
Analysis: 740 μs
Configuration: 620 μs
Processing: 0 μs
Scan: 39198 μs

Trigger frequency = 5 KHz
 Injections = 100

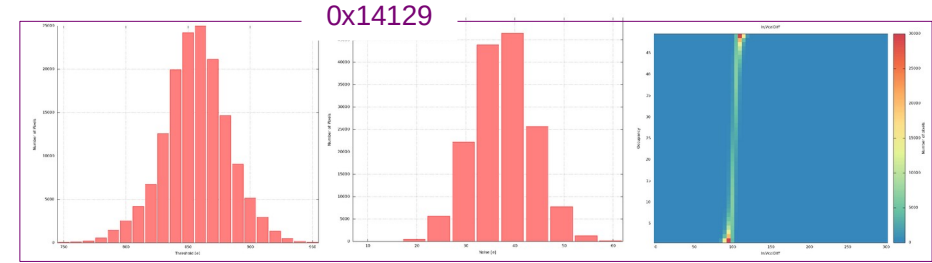
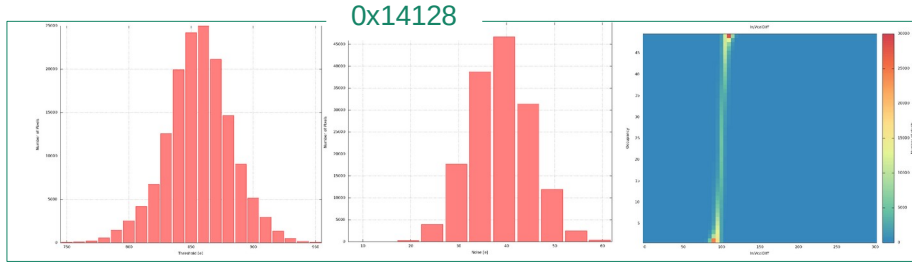
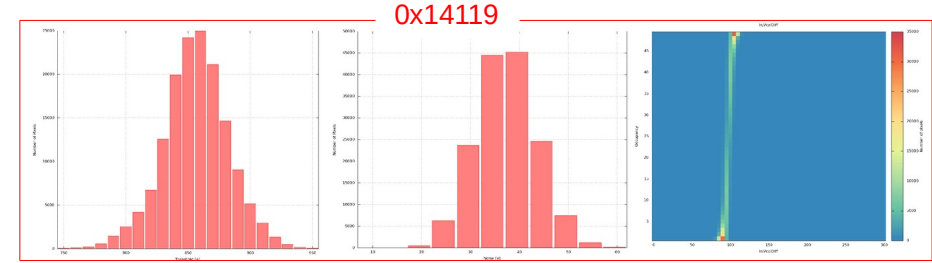
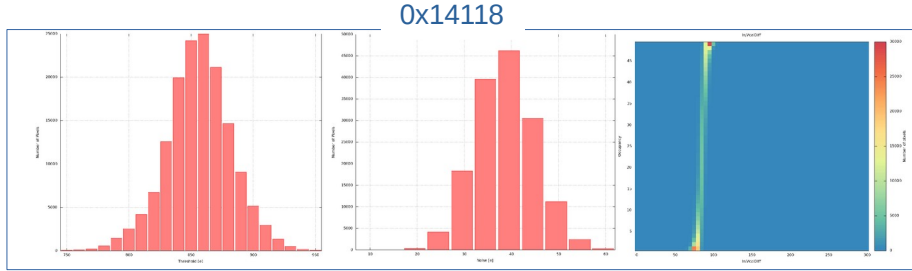
Analog Scan



User time: 46.3 s
Analysis: 729 μs
Configuration: 703 μs
Processing: 0 μs
Scan: 43065 μs

Scan results (2/2)

Threshold Scan



```
[ info ][ StdAnalysis ][20872]: [1][0x14128][0] Threshold Mean = 978.6095947752412 +- 30.810425680406215
[ info ][ StdAnalysis ][20869]: [0][0x14118][0] Threshold Mean = 855.4551088958542 +- 29.785273598132484
[ info ][ StdAnalysis ][20878]: [3][0x14119][0] Threshold Mean = 945.6960709171823 +- 25.520117177133592
[ info ][ StdAnalysis ][20872]: [1][0x14128][0] Noise Mean = 38.77379065992978 +- 6.260338252076129
[ info ][ StdAnalysis ][20872]: [1][0x14128][0] Number of failed fits = 4
[ info ][ StdAnalysis ][20875]: [2][0x14129][0] Threshold Mean = 963.3372355625197 +- 25.759518161537752
[ info ][ StdAnalysis ][20869]: [0][0x14118][0] Noise Mean = 38.55561013224672 +- 6.336692879729476
[ info ][ StdAnalysis ][20869]: [0][0x14118][0] Number of failed fits = 123
[ info ][ StdAnalysis ][20878]: [3][0x14119][0] Noise Mean = 37.25460401490792 +- 6.102259783450186
[ info ][ StdAnalysis ][20878]: [3][0x14119][0] Number of failed fits = 24
[ info ][ StdAnalysis ][20875]: [2][0x14129][0] Noise Mean = 37.52114141691696 +- 6.063402691153536
[ info ][ StdAnalysis ][20875]: [2][0x14129][0] Number of failed fits = 6
```

User time: 1503.3 s
Analysis: 787 μ s
Configuration: 696 μ s
Processing: 0 μ s
Scan: 1733258 μ s

Timing vs N Front-Ends (FEs)

| Scans | 1 FE | 2 FE | 3 FE | 4 FE (full quad) |
|------------------|--|--|---|---|
| Digital | User time: 11.81s "analysis": 563, "config": 191, "scan": 27788 | User time: 23.71s "analysis": 770, "config": 401, "scan": 32795 | User time: 37.25s "analysis": 800, "config": 569, "scan": 37742 | User time: 47.92s "analysis": 740, "config": 775, "scan": 42364 |
| Analog | User time: 12.05s "analysis": 556, "config": 206, "scan": 28238 | User time: 25.02s "analysis": 465, "config": 377, "scan": 34853 | User time: 37.10s "analysis": 496, "config": 548, "scan": 39639 | User time: 48.34s "analysis": 800, "config": 748, "scan": 44799 |
| Threshold | User time: 373.32s "analysis": 704, "config": 186, "scan": 1251930 | User time: 768.90s "analysis": 734, "config": 399, "scan": 1430736 | User time: 1195.37s "analysis": 621, "config": 538, "scan": 1594621 | User time: 1544.56s "analysis": 886, "config": 704, "scan": 1743871 |

Configuration time scales with number of FEs, looks suspicious and obvious place for improvement.

- Data transmission with ItkPix Quad V1.1 via YARR-FELIX interface in place now.
- Can run all the calibration scans (including the tunings), as well as noise scans with time-based firmware-trigger generation.
- New improved YARR data loop with a feedback mechanism, which is immune to latencies in the network and data buffering as well as variability of different setups. [MR !582](#)
- Software-based trigger generation is also fixed - sync commands to be inserted before sending the calibration injection and trigger sequence. All scans can be run successfully at 5KHz frequency. [MR !659](#)

Future improvements:

- Firmware limitations (running scans above 5 KHz frequency, and for more than 100 injections) and FELIX SW wishlist items (such as setting FELIX registers for running various scan configurations through DAQ SW) to be communicated to the experts (ANL), hopefully at the upcoming ITk week.
- Better parallelization for configuring the module and other timing optimizations to be done in YARR.

- To switch to latest FELIX SW (FELIX-star) and FELIX-Client (for YARR).

- To setup the SP quad module chain readout with FELIX.