

Measuring the performance of the Mu2e Tracker Prototype using a pixel cosmic ray telescope

Richie Bonventre, Dave Brown, Andrew Edmonds, Yury
Kolomensky

January 20, 2016

Lepton Flavor Violation

The Nobel Prize in Physics 2015



Photo © Takaaki Kajita

Takaaki Kajita

Prize share: 1/2



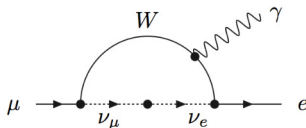
Photo: K. McFarlane,

Queen's University

/SNOLAB

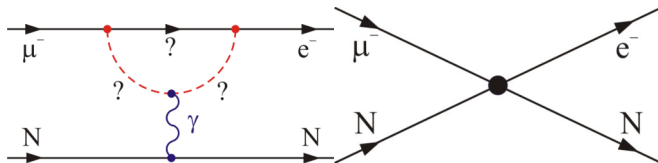
Arthur B. McDonald

Prize share: 1/2



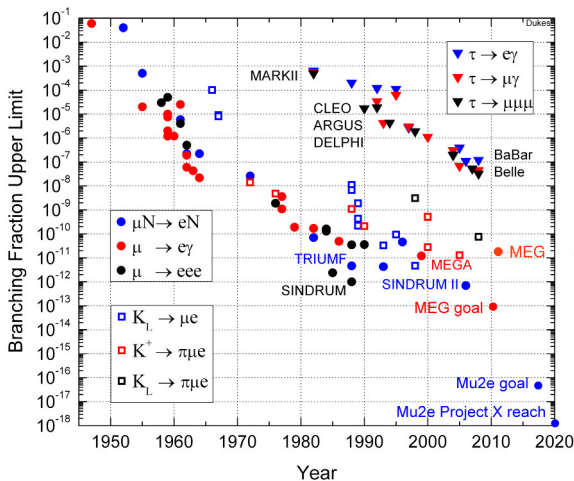
- ▶ Mu2e is looking for charged lepton flavor violation (CLFV)
- ▶ Discovery of neutrino mass and mixing, lepton flavor violation
- ▶ Neutrino mixing implies CLFV, but rate is extremely small (10^{-54})
- ▶ Observation would be an unambiguous sign of new physics

Beyond the Standard Model possibilities



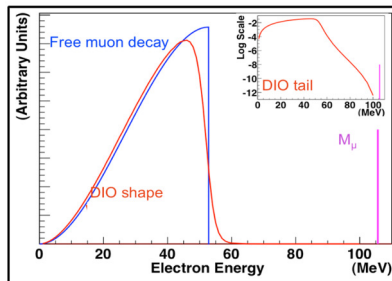
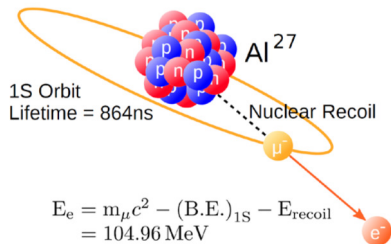
- ▶ Effective Lagrangian for CLFV has two types of terms, loop and contact
- ▶ Signal is either $\mu \rightarrow e\gamma$ or $\mu N \rightarrow eN$
- ▶ Many models of new physics enhance CLFV and predict measurable rates:
 - ▶ Supersymmetry
 - ▶ Leptoquarks
 - ▶ Heavy neutrinos
 - ▶ Second Higgs doublet
 - ▶ Compositeness
 - ▶ Heavy Boson / anomalous couplings
- ▶ allows sensitivity to extremely high mass scales not accessible with accelerators ($O(10,000 \text{ TeV})$)

Current Limits



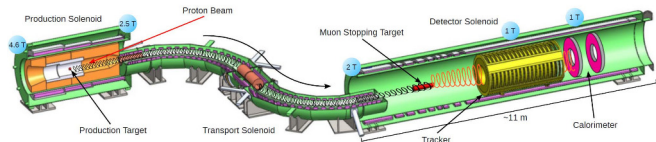
- ▶ $\mu N \rightarrow eN$: SINDRUM-II limit at 6×10^{-13}
- ▶ $\mu \rightarrow e\gamma$: MEG limit at 5.7×10^{-13}
- ▶ Mu2e sensitivity target is 3×10^{-17}

Mu2e Experiment



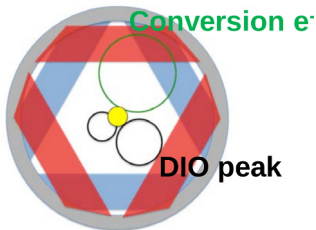
- ▶ Muons capture on Al
- ▶ Conversion produced mono energetic electron at 105 MeV
- ▶ Main background is muon decay in orbit (DIO), require very good momentum resolution
- ▶ Measure $R_{\mu e} = \frac{\Gamma(\mu^- + (A, Z) \rightarrow e^- + (A, Z))}{\Gamma(\mu^- + (A, Z) \rightarrow \nu_\mu + (A, Z-1))}$

Mu2e Experiment



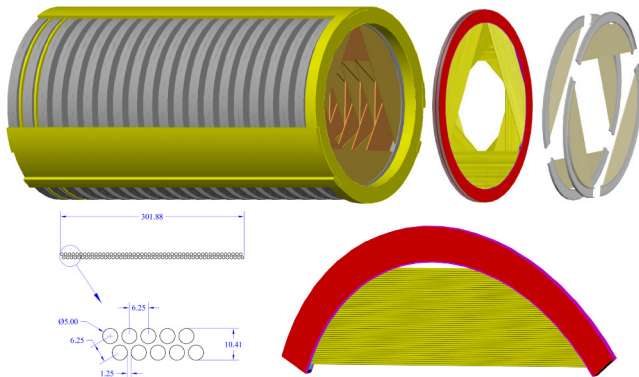
- ▶ High intensity proton beam (require $> 10^{18}$ stopped muons)
- ▶ Three areas with superconducting solenoids
- ▶ Straw tracker, calorimeter, cosmic ray veto

Mu2e Straw Tracker



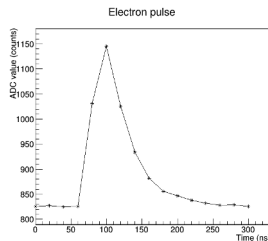
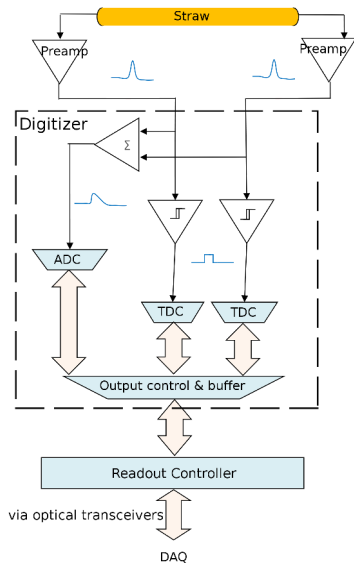
- ▶ 20,000 straws in total
- ▶ 5mm diameter, $15\mu\text{m}$ thick mylar wall
- ▶ $25\mu\text{m}$ gold plated tungsten sense wire
- ▶ Cylindrical tracker, insensitive to <53 MeV electrons

Mu2e tracker design



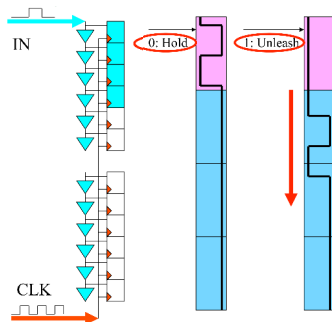
- ▶ 96 straws form 120° arc called a panel
- ▶ 12 rotations form a station
- ▶ 18-20 stations in total (20,000 straws)
- ▶ Electronics enclosed in panel around straws

Straw electronics



- ▶ Straws are instrumented on both ends
- ▶ After preamp, signal routed to ADC and TDC on digitizer board
- ▶ 50 MHz 12 bit ADC to measure pulse height

Firmware "Wave Union" TDC

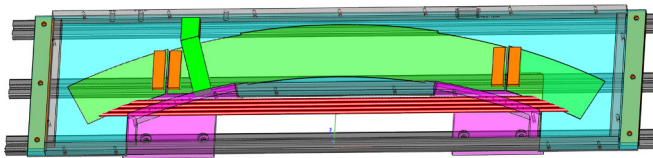
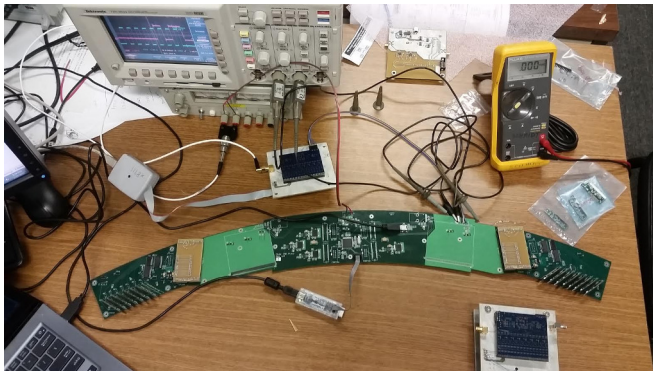


- ▶ Delay chain
- ▶ Creates histogram to calibrate bin widths
- ▶ Can use multiple edges to deal with large bins
- ▶ ~ 30 ps resolution

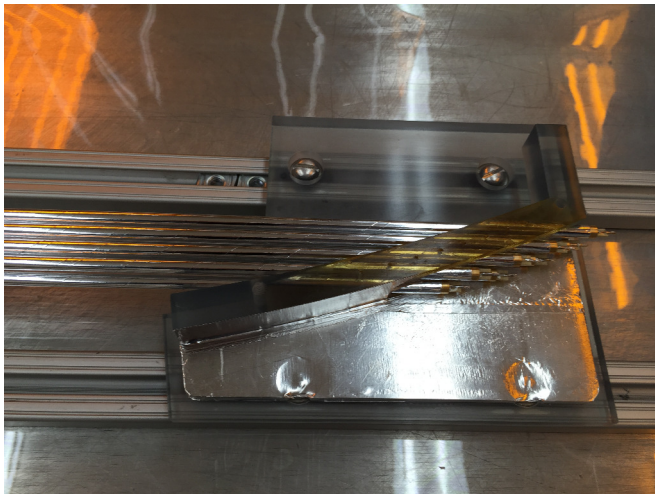
Proposal to build a tracker prototype at LBL

- ▶ Many new elements had yet to be tested
 - ▶ Curved manifold
 - ▶ New electronics
- ▶ No other multi-straw setup, full system setup
- ▶ Want to measure straw timing resolution
- ▶ Many measurements used for CD3 review

Designing the LBL tracker prototype

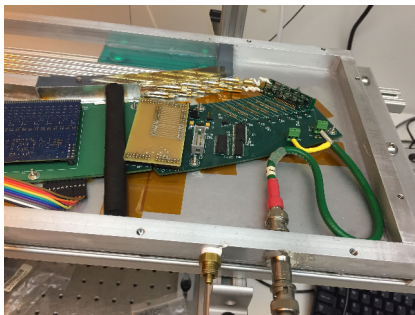
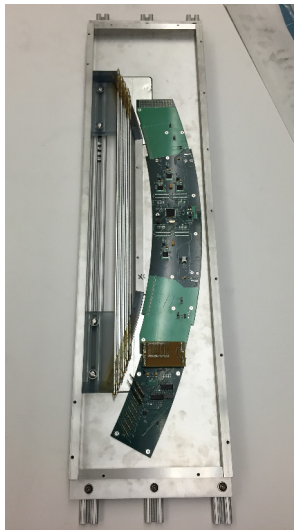


Designing the LBL tracker prototype



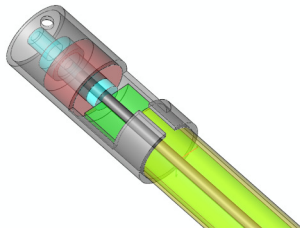
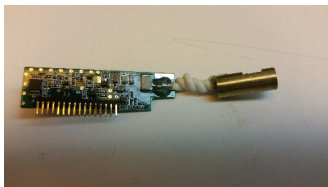
- Straws held in 3D printed manifold

Construction of the LBL tracker prototype



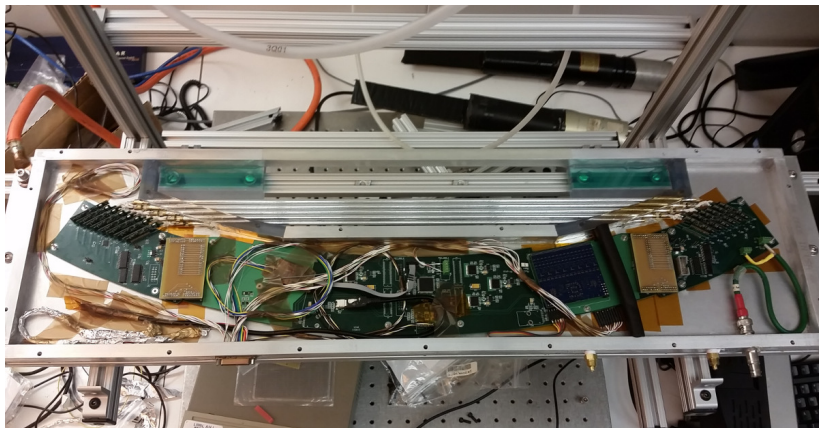
- ▶ Lot of help from Cory Lee
- ▶ Fixing gas seal around manifold, change in straw gluing procedure
- ▶ Designed temporary "rib" to force gas through the straws

Straw end connector



- ▶ Needed to develop method for connecting preamps to straws
- ▶ Flexible twisted pair, brass connector

The LBL tracker prototype chamber

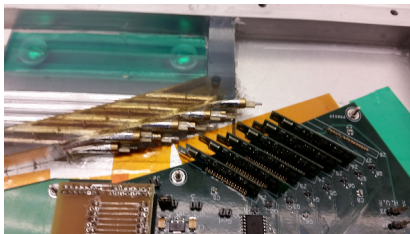


- (Downstairs in 50-2155)

Prototype readout and DAQ development

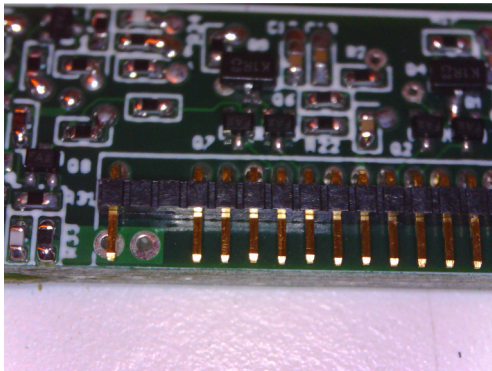
- ▶ Readout controller still being developed, prototypes use microcontroller
- ▶ Communicates to PC by serial over USB, simple python DAQ
- ▶ Can send calibration pulses to each channel with variable height and frequency
- ▶ Map out per channel noise rates, set gains and thresholds
- ▶ Readout speed 1000 hits per second (limited by serial communication on uC)
- ▶ Final ROC expect 30+ Gbps

Electronics testing



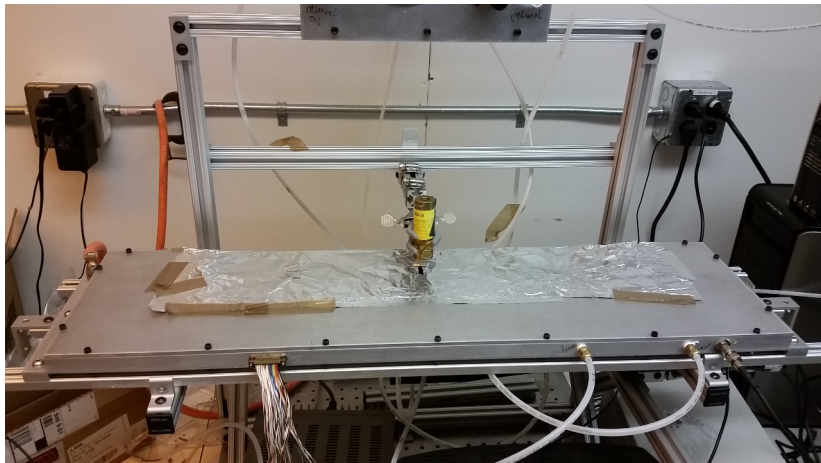
- ▶ Feedback led to design changes in next preamp iteration
- ▶ Noise issues, threshold step size, HV breakdown points

Electronics testing

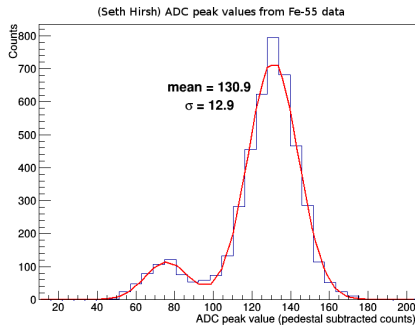
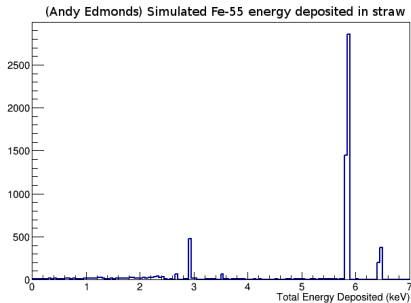


- ▶ Feedback led to design changes in next preamp iteration
- ▶ Noise issues, threshold step size, HV breakdown points

Testing with sources

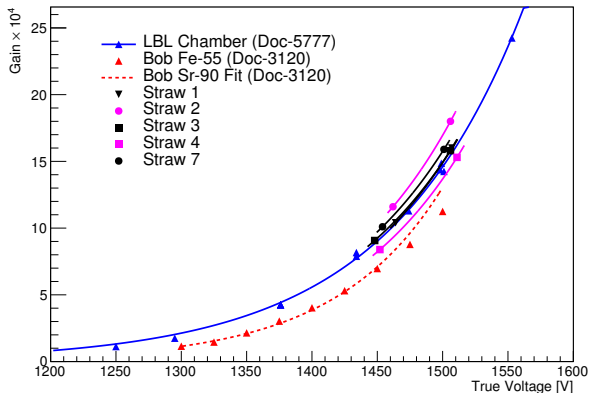


Can resolve ^{55}Fe peaks using ADC data



- ▶ From simulation, without electronics effect expect best possible resolution is 6.8%
- ▶ Peak - pedestal ADC value gives 9.9%

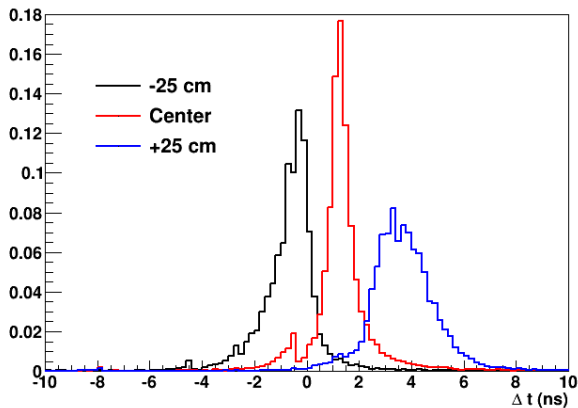
(Andy Edmonds) Measuring gas gain with ^{55}Fe data



- ▶ Record hit rate, voltage, and HV supply current

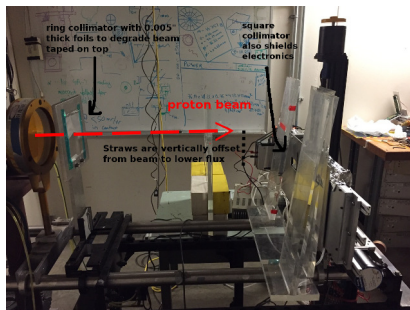
- ▶
$$\text{Gain} = \frac{\text{HV supply current}}{\text{Rate} \times \frac{E_{\text{per gamma}}}{\text{Ionization energy}} \times \text{Electron charge}}$$

Using ^{90}Sr source, able to see change in time measurement as a function of position on straw



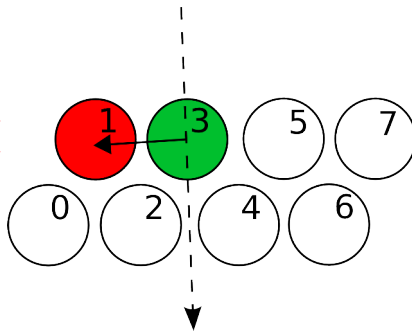
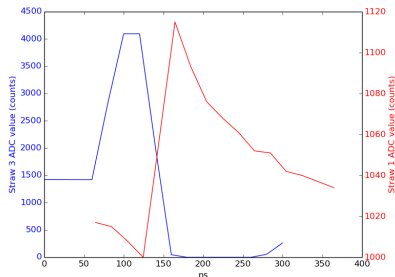
- $v_{\text{propagation}}$ consistent with expectations

Proton beam testing at 88 inch cyclotron



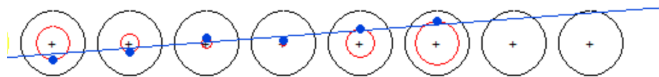
- ▶ Protons are produced after muon capture by Aluminum
- ▶ Looking for cross talk from straw to straw from large proton signals
- ▶ Ran twice, once with each model preamp

Cross talk from protons



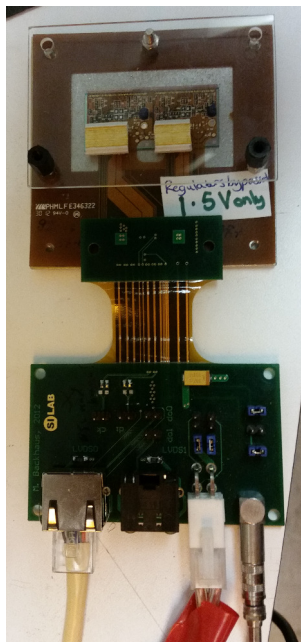
- ▶ Old preamps had clear cross talk signals
- ▶ New preamps fixes this, still some cross talk within preamp

Measuring resolution



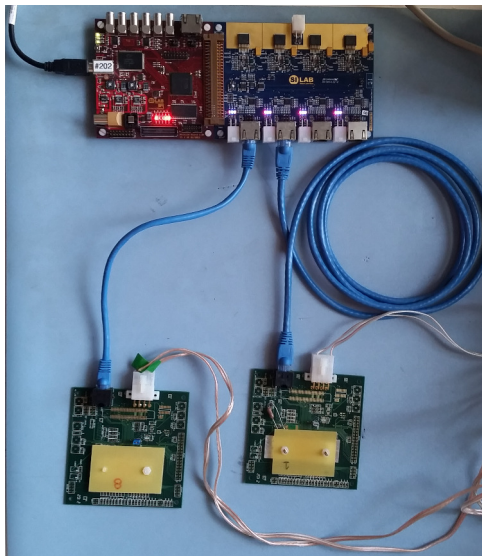
- ▶ Measurement of drift time tells us radial position of track
- ▶ Simulations show $200\ \mu\text{m}$ resolution is sufficient for reconstruction
- ▶ To determine resolution need independent measure of track position

ATLAS FEI4 pixel chips



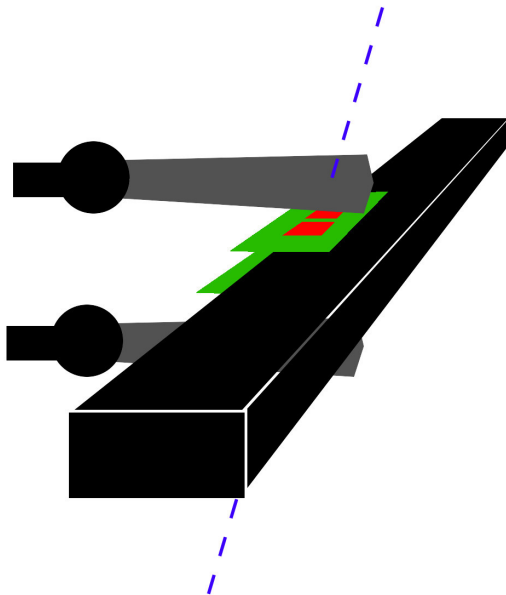
- ▶ 80x336 pixel array (26680 total)
- ▶ 250x50um, 2.0x1.9cm chips
- ▶ Data is row, column, TOT (pulse size), BCID (gives time from trigger in 25ns ticks)

Bonn USBpix readout system

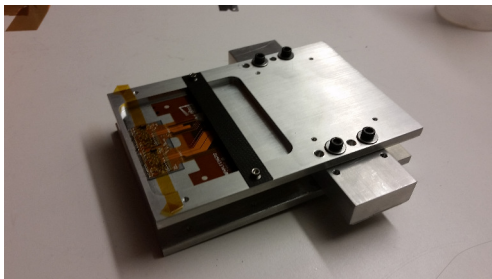


- ▶ Read out over USB
- ▶ External trigger input
- ▶ pyBAR - python based DAQ, developed multichip support
- ▶ Thanks to Maurice + pixel group, Rebecca Carney, Jens Janssen for lots of help

Development of cosmic setup

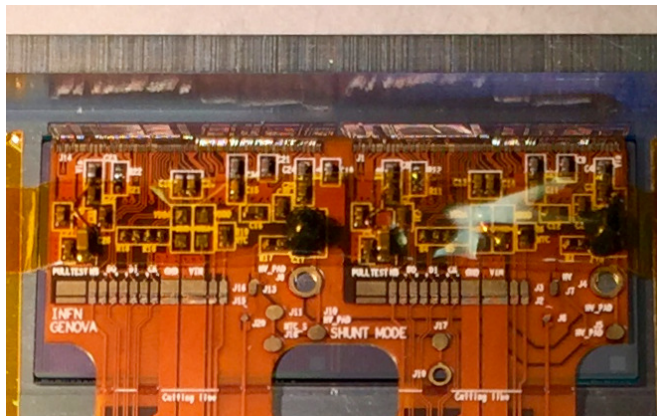


Pixel Mount



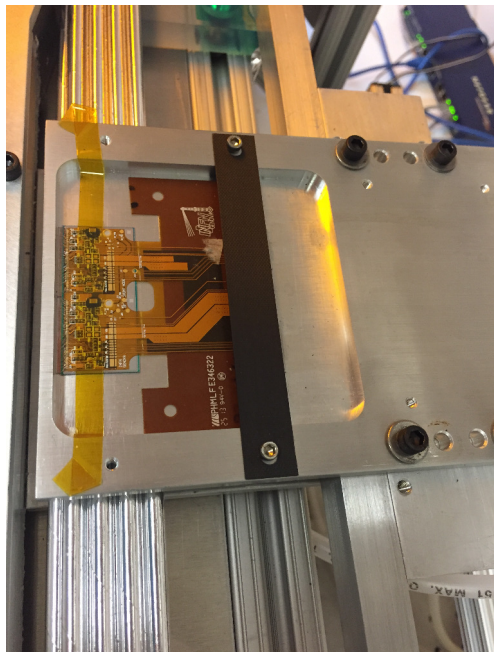
- ▶ Want to put pixels as close to straws as possible
- ▶ Need to ensure consistent pixel position
- ▶ Want to be able to move along straw, adjust relative pixel positions
- ▶ Non destructive

Mounting the pixel modules

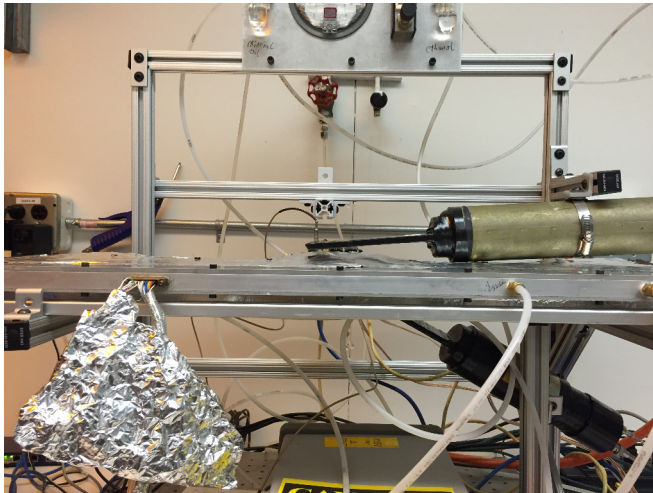


- ▶ Positioned by hand by Rhonda Witharm
- ▶ Want to ensure they are parallel

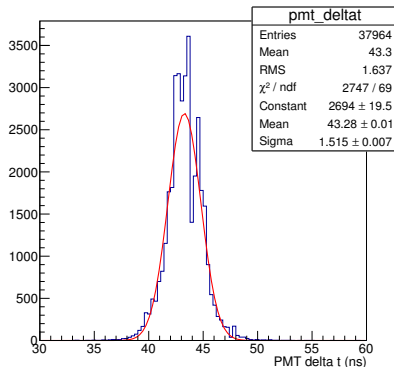
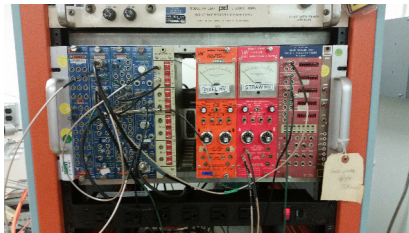
Mounting the pixel modules



Mounting the pixel modules

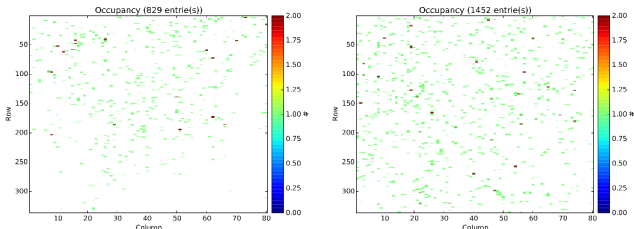


Readout and PMT coincidence / triggering logic



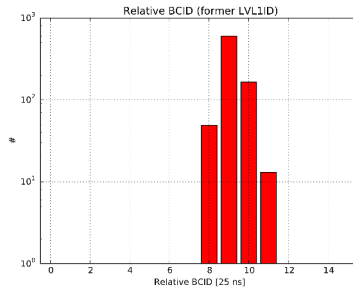
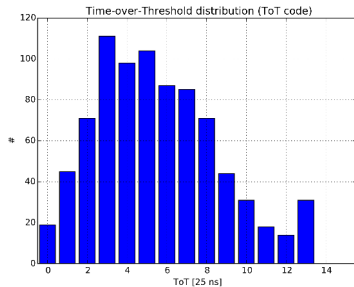
- ▶ Create PMT coincidence, need to get to both pixels and chamber, but 40 MHz vs 50 MHz clocks
- ▶ Input into digitizer TDC, get measurement in straw clock domain
- ▶ Input into USBpix as external trigger for pixels, keep track of trigger count in both systems

Pixel results



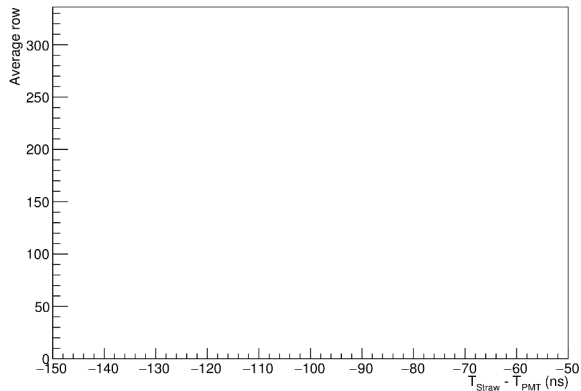
- ▶ Chips individually calibrated with pulser circuit, threshold ~ 2500 electrons
- ▶ Cosmic rays fire a single pixel
- ▶ Negligible noise rate

Pixel results

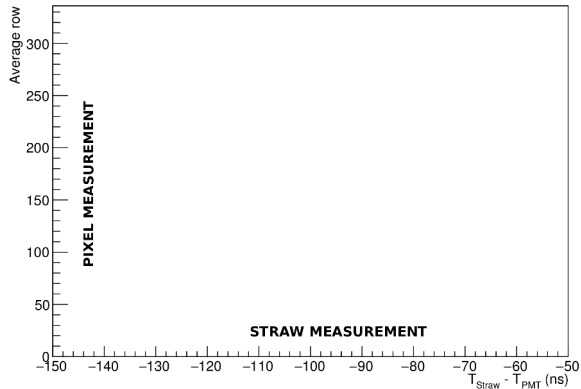


- Not sure why hits spread out over 100 ns

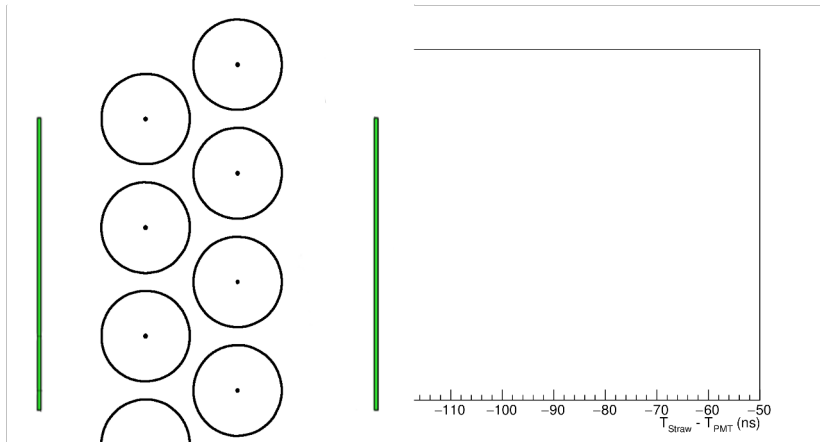
Sanity check - assume all events are straight down



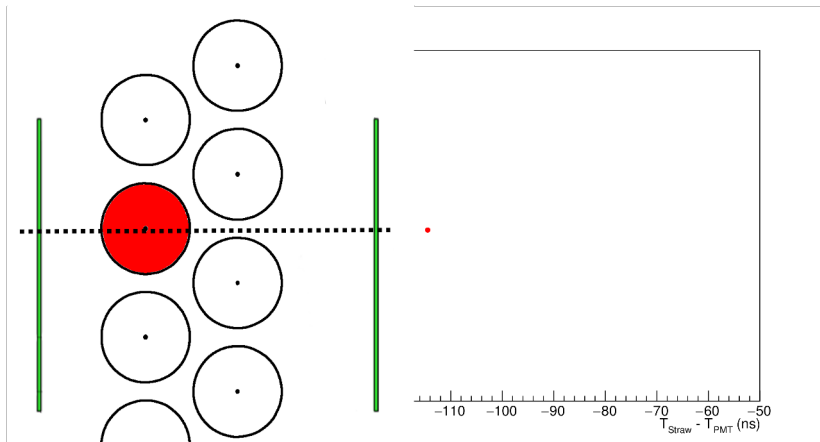
Sanity check - assume all events are straight down



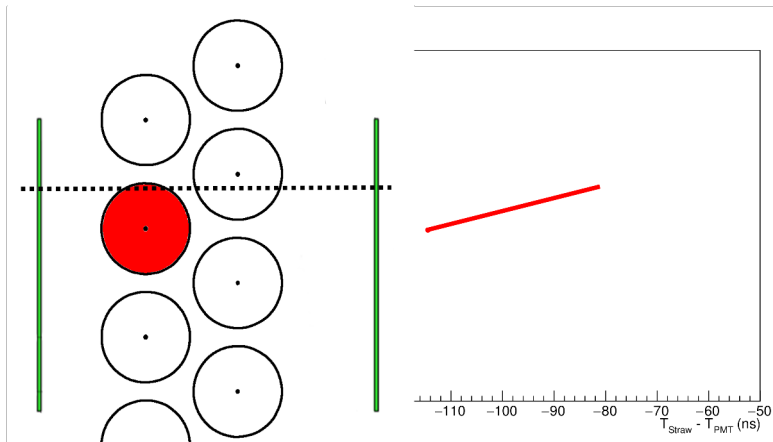
Sanity check - assume all events are straight down



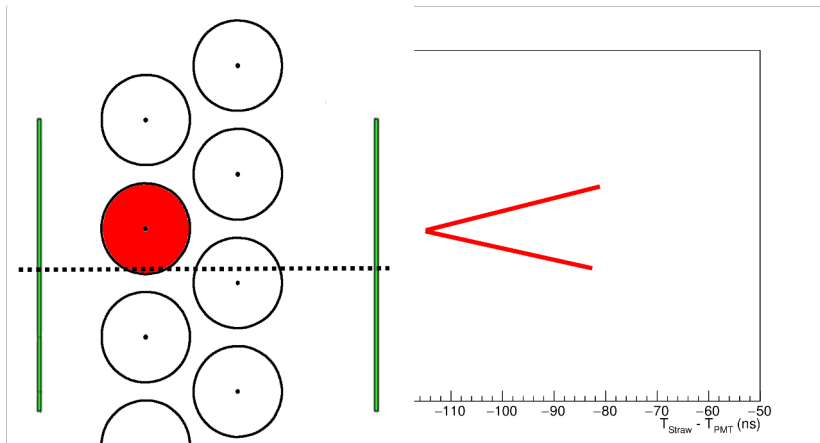
Sanity check - assume all events are straight down



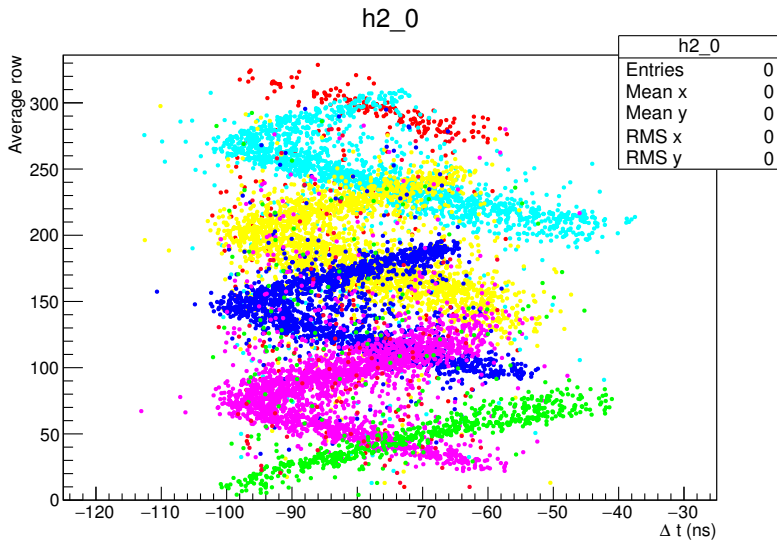
Sanity check - assume all events are straight down



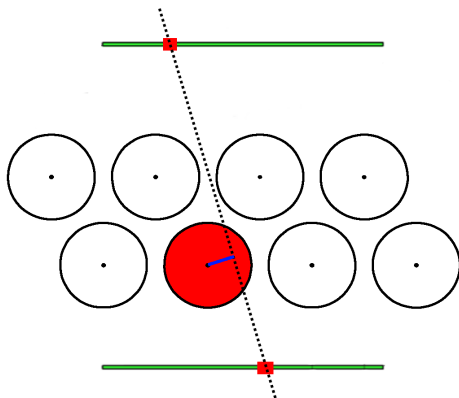
Sanity check - assume all events are straight down



Sanity check - assume all events are straight down

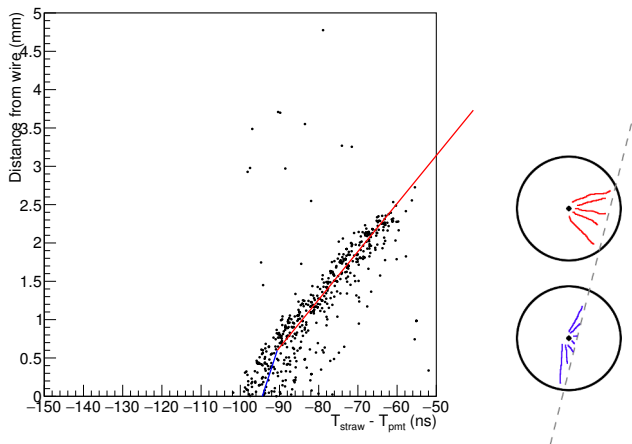


Full data analysis



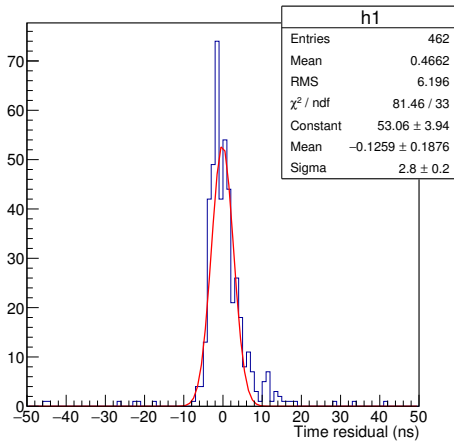
- ▶ Assuming perfectly parallel pixels and straws, no offset between pixels
- ▶ Maximum likelihood fit for 2-D wire position, drift velocity
- ▶ For each event calculate minimum distance to wire and expected drift time

Resolution and drift velocity (at 1425V)



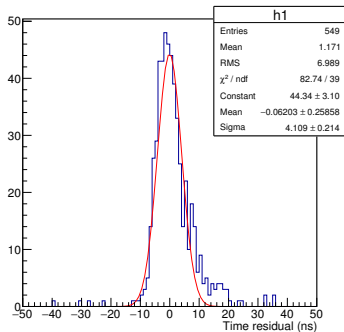
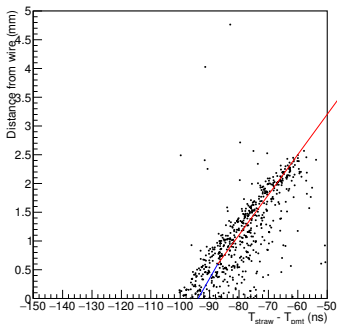
- ▶ Model drift velocity as being constant at a distance of 0.6mm to the wire and farther
- ▶ Drift velocity = $62.6 \pm 0.5 \mu\text{m/ns}$, agrees well with analysis by Jason Bono

Resolution and drift velocity (1425V)



- ▶ Subtracting PMT time spread (assuming $1.5/\sqrt{2}$ ns), get position resolution of $162 \pm 13 \mu\text{m}$
- ▶ 6-7% of hits coming late, not yet understood

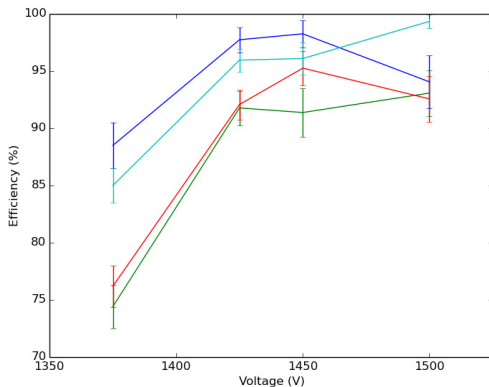
Looking at 1375V



- ▶ Original target voltage was 1375V
- ▶ Much worse efficiency and resolution than expected

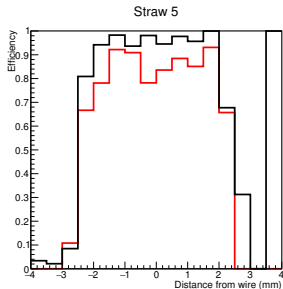
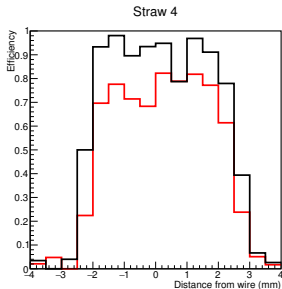
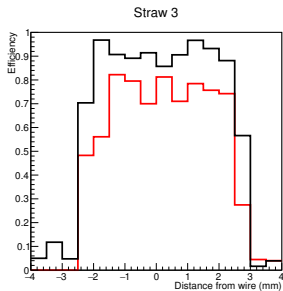
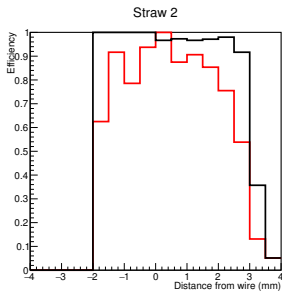
Efficiency (%)

- ▶ Look for events where pixels say track goes through straw, see if there is a hit
- ▶ Exclude outer 0.5 mm of radius

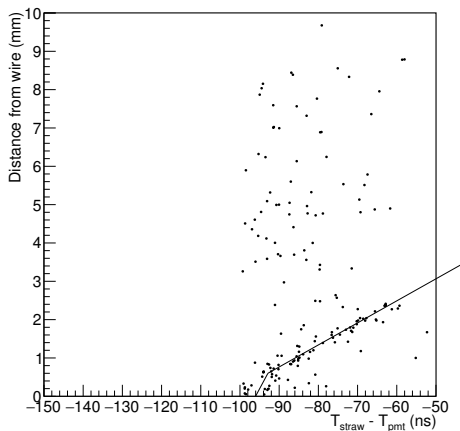


Efficiency (%)

black: 1425V, red: 1375V

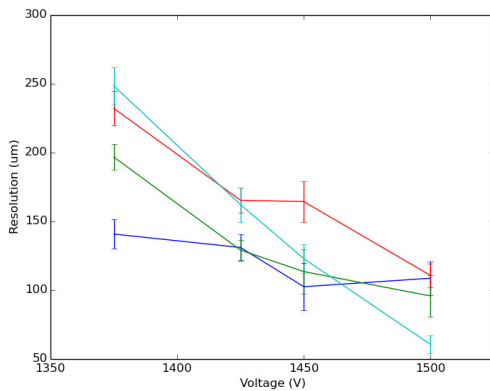


Missing efficiency



- ▶ Events with hits in non-adjacent straws (3-5% of hits) show signs of showers or scattering
- ▶ Possible similar effect fooling the efficiency measurement

Resolution (μm)

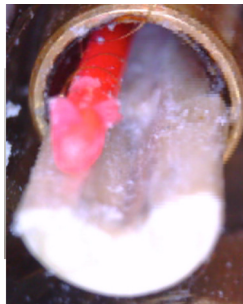
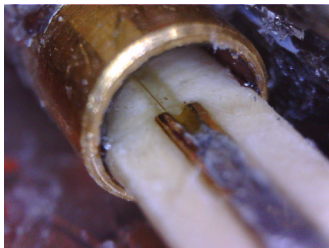


Conclusions

- ▶ LBL prototype allowed us to test many different components of the tracker system
- ▶ FEI4 pixel modules allow for precision measurement of straw response as a function of track position
- ▶ Were able to demonstrate required time resolution
- ▶ Fed back many design changes to full system
- ▶ Future plans:
 - ▶ High rate source for aging and gain saturation
 - ▶ Measuring electronics gains, thresholds, calibration pulse
 - ▶ Stability tests
 - ▶ Publication of results

Backup

Positioning of wires



- ▶ After first few weeks of running noticed wires out of expected positions
- ▶ Several straws had also been broken
- ▶ Restrung straws in place, but some offset remains