
Reducing fake tracks for the Muon Collider Detector

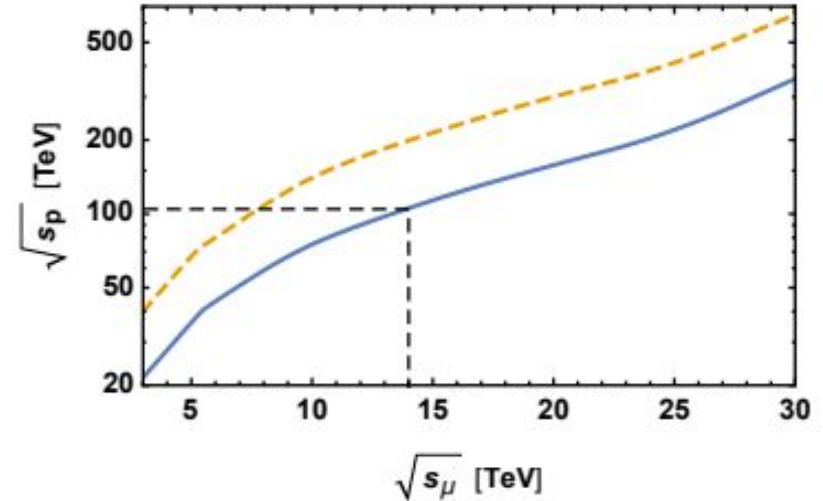
Natalie Bruhwiler
UC Berkeley

Mentors: Karol Krizka, Simone Pagan Griso, Sergo Jindariani
August 12, 2022



Motivation

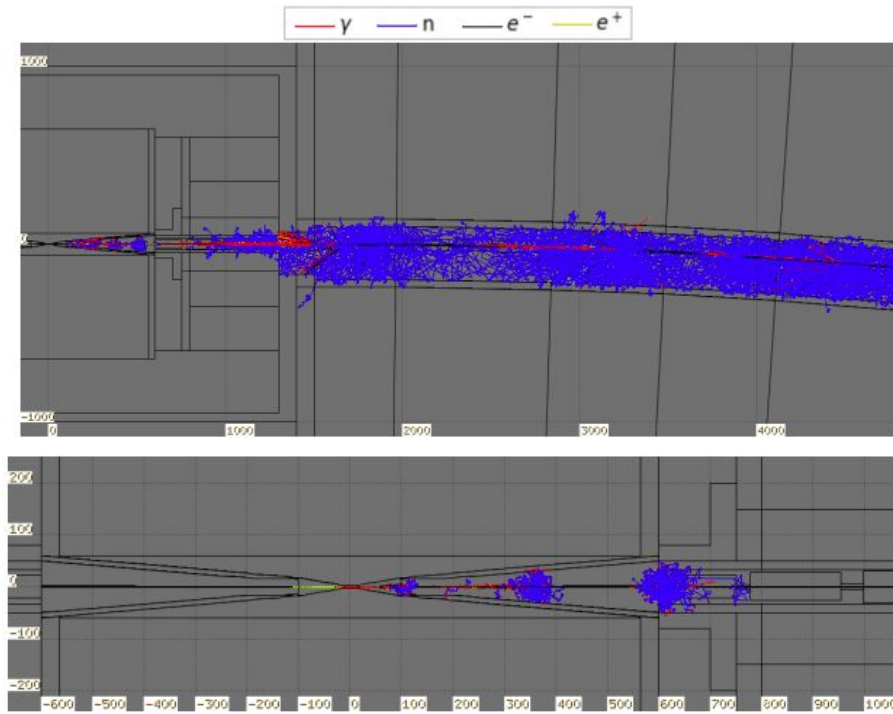
- High energy muon collisions have a lot of scientific potential
- Proton collisions occur between proton constituents, and the energy is divided between them
- Muons are leptons, so the energy isn't divided



Delahaye et al., *Muon Colliders* for the European Particle Physics Strategy Update, 18 January 2019

The problem

- Muons have a finite lifetime and produce a multitude (order 10^8 per bunch crossing) of particles that strike the detector. These are known as beam induced background (**BIB**)



ATLAS ITk Layer	ITk Hit Density [mm^2]	MCD Equiv. Hit Density [mm^2]
Pixel Layer 0	0.643	3.68
Pixel Layer 1	0.022	0.51
Strips Layer 1	0.003	0.03

Approach

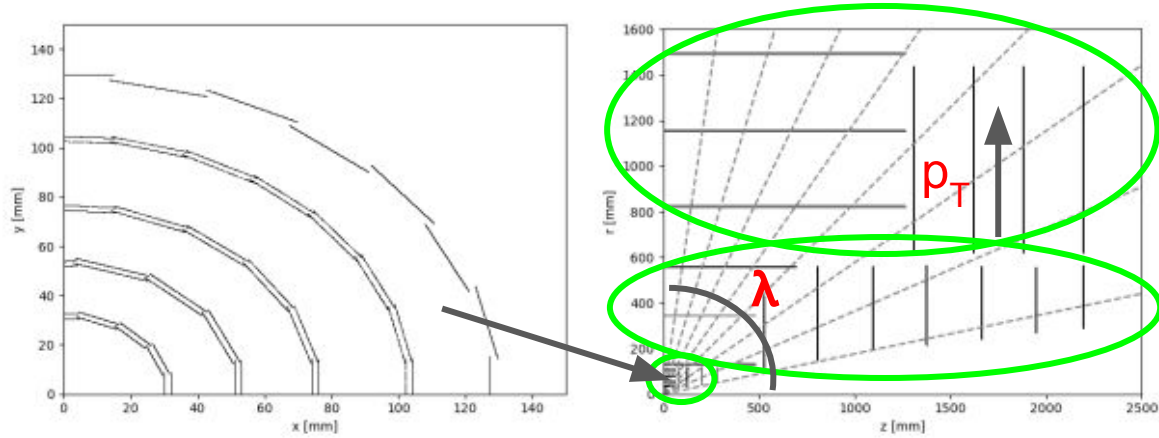
- **ACTS** (A Common Tracking Software) is our starting point
 - Modern library for charged particle reconstruction
 - ACTS implements a **Combinatorial Kalman Filter** (CKF) algorithm
 - 100,000+ reconstructed tracks every event, when there should only be one
- Goal is to **maximize reconstruction efficiency** and **minimize “fake” tracks** from BIB

Fit Library	Kalman Filter Execution Time
ACTS	0.5 ms / track
iLCsoft	100 ms / track

Krizka, *Detector and Reconstruction Performance* for Snowmass 2022, 11 January 2022

Detector layout

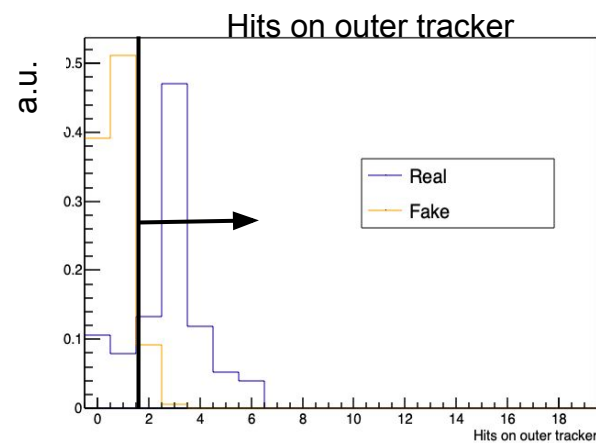
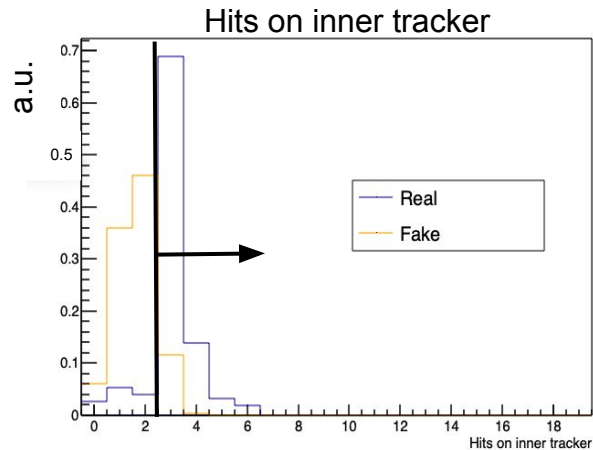
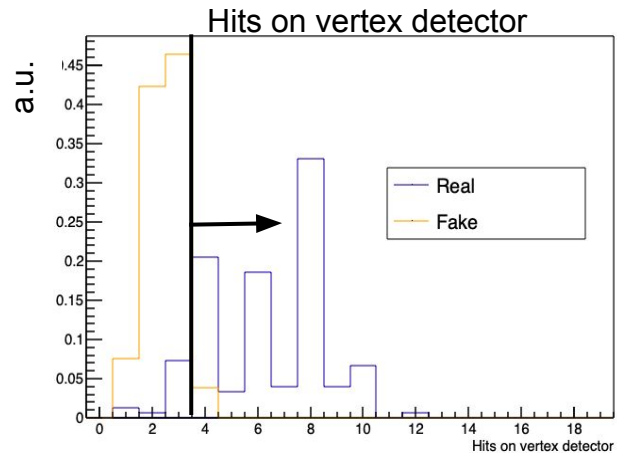
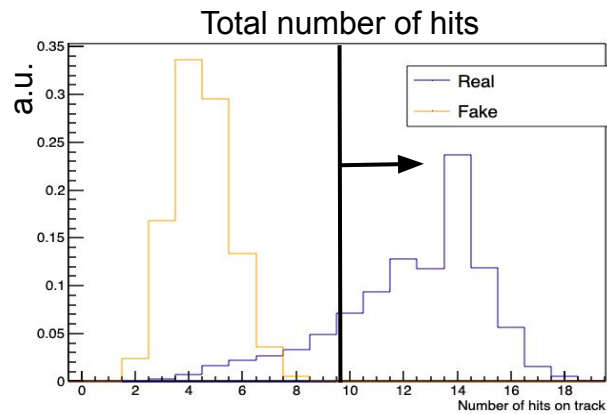
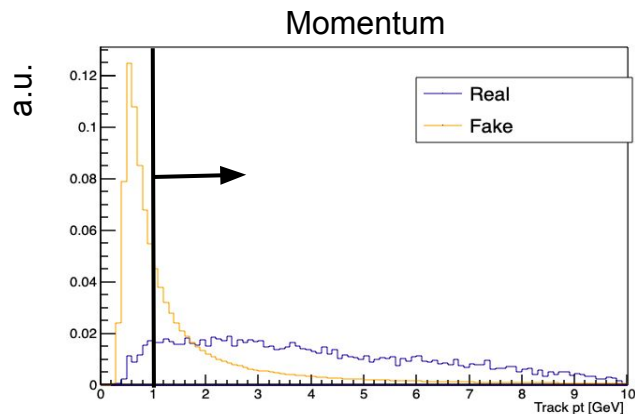
- Cylindrical layout
- All-silicon tracking detector has three parts:
 - Outer tracker
 - Inner tracker
 - Vertex detector
 - Double-layers



	Vertex Detector	Inner Tracker	Outer Tracker
Cell type	pixels	macropixels	microstrips
Cell Size	$25\mu\text{m} \times 25\mu\text{m}$	$50\mu\text{m} \times 1\text{mm}$	$50\mu\text{m} \times 10\text{mm}$
Sensor Thickness	$50\mu\text{m}$	$100\mu\text{m}$	$100\mu\text{m}$
Time Resolution	30ps	60ps	60ps
Spatial Resolution	$5\mu\text{m} \times 5\mu\text{m}$	$7\mu\text{m} \times 90\mu\text{m}$	$7\mu\text{m} \times 90\mu\text{m}$

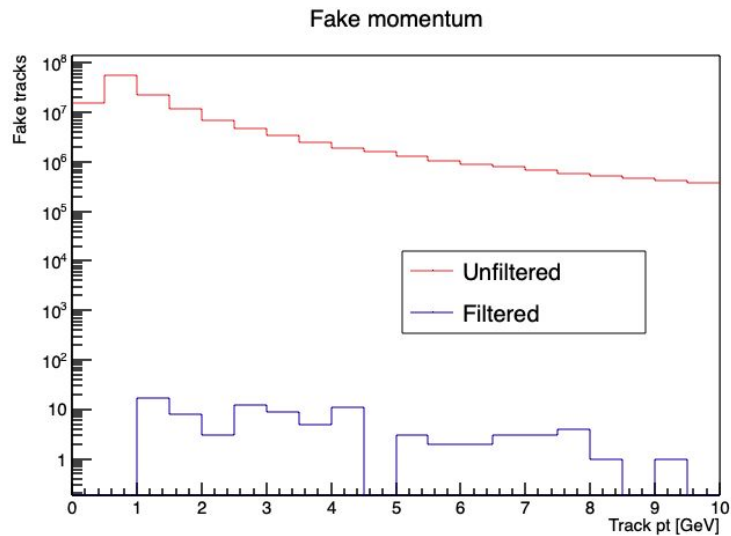
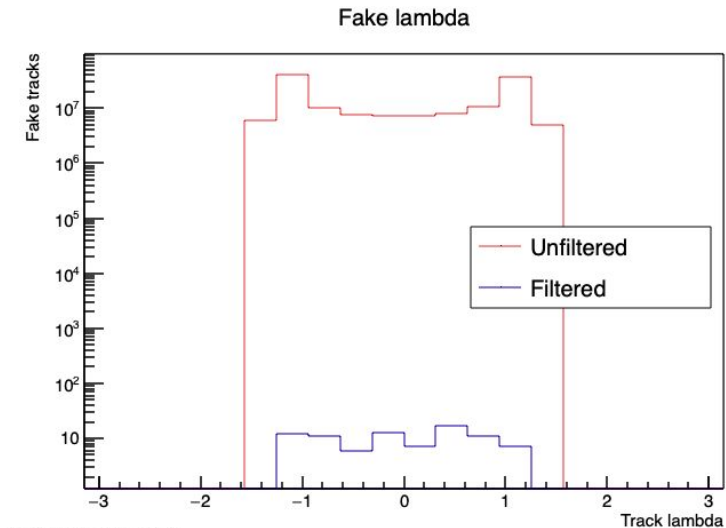
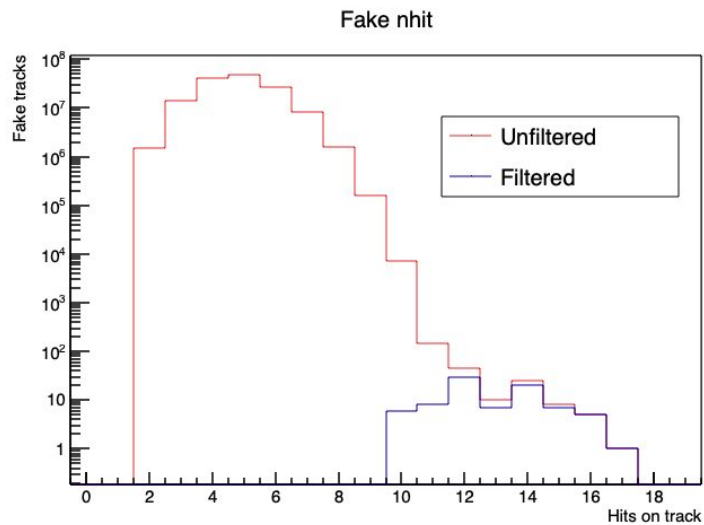
New processor: Filter Tracks

- Takes an input collection of tracks and outputs a collection filtered by certain parameters



Fake tracks

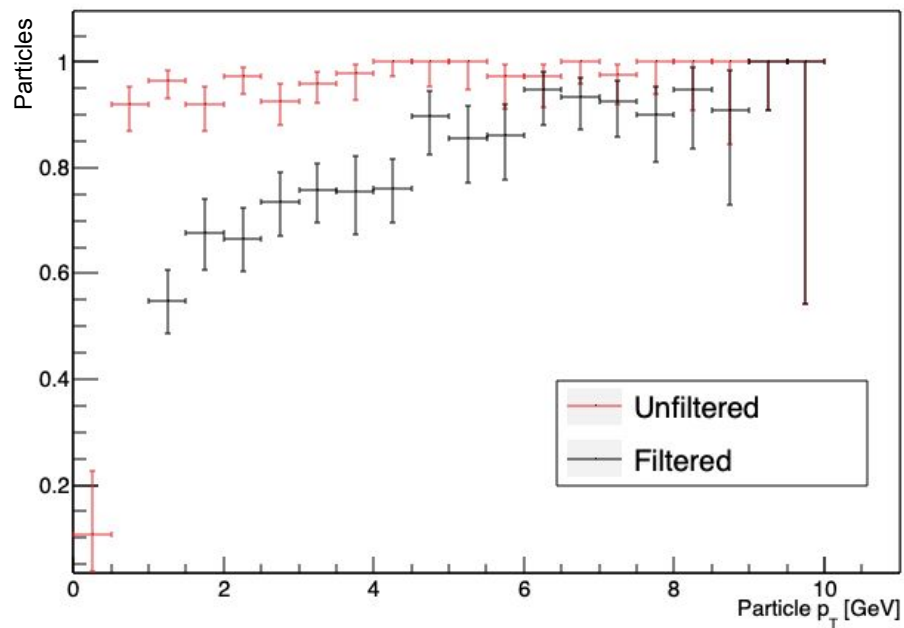
Average number of fake tracks per event: 134,000 \rightarrow 0.08



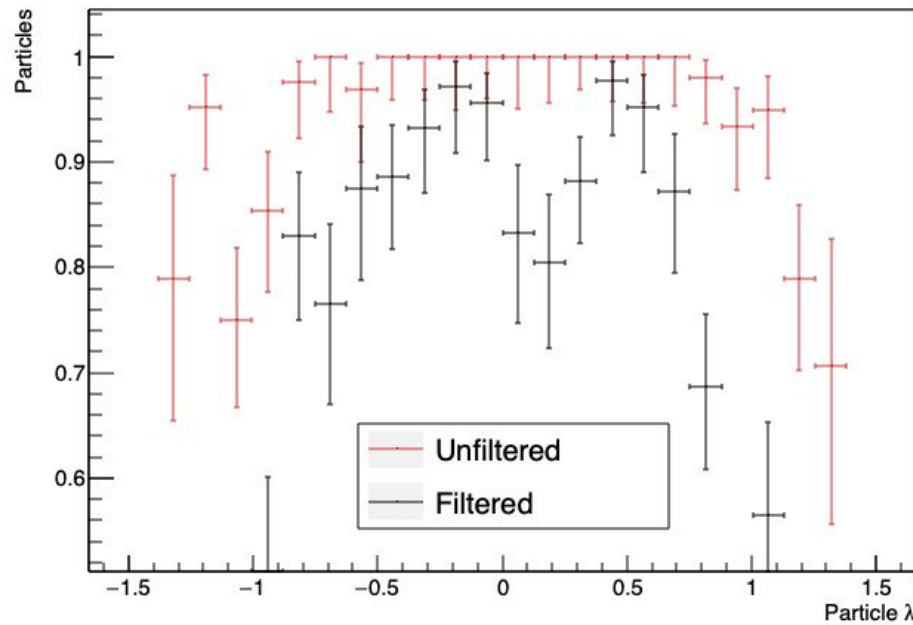
Efficiency

Average efficiency: 0.93 \rightarrow 0.64

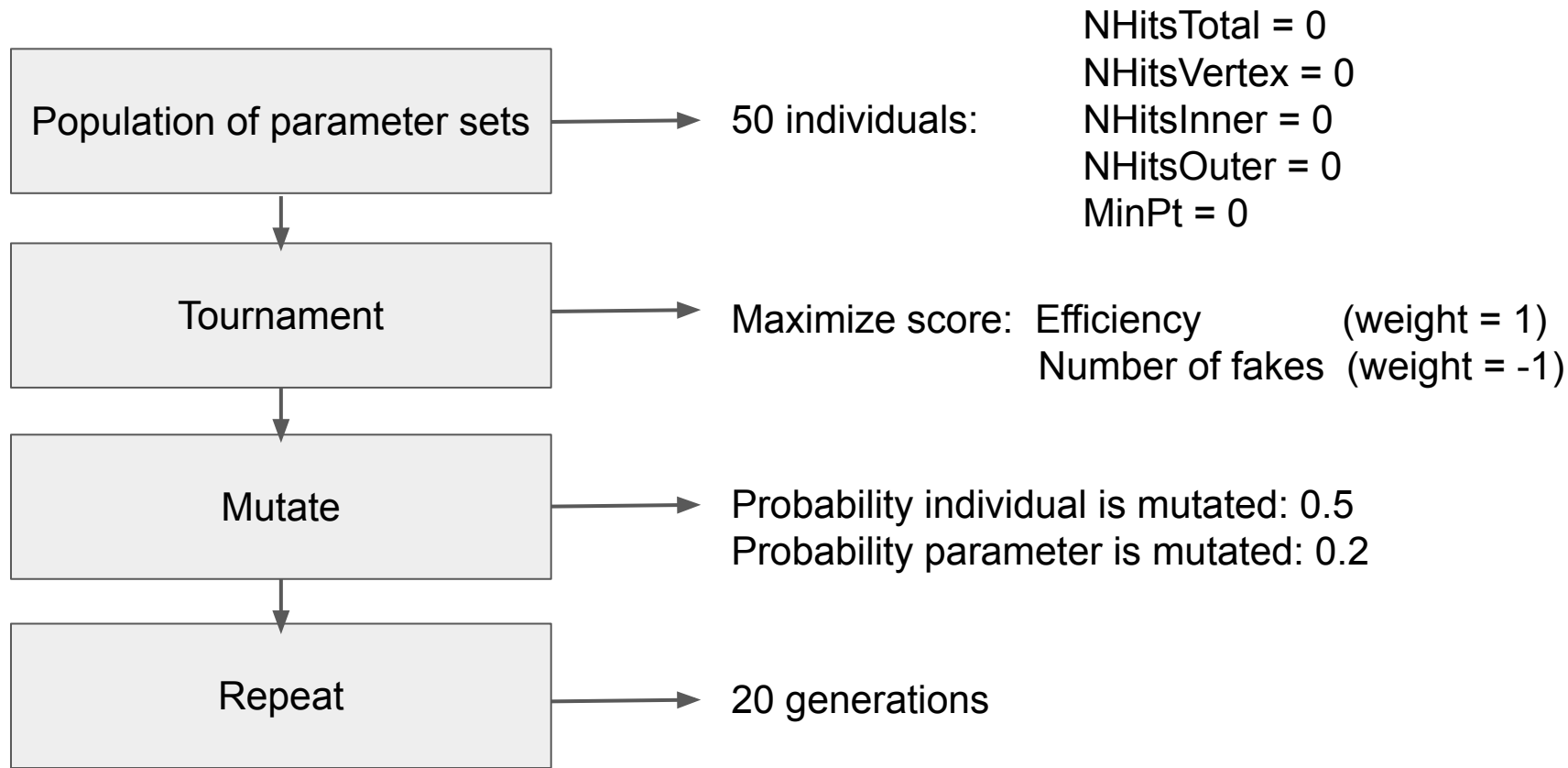
Efficiency vs. Momentum



Efficiency vs. Lambda



Optimization with evolutionary algorithm



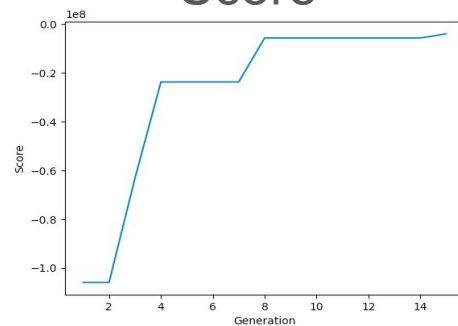
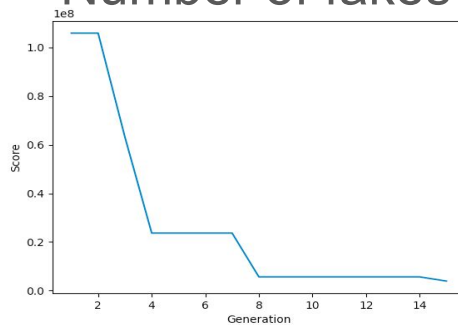
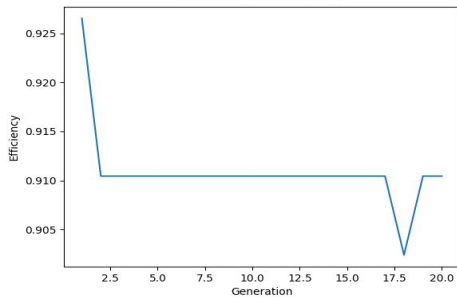
Target efficiency

Efficiency

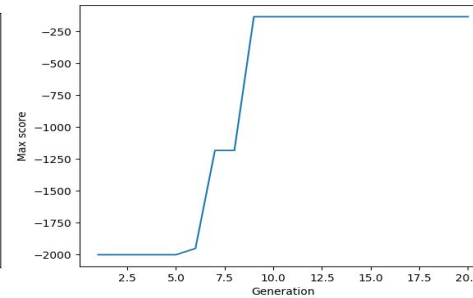
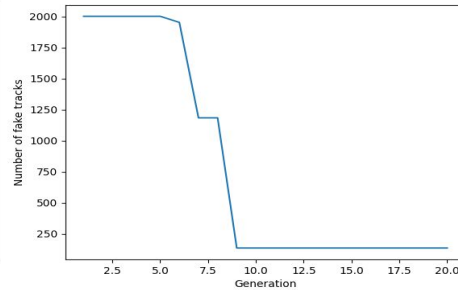
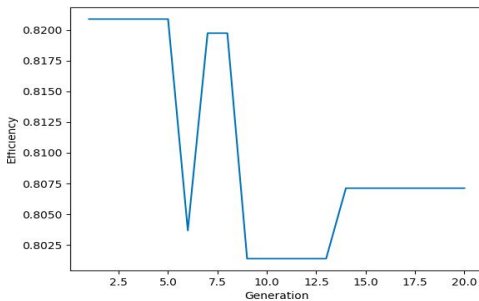
Number of fakes

Score

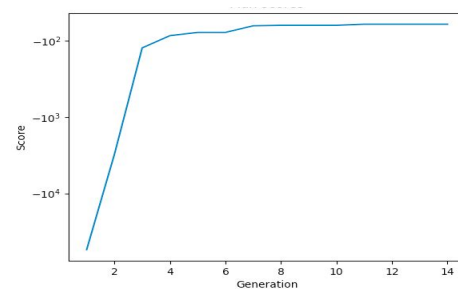
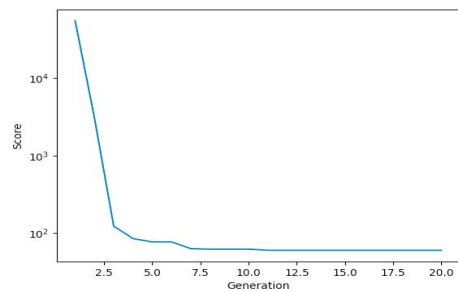
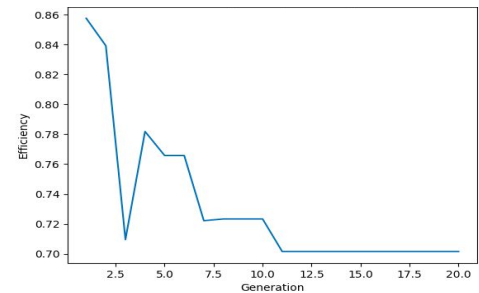
90%



80%

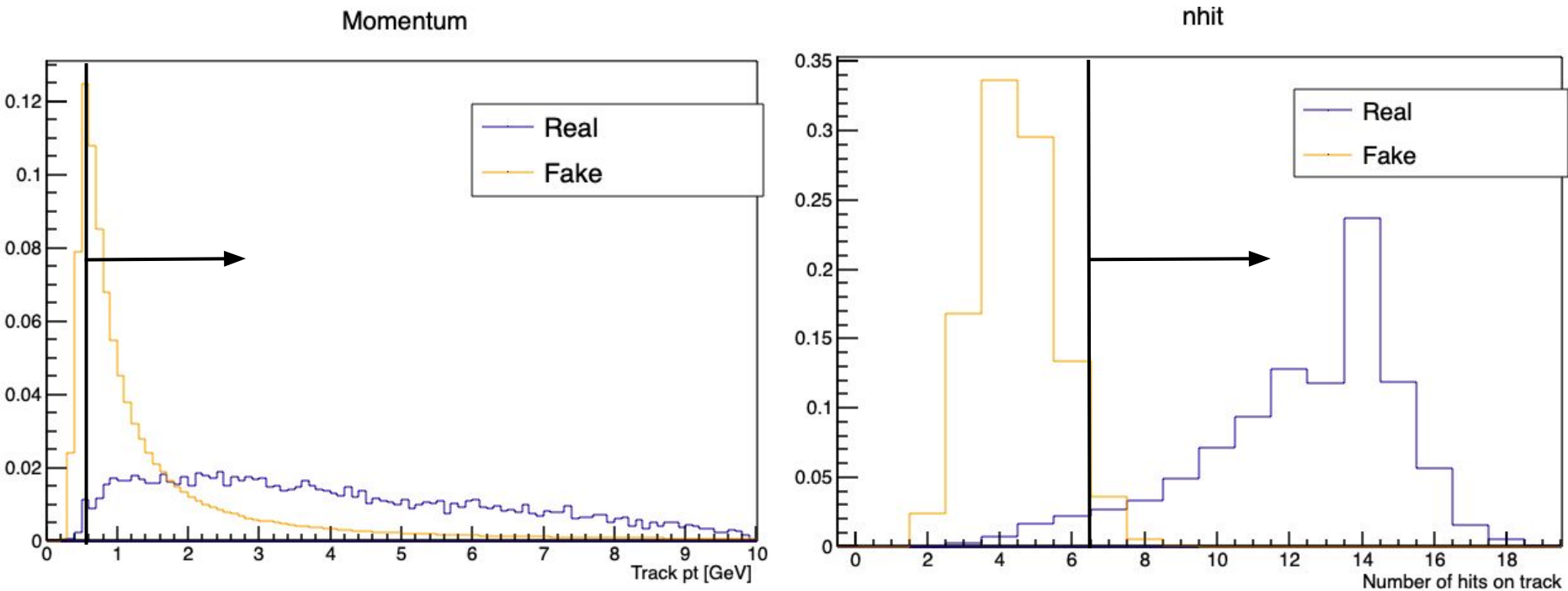


70%



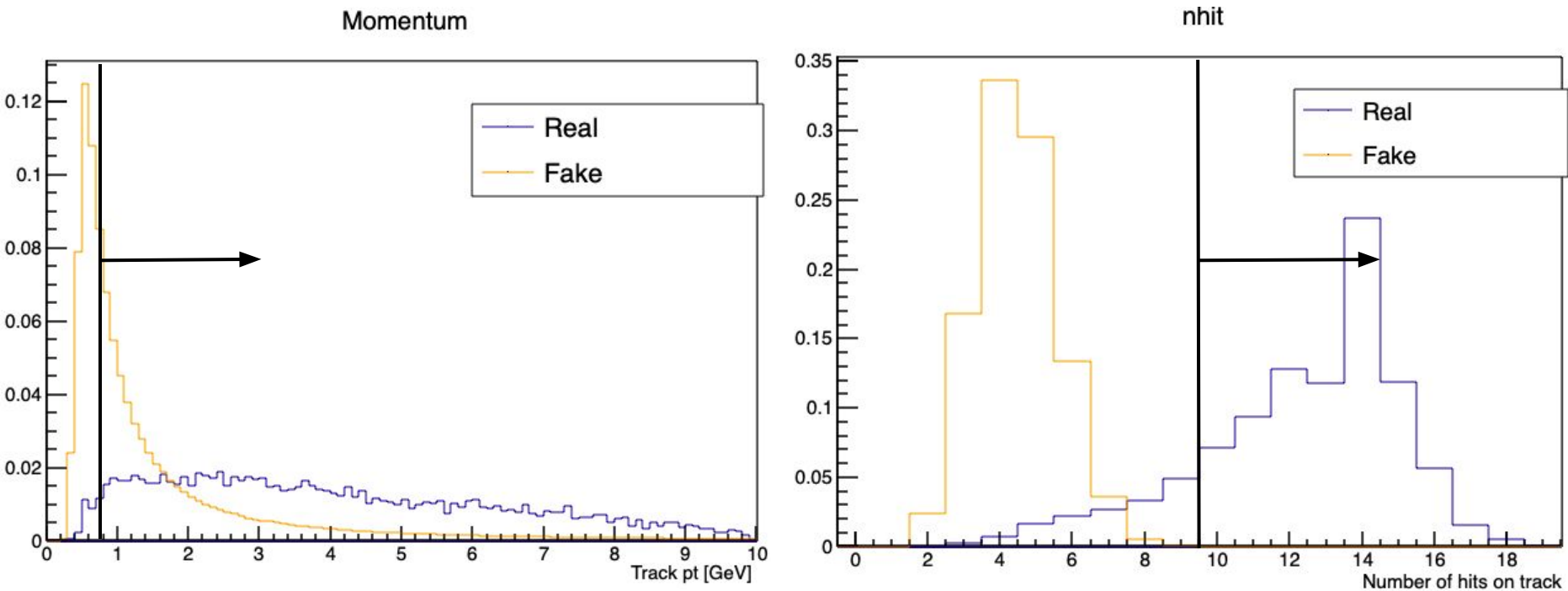
Winning parameters for 90% efficiency:

NHitsTotal = 6, NHitsVertex = 0, NHitsInner = 0, NHitsOuter = 0, MinPt = 0.5



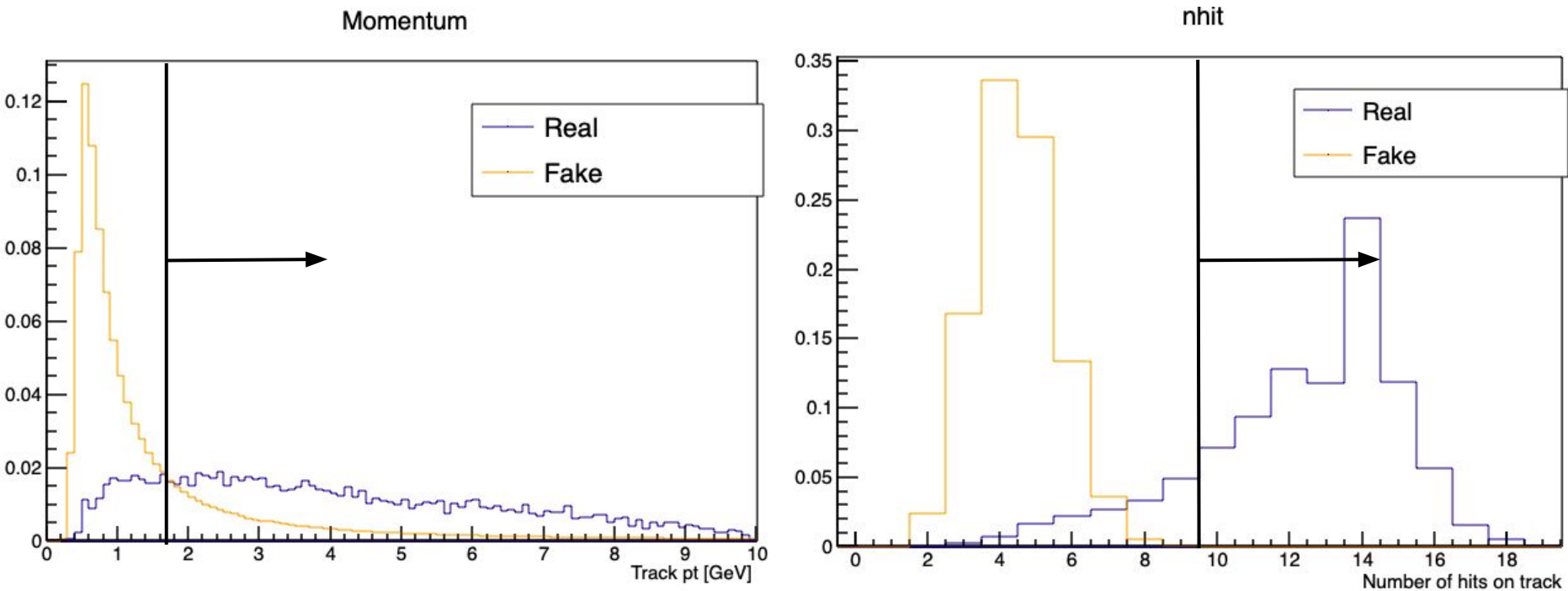
Winning parameters for 80% efficiency:

NHitsTotal = 9, NHitsVertex = 0, NHitsInner = 0, NHitsOuter = 0, MinPt = 0.7



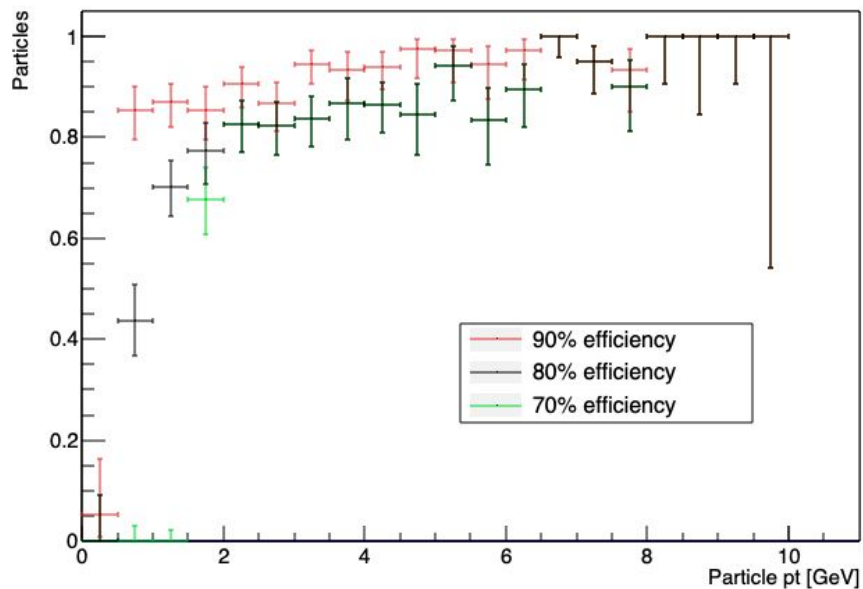
Winning parameters for 70% efficiency:

NHitsTotal = 9, NHitsVertex = 0, NHitsInner = 0, NHitsOuter = 0, MinPt = 1.6

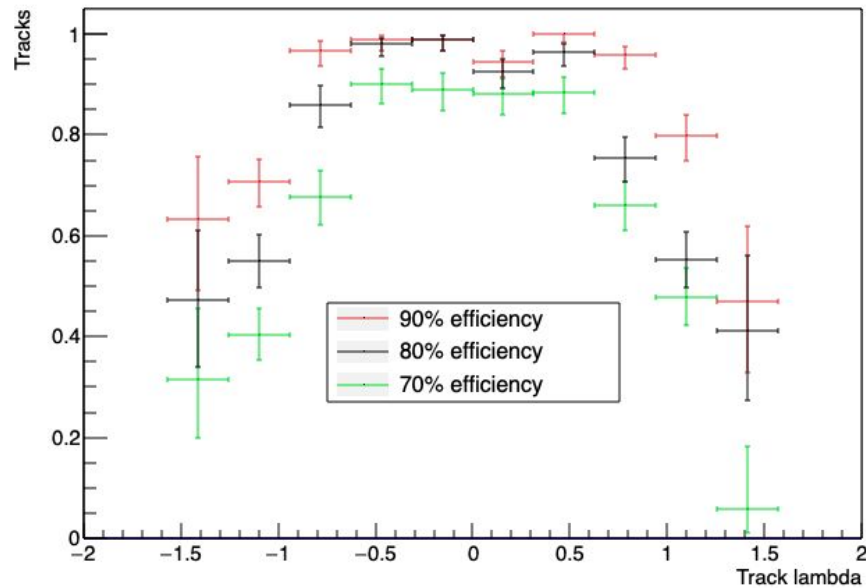


Comparing efficiency

Efficiency



Efficiency



Comparing number of fakes

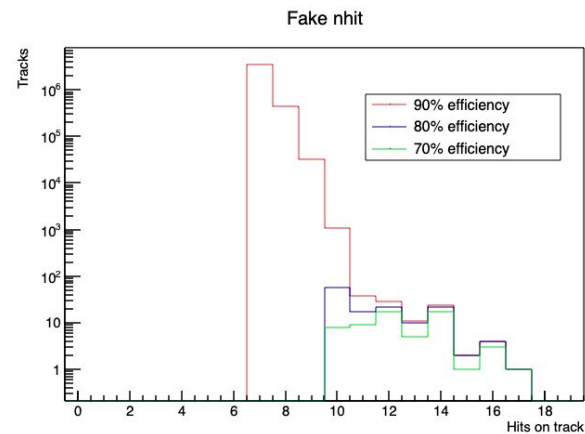
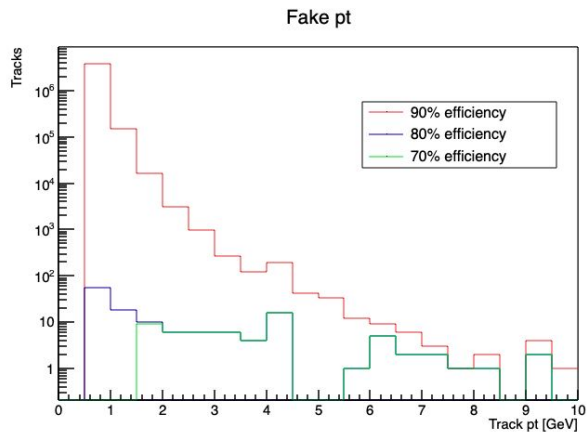
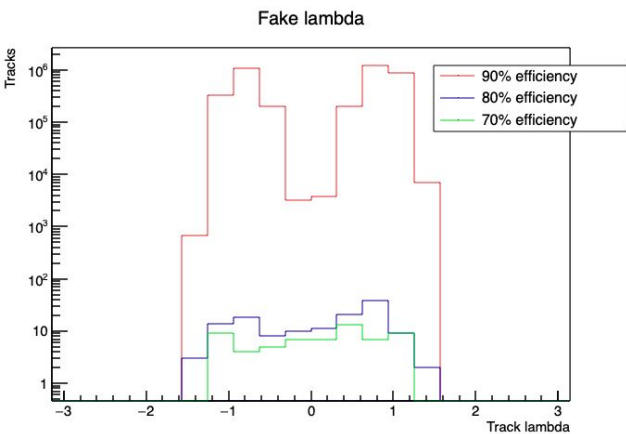
Number of fakes/event: (before filter $\sim 134,000$)

90% \rightarrow $\sim 3,900$

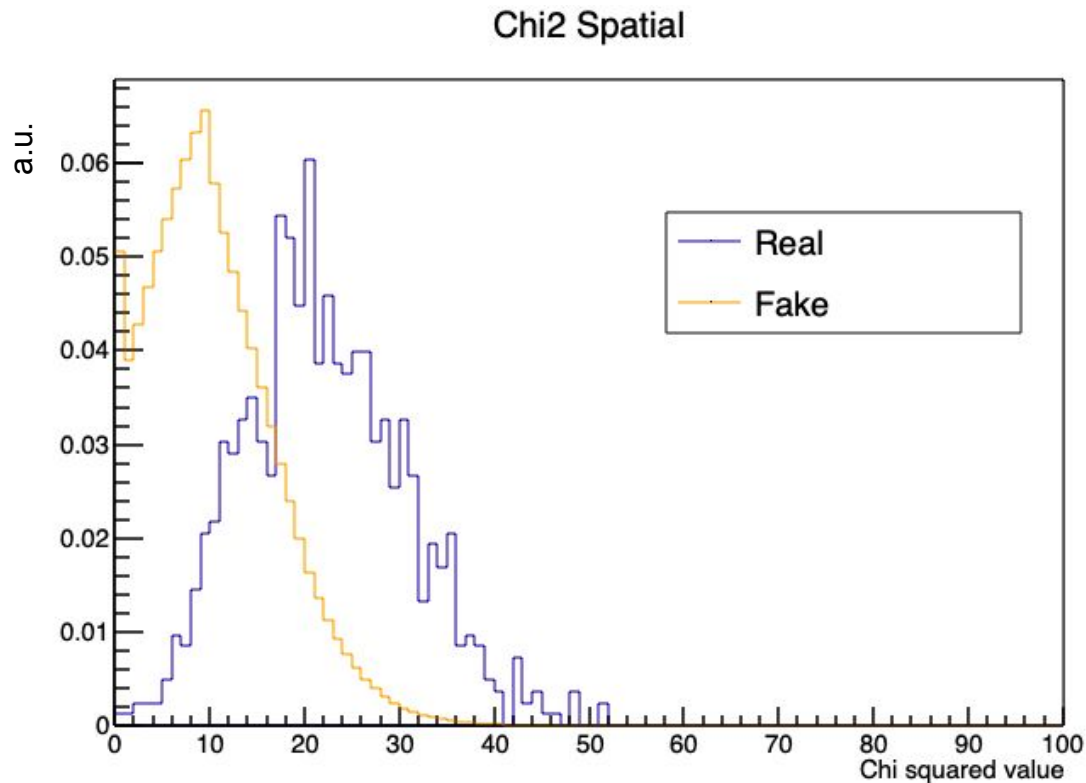
80% \rightarrow ~ 0.13

70% \rightarrow ~ 0.06

(When cutting by hand: 64% \rightarrow ~ 0.08)



Filtering chi-squared values?



Timing information

- Access two consecutive hits on a track (**measured positions and times**)
- Calculate **expected time** between hits (approximate track as a straight line)
- Find difference between expected time and observed time

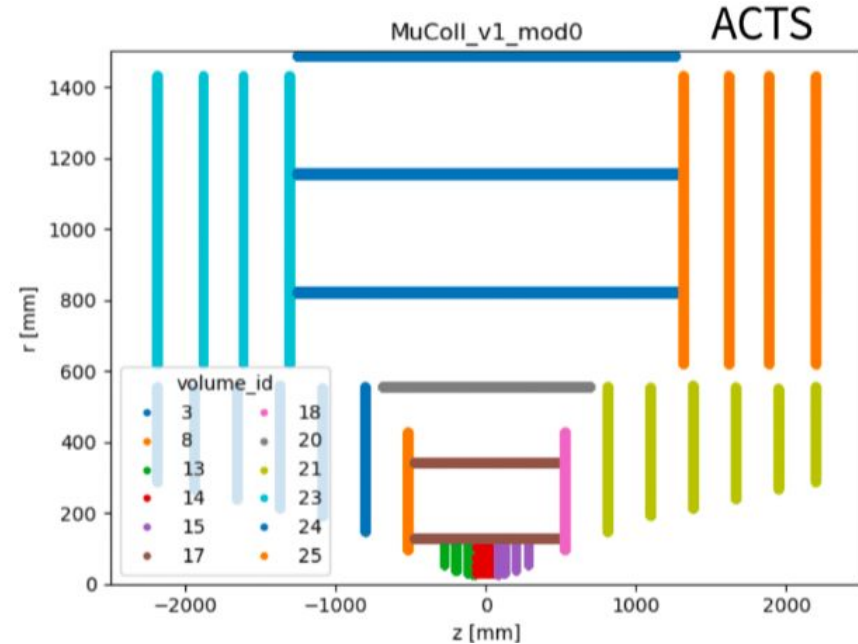
Conclusions

- Cutting fakes comes with a cost on efficiency
- Once a cut on NHitsTotal is made at 9 hits, the most efficient way to reduce fakes is to cut low momentum particles
- Filter could be refined further with spatial chi-squared and timing information
 - Timing cuts could be incorporated into track fitting

Outside-in tracking

ATLAS ITk Layer	ITk Hit Density [mm^2]	MCD Equiv. Hit Density [mm^2]
Pixel Layer 0	0.643	3.68
Pixel Layer 1	0.022	0.51
Strips Layer 1	0.003	0.03

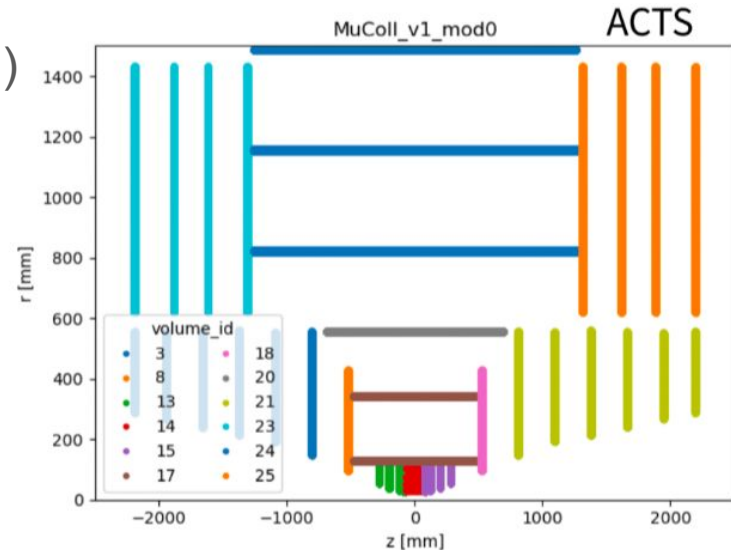
- Outer tracker has lower hit density than vertex detector
- Smaller hit density = fewer seeds = fewer fake tracks
- Try seeding with outer tracker (layers 23, 24, 25)



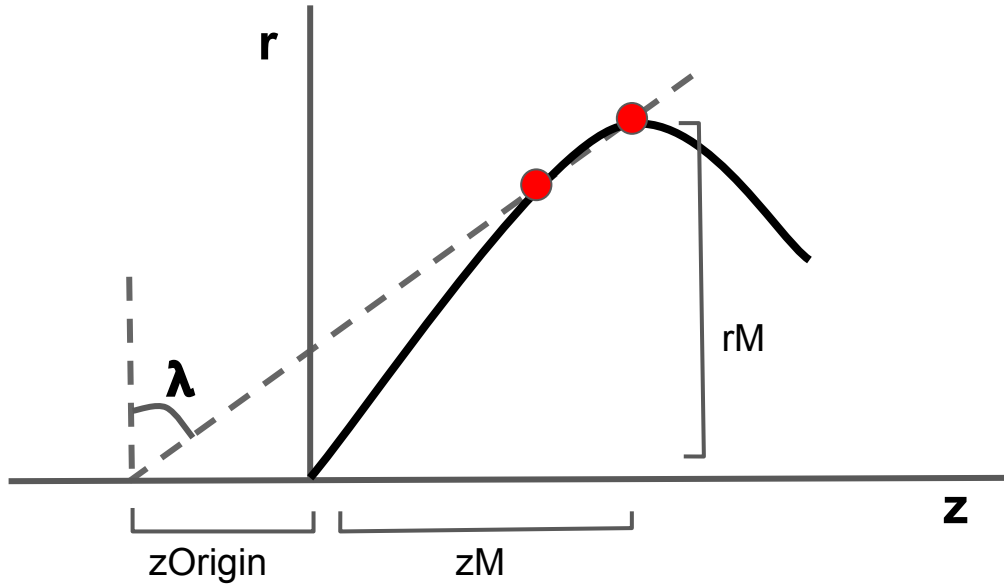
Parameters changed

- SeedingLayers 13, 14 ,15 \rightarrow 23, 24, 25
- SeedFinding_RMax: 150 \rightarrow 1600 (mm)
- SeedFinding_DeltaRMax: 80 \rightarrow 400 (mm)
- SeedFinding_ZMax NA \rightarrow 2500 (mm)
- PropagateBackward FALSE \rightarrow TRUE
- InitialTrackError_Pos 10 \rightarrow 100 (μm)

	Vertex Detector	Inner Tracker	Outer Tracker
Cell type	pixels	macropixels	microstrips
Cell Size	$25\mu\text{m} \times 25\mu\text{m}$	$50\mu\text{m} \times 1\text{mm}$	$50\mu\text{m} \times 10\text{mm}$
Sensor Thickness	$50\mu\text{m}$	$100\mu\text{m}$	$100\mu\text{m}$
Time Resolution	30ps	60ps	60ps
Spatial Resolution	$5\mu\text{m} \times 5\mu\text{m}$	$7\mu\text{m} \times 90\mu\text{m}$	$7\mu\text{m} \times 90\mu\text{m}$



- SeedFinding_CollisionRegion: 1 → 50 (mm)



$$\tan(\lambda) = \frac{zM - zOrigin}{rM}$$

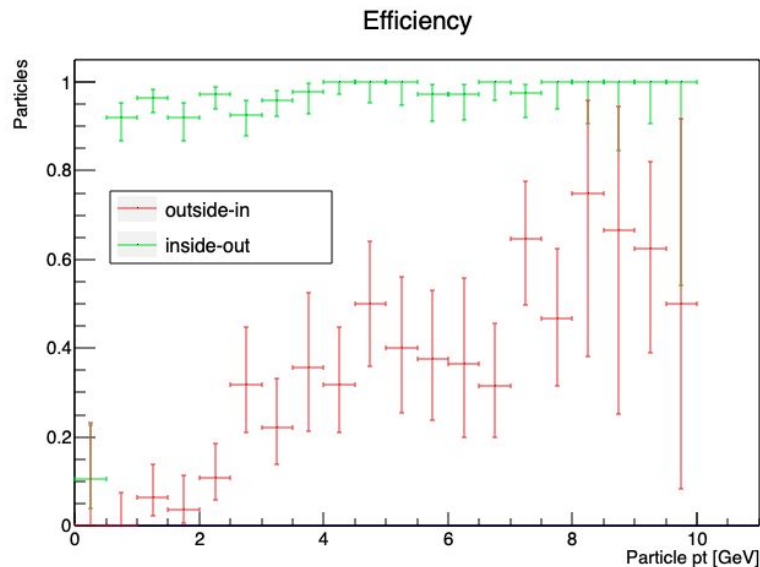
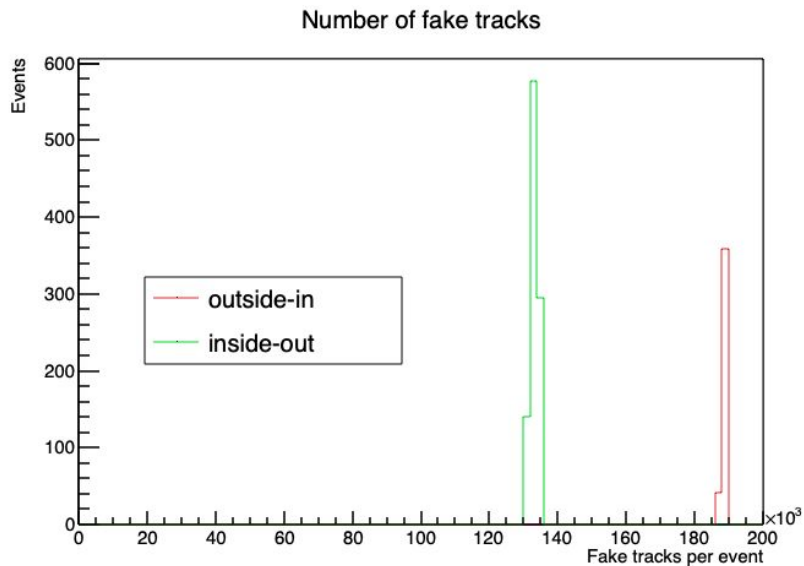
$$zOrigin = zM - rM * \tan(\lambda)$$

- SeedFinding_MinPt 500 → 2000 (MeV)

$$p_T = radius * 300 * B_z$$

Performance

- Outside-in has more seeds, more fake tracks, and lower efficiency
- Outside-in takes longer to complete MyCKFTracking
 - Inside-out: ~ 350 seconds/event
 - Outside-in: ~ 780 seconds/event



Outside-in conclusions:

- Initial assumption that outside-in tracking would have fewer seeds was wrong (with current parameters)
- Possibility of using evolutionary algorithm to optimize parameters
 - Did not complete this because of how long outside-in reconstruction takes
- Outside-in tracking could still be useful for particles with displaced tracks that don't leave hits on the vertex detector (not optimal but possible if necessary)

Final conclusions

- Two methods of reducing fake tracks:
 - Inside-out tracking with track filter, using evolutionary algorithm for optimization
 - Reduction in fakes comes with loss of efficiency, **especially from removing low momentum particles**
 - Could be improved further with **spatial and temporal chi-squared cuts**
 - Outside-in tracking
 - Didn't work as expected
 - **Will impact track reconstruction of displaced particles**

Thanks for listening!
