

Tracking at Colliders with Semiconductor Particle Detectors: Parts 1 & 2

Carl Haber

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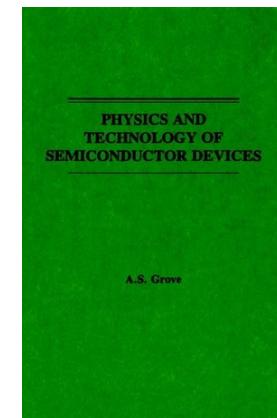
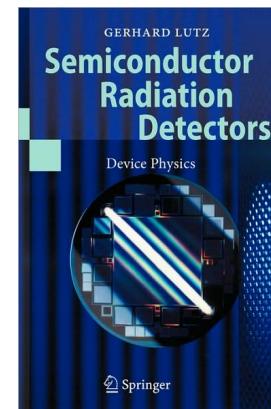
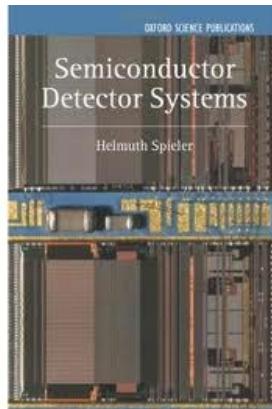
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Suggestions for further reading

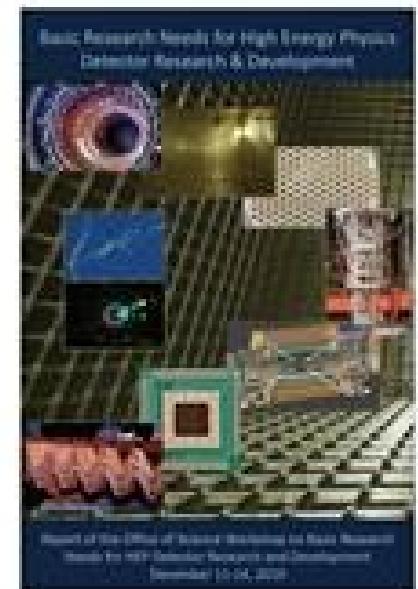
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See also: <http://www-physics.lbl.gov/~spieler/>
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- W.Blum, W.Reigler, L.Rolandi, Particle Detection with Drift Chambers, 2nd edition, Springer, 2008
- https://pdg.lbl.gov/2020/reviews/contents_sports.html
- <https://pdg.lbl.gov/2020/reviews/rpp2020-rev-particle-detectors-accel.pdf>
- [P.A. Zyla et al. \(Particle Data Group\), Prog. Theor. Exp. Phys. 2020, 083C01 \(2020\).](#)

...and references therein



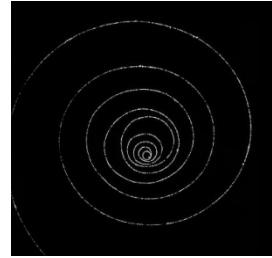
Basic Research Needs

- In 2019-20 the Dept of Energy Office of High Energy Physics requested a community study of needs for transformational instrumentation R&D for future HEP experiments. Report released Aug 2020
- <https://science.osti.gov/hep/Community-Resources/Reports>
- Input to the HEP Snowmass process for summer 2022
- Tracking recommendations
 - High resolution per pixel fast (ps) timing
 - Scalable irreducible mass trackers
 - New materials and processes
 - Sustain/expand/create infrastructure including test beams, irradiation facilities, ASIC and mechanical engineering, silicon fabrication capabilities...

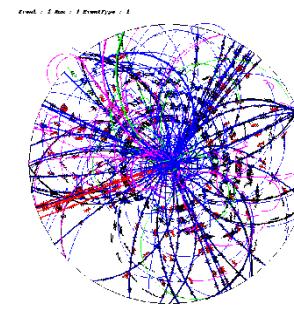


Outline

- Introduction to tracking
- Semiconductor detectors
- Signal processing
- Sensors and architectures
- Radiation effects
- System issues – mechanics, power, metrology
- Conclusions



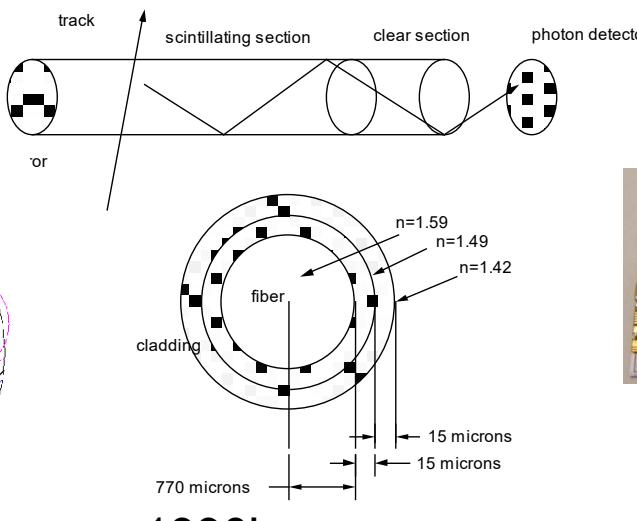
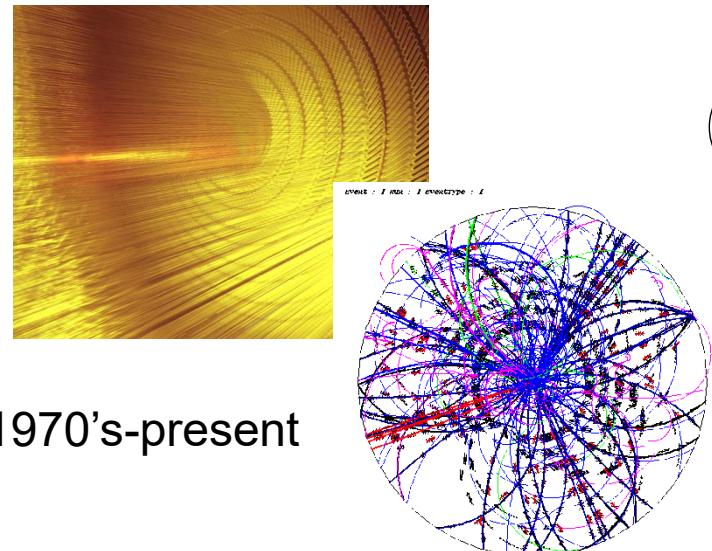
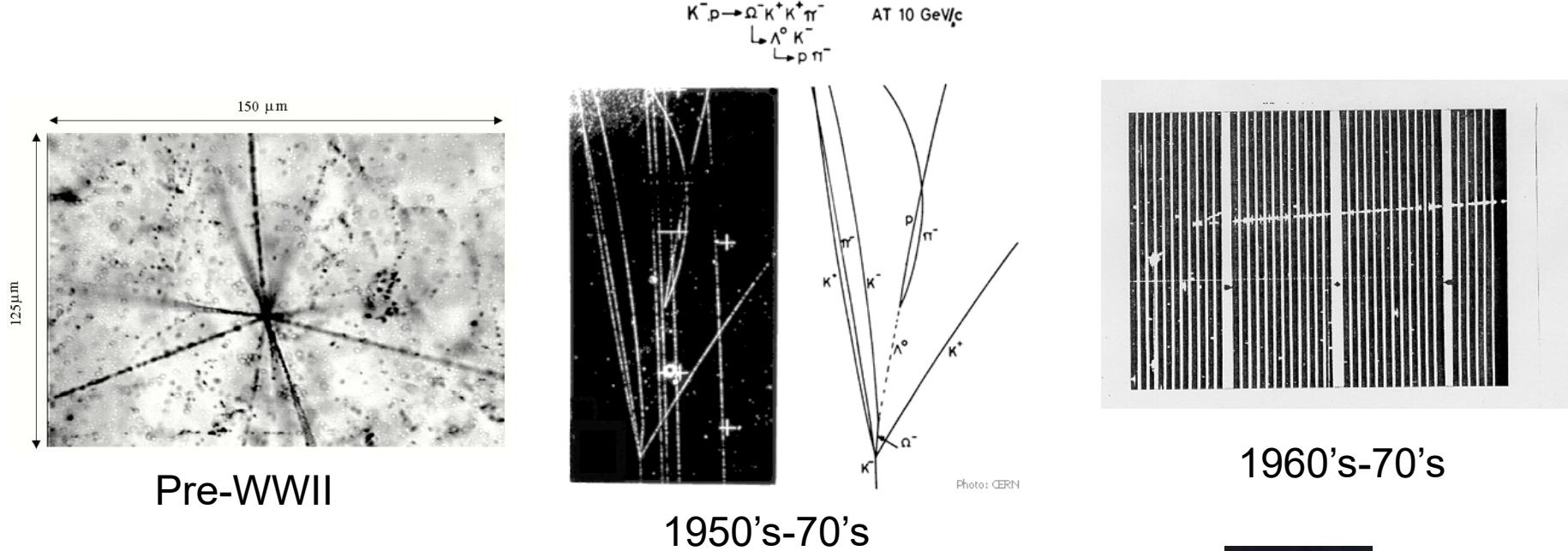
Tracking



- The process of sampling a particle's trajectory and determining its parameters.
 - Momentum, Direction, Decay points (kinks)
- High energy
 - Small fraction of energy deposited in instrument
- Trajectory is disturbed minimally by the process.
- Charged particles ionize matter along their path.
- Tracking is based upon detecting ionization trails.
- An “image” of the charged particles in the event.

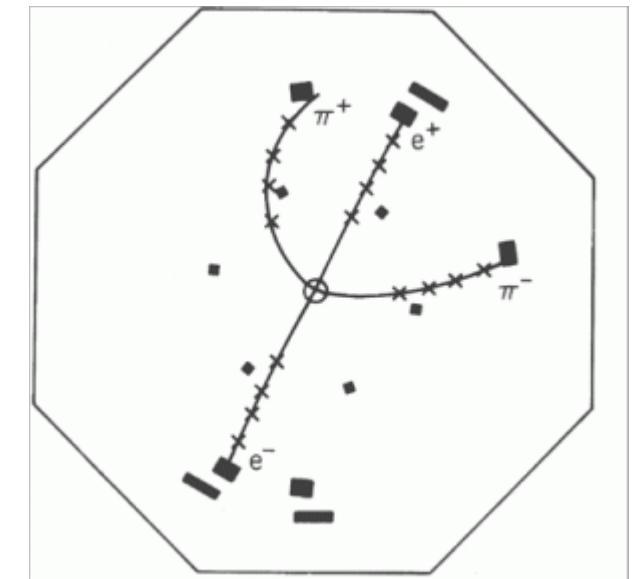
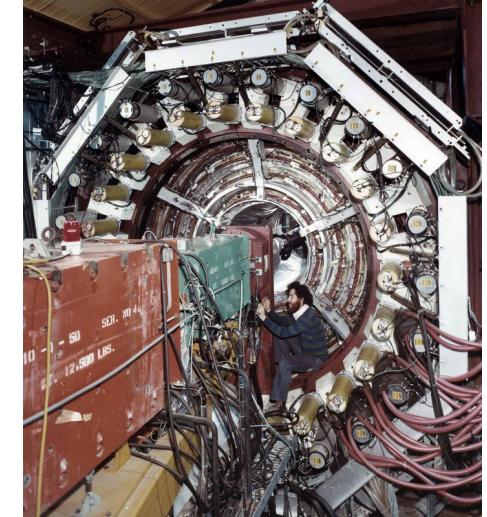
Technology

- “Old”: Emulsions, cloud, and bubble chambers
 - Continuous media
 - Typically gave very detailed information but were slow to respond and awkward to read out
- “New”: Electronic detectors, wire chambers, scintillators, solid state detectors
 - Segmented
 - Fast, can be read out digitally, information content is now approaching the “old” technology



Track Parameters

- Basic idea is a track curving in a magnetic field
- 3D track described by 5 parameters
- p =momentum (or curvature in B field)
- d =distance of closest approach to the origin
- ϕ =azimuthal angle at the origin
- z_0 = vertex along the beamline
- θ = polar angle



Tracker Characteristics

- Performance on reconstruction of track parameters defined in terms of:
 - parameters of the system (geometry, layout, material, magnetic field, etc)
 - performance of position sensing elements.
- Performance of position sensing elements
 - hit resolution, timing resolution, effects of data transmission, 1D/2D/3D
 - Radiation damage effects
 - defined by physics of detecting medium/process and general considerations such as segmentation and geometry.
- Evaluation
 - Initially evaluate with simple parametric analyses.
 - Fast simulation
 - Full simulation
 - Bench, CR, and beam tests

Momentum Resolution

Simple case: Measure sagitta s of track with radius R , over projected arc length L (cm, KGauss, MeV/c), assuming $R \gg L$

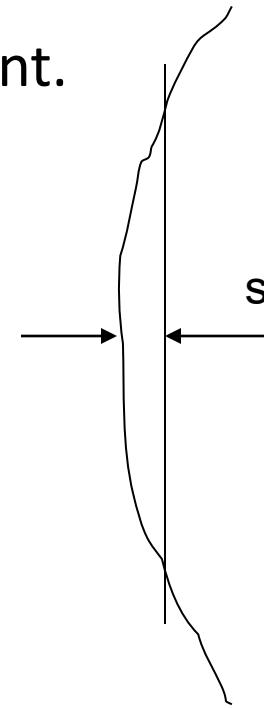
$$p = \frac{0.3BR}{\cos \theta} = \frac{0.3BL^2}{8s \cos \theta} \text{ using } R = \frac{L^2}{8s} \Rightarrow \left(\frac{\Delta p}{p} \right)_{sagitta} = \frac{8p\Delta s}{0.3BL^2 \cos \theta}$$

where Δs is the error on the sagitta measurement.

Effect of material: multiple scattering

$$(\Delta s)^2 = \frac{\sigma_{MCS}^2}{16} \frac{L^2}{3 \cos^2 \theta} \Rightarrow \left(\frac{\Delta p}{p} \right)_{MCS} = \frac{52.8}{B \sqrt{L X_0 \cos \theta}}$$

$$\frac{\Delta p}{p}_{TOTAL} = \left(\left(\frac{\Delta p}{p} \right)_{sagitta}^2 + \left(\frac{\Delta p}{p} \right)_{MCS}^2 \right)^{\frac{1}{2}}$$



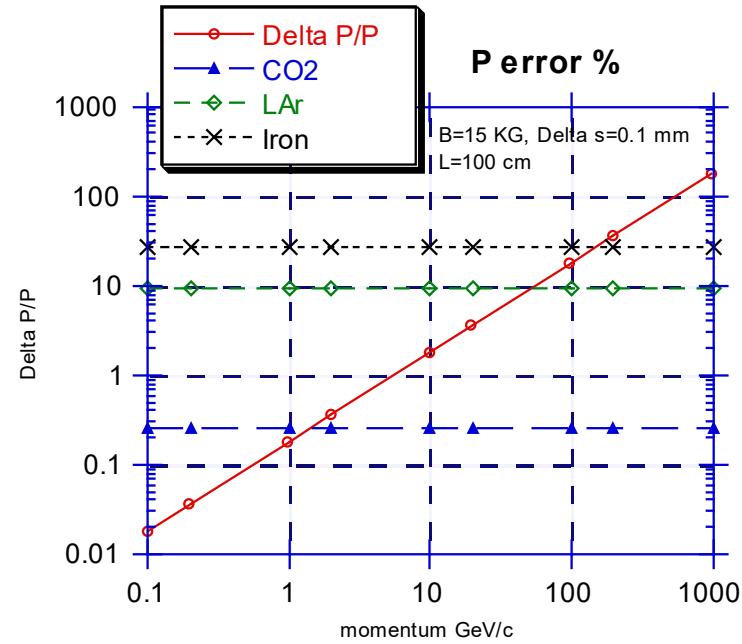
Effect of Material

$$\left(\frac{\Delta p}{p}\right)_{sagitta} = \frac{8p\Delta s}{0.3BL^2 \cos \theta}$$

$$\left(\frac{\Delta p}{p}\right)_{MCS} = \frac{52.8}{B\sqrt{LX_0 \cos \theta}}$$

$$\frac{\Delta p}{p}_{TOTAL} = \left(\left(\frac{\Delta p}{p}\right)_{sagitta}^2 + \left(\frac{\Delta p}{p}\right)_{MCS}^2 \right)^{\frac{1}{2}}$$

- Minimize sagitta error
- Maximize B,L
- Minimize material



Vertex Resolution

$x1, x2$ = measurement planes

$y1, y2$ = measured points, with errors δy

$$y = a + bx$$

$$b = \text{slope} = \frac{y1 - y2}{x1 - x2} = \frac{y1 - y2}{\Delta x}$$

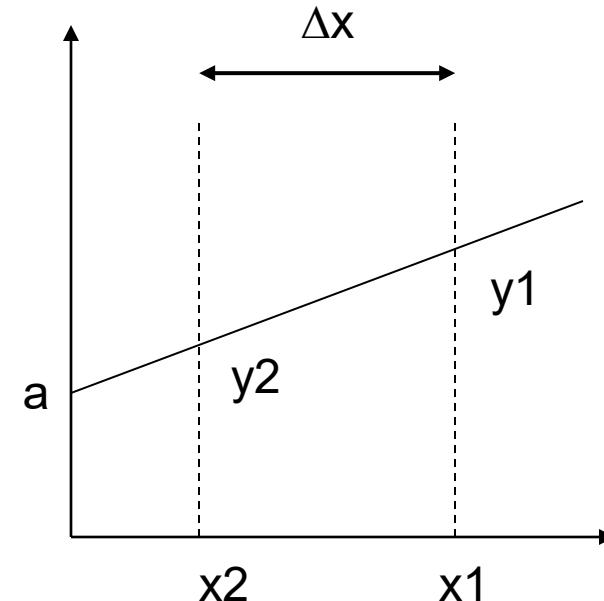
$$a = \text{intercept} = \frac{1}{2}(y1 + y2) - \frac{1}{2}(y1 - y2)\left(\frac{x1 + x2}{\Delta x}\right) = \bar{y} - b\bar{x}$$

$$(\delta b)^2 = \left(\frac{\partial b}{\partial y1}\right)^2 (\delta y)^2 + \left(\frac{\partial b}{\partial y2}\right)^2 (\delta y)^2 \Rightarrow \delta b = \frac{\sqrt{2}\delta y}{\Delta x}$$

$$\delta a = \frac{\delta y}{2} \sqrt{1 + \frac{8\bar{x}}{\Delta x}}$$

for good resolution on angles (ϕ and θ) and intercepts (d, z_0)

- Precision track point measurements
- Maximize separation between planes for good resolution on intercepts
- Minimize extrapolation - first point close to interaction

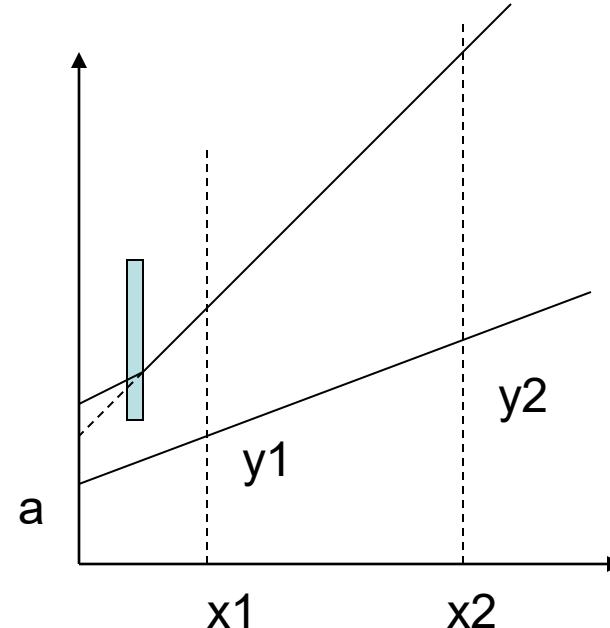


Effect of Material

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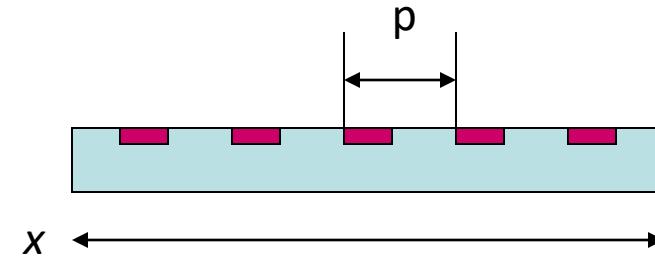


for good resolution on angles (f and q) and intercepts (d, z_0)

- Precision track point measurements
- Maximize separation between planes for good resolution on intercepts
- Minimize extrapolation - first point close to interaction
- Material inside 1st layer should be at minimum radius (multiple scattering)

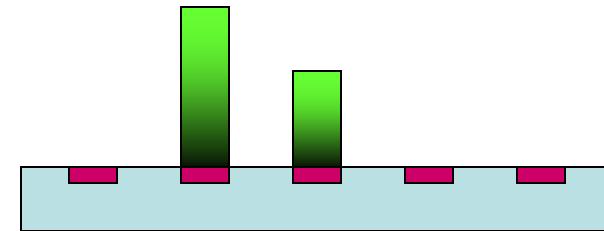
Point Resolution: Segmentation

- Discrete sensing elements (binary response, hit or no hit), on a pitch p , measuring a coordinate x



$$\sigma_x = \frac{p}{\sqrt{12}}$$

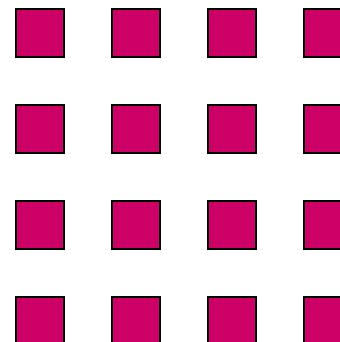
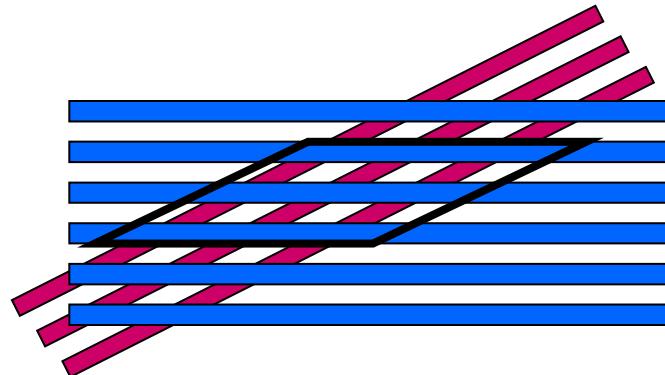
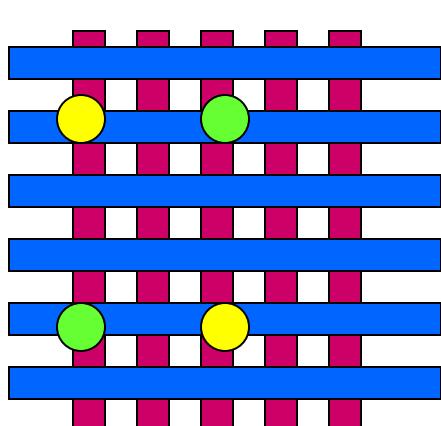
- Discrete sensing elements (analog response with signal to noise ratio S/N) on a pitch p , where f is a factor depending on pitch, threshold, cluster width



$$\sigma_x \sim fp\left(\frac{N}{S}\right) < \frac{p}{\sqrt{12}}$$

2D

- The problem of 2 dimensions:
 - 90° array of n elements on pitch p : equal resolution on both coordinates.
 - m hits $\rightarrow m^2$ combinations with $m^2 - m$ false combinations
 - Small angle stereo geometry, angle α
 - False combinations are limited to the overlap region but resolution on second coordinate is worse by $1/\sin(\alpha)$
- Pixel structure: $n \times m$ channels
 - Ultimate in readout structure
 - Expensive in material, system issues, technology, cost
- Pixels and strips can also be thought of as 2 extremes of a continuum (super-pixels, short-strips,...)
 - Some potential for optimizations of performance vs. complexity but needs to be analyzed on a case by case basis

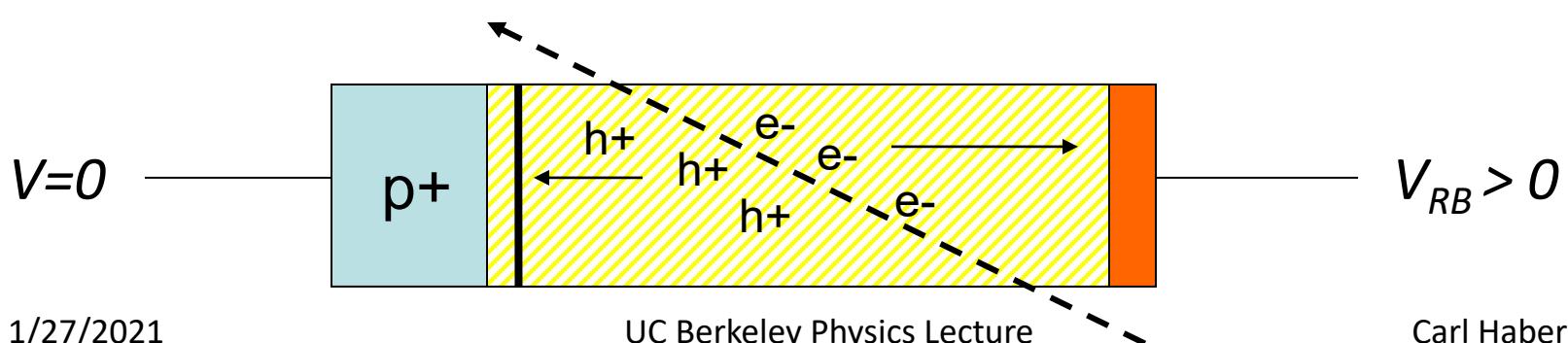
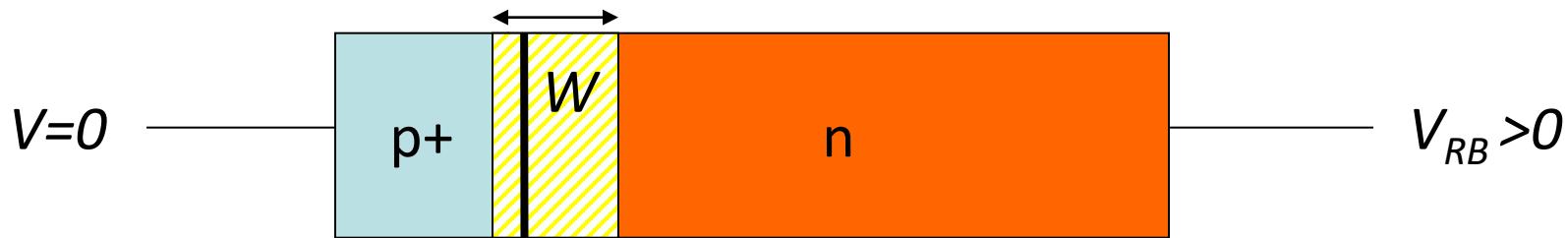


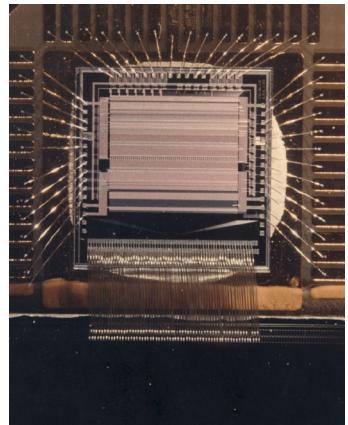
Semiconductor Detectors

- Since mid-80's use of position sensitive "silicon detectors" became widespread
- Can resolve track positions to ~ 10 microns
- Used to measure **momentum** and identify secondary **vertices** due to decays of primary particles
- Handle high particle rates and radiation dose
- Substantial commercial basis for technology

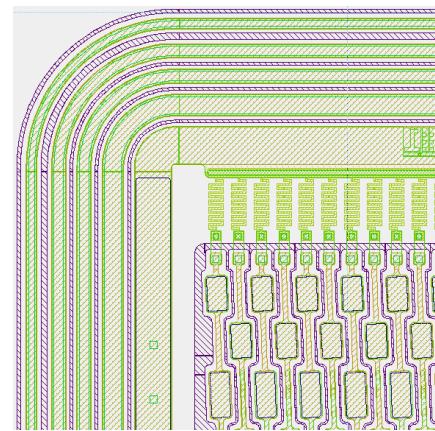
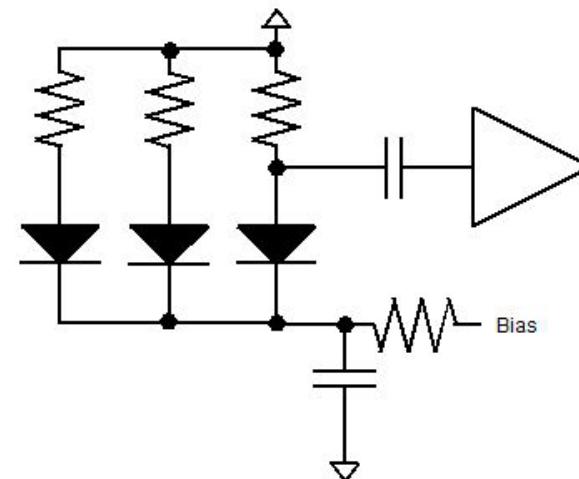
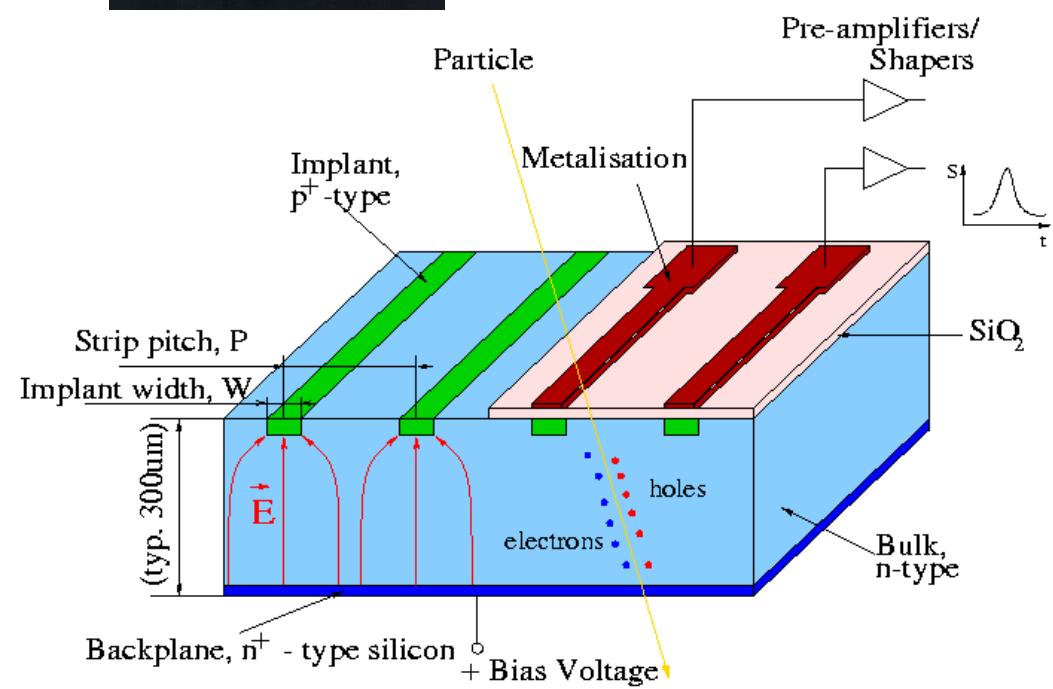
Silicon Detectors

- Asymmetric diode junction: p(+) into contact with n, ($N_A \gg N_D$) (can also have n+ in p)
- Space charge region formed by diffusion of free charges, increased with "reverse bias"
- Electron-hole pairs formed in the depletion zone drift under the influence of the electric field
- Signal depends on width of depletion zone
- Drift time determined by mobility and field
 - ~7 ns to cross 300 microns
- Drifting charge is a current which can be measured

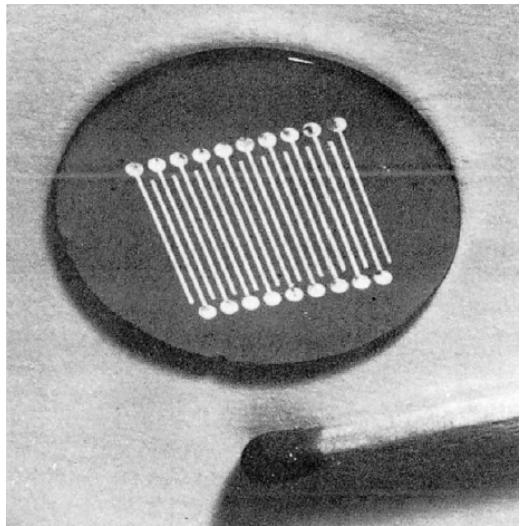




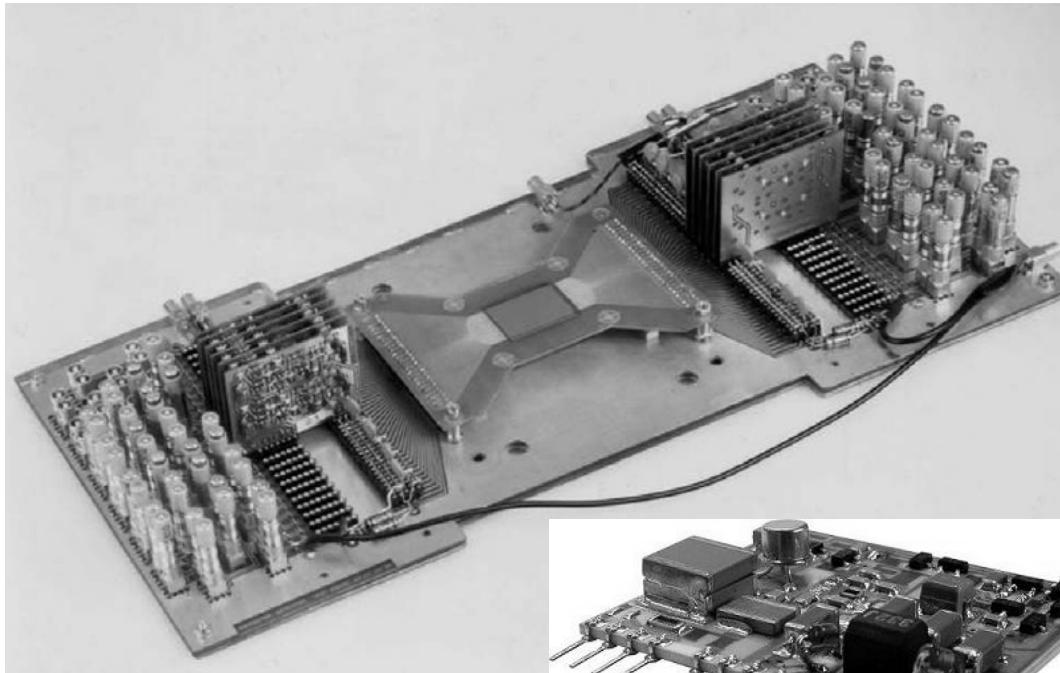
Basic Strip Sensor Details



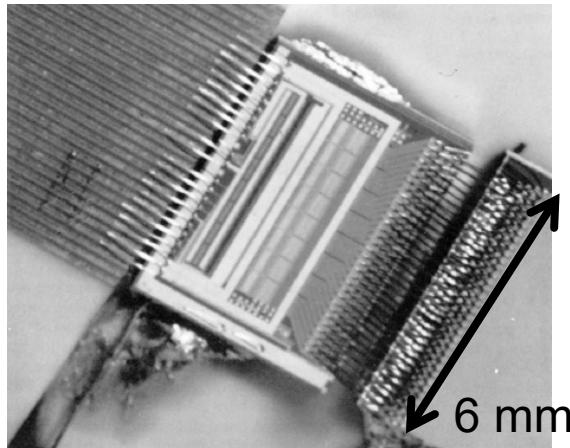
Looking for charm in fixed target hadronic interactions.....b's at lepton colliders....Higgs/BSM @LHC



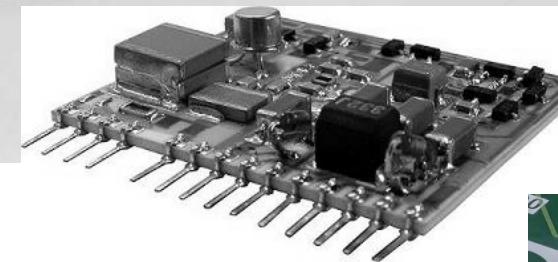
Late 1970's surface barrier strip detector (Pisa)



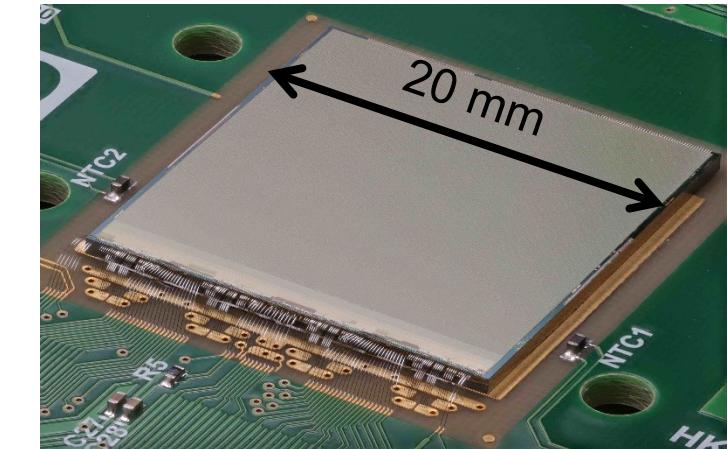
~1980, 128 discrete channels
~14 mW/channel (CERN)



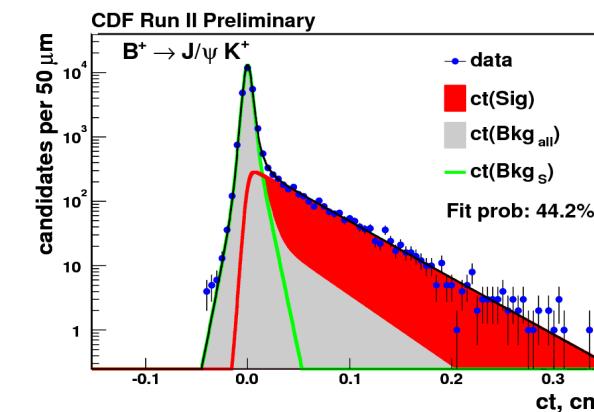
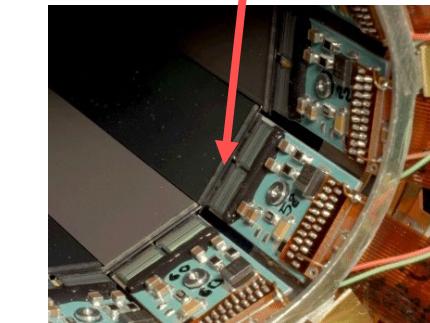
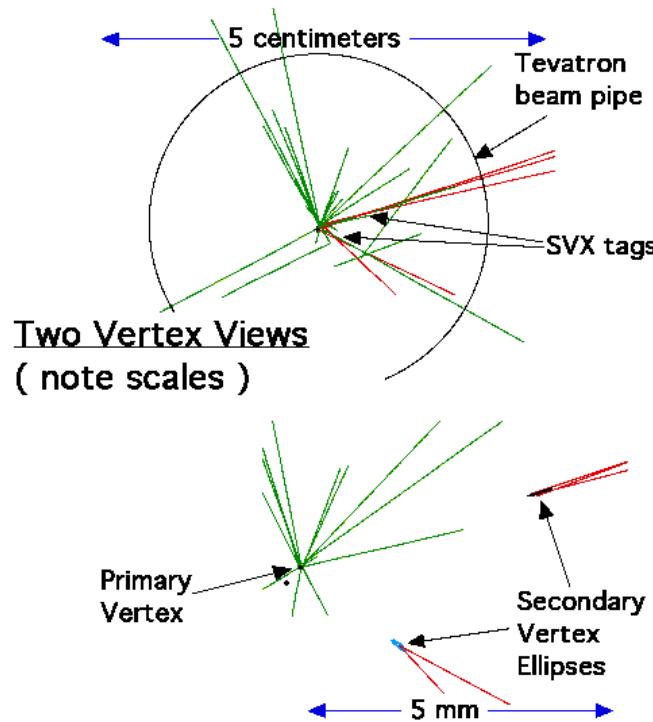
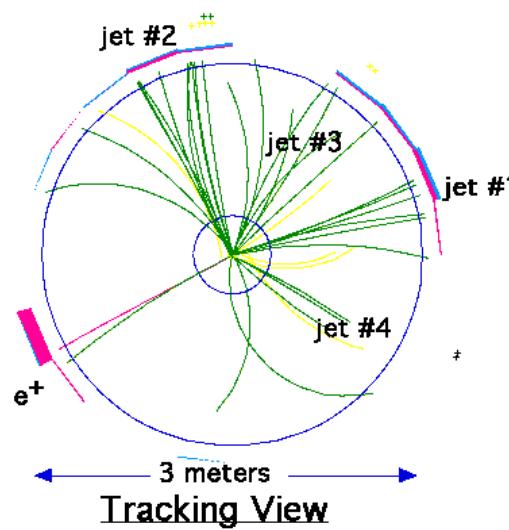
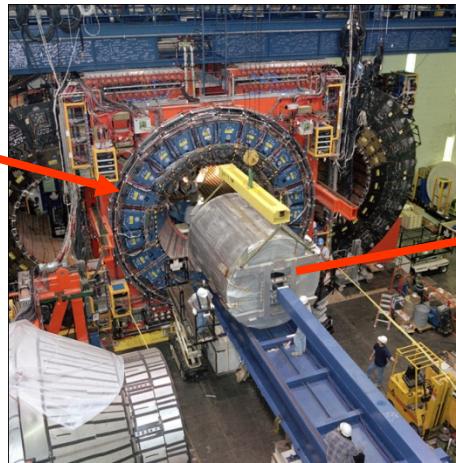
~1985, "Microplex", 3 mW/ch
1st 128 readout ASIC,
1st application to colliding beams
(SLAC Mark II)
(Parker,Hyams,Walker)



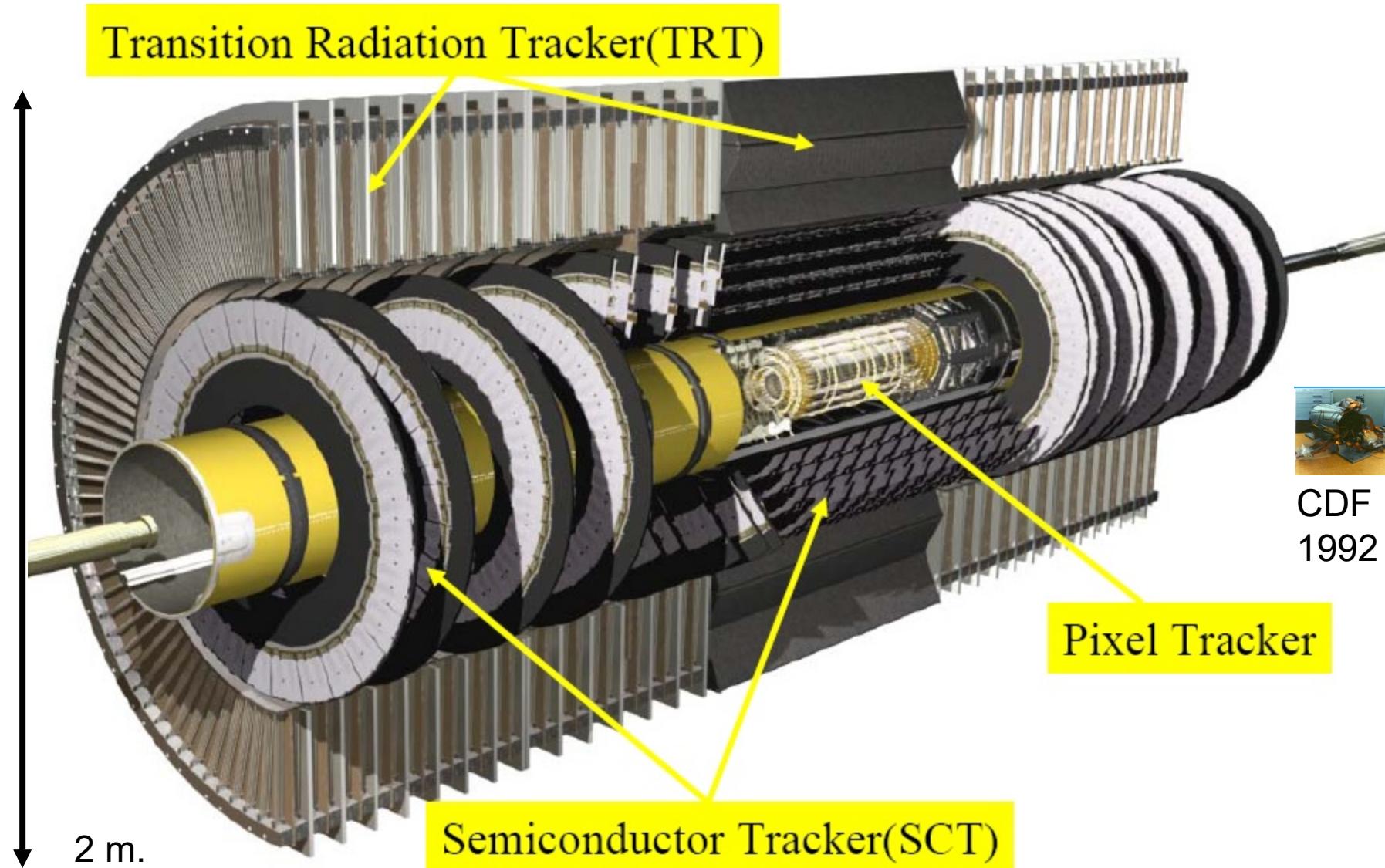
2020 RD53B
ATLAS
153,600 pixels
8 μ A /pixel



Finding top and bottom at the Tevatron ~1995.....



CERN ATLAS tracker (4th generation, beam in 2008)

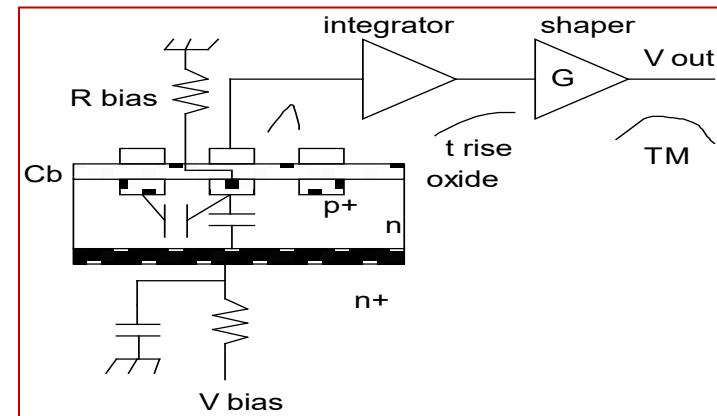


Hadron Collider View

| generation | year | luminosity | ΔT | chan/area | dose | readout |
|-----------------|-------|--------------------|-----------------|--|----------------------------------|--------------------------------------|
| 1 CDF SVX | 1990 | 10^{29} | 3.5 μ s | 50K/ 0.68 m ² | 25 Krad | 3 μ m CMOS |
| 2 CDF SVX* | 1995 | 10^{30} | 3.5 μ s | 50K | 100 Krad | 1.2 μ m RHCmos |
| 3 Run 2 | 2000 | 10^{32} | 128 ns | 600K / 5 m ² | 1 Mrad, $10^{13}/\text{cm}^2$ | 0.8 μ m RHCmos |
| 4 LHC | 2009 | 10^{34} | 25 ns | 5×10^6 / 68 m ² 10^8 pixels | 10 Mrad 10^{15} | 0.25 μ m CMOS RH Bi-CMOS |
| 5 HL-LHC | 2025 | 5×10^{34} | 25 ns | 10^8 / 200 m ² 10^9 pixels | 100 Mrad 10^{16} | 65 – 130 nm CMOS SiGe, Commercial |
| 6 HE-LHC/FCC | >2035 | 3×10^{35} | 25 ns (5 ps) | 5×10^8 / 400 m ² 5×10^9 pixels | 1-10 Grad 10^{18} | Unknown features Monolithic CMOS? |

Signal Processing Issues

- Signal
 - Energy loss by particle in Si
 - Proportional to thickness (volume)
 - Radiation can effect efficiency
- Leakage current
 - If DC coupled then must be compensated by filter, feedback, or injection
 - Before (after) LHC radiation damage $\sim 1 \text{ nA}$ ($1 \mu\text{A}$)
 - AC component is seen by pre-amp: noise source
- Input Noise
 - Preamp “input noise charge”, white noise, decreases with pre-amp current, increases with faster risetime
 - Bias resistor: source of thermal noise
 - Radiation activated



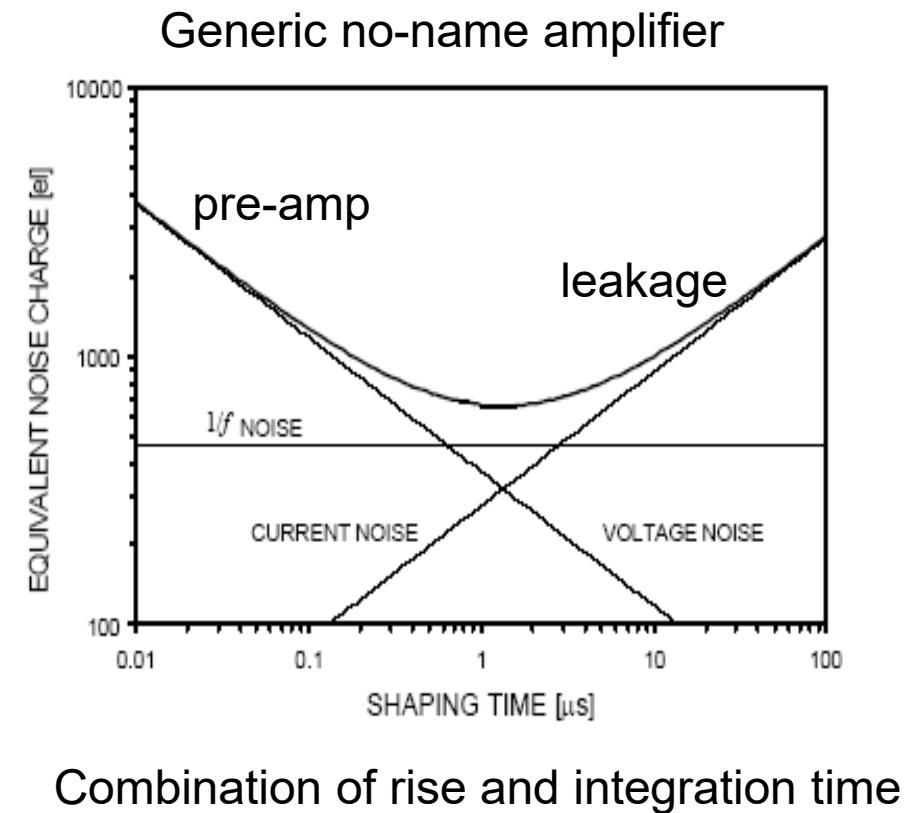
$$\sigma_N \propto \sqrt{I_{LEAK} T_M}$$

$$\sigma_N \propto a + bC_D$$

$$\sigma_N \propto \frac{1}{R_{BIAS}}$$

Signal Processing Optimizations

- Signal increases with volume
- Leakage current
 - Decreases with lower temp and volume
 - Increases with radiation and integration time
- Noise
 - Decreases with capacitance, leakage, power
 - Increases with faster risetime



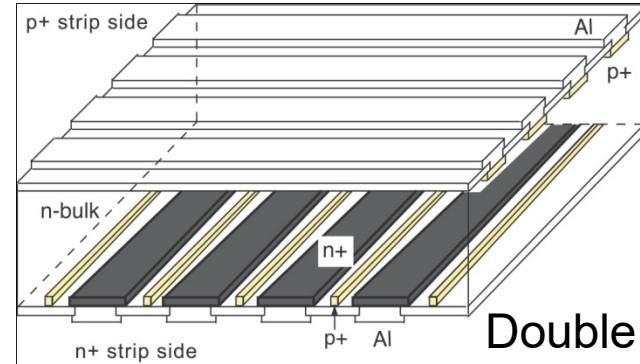
1st Order Correlations Between Sensor and Readout Electronics Characteristics

| Dep\Indep | Volume | Radiation | Temp | Power | Leakage | Capacitance | Integrat. time | Risetime* |
|---------------|--------|-----------|------|-------|---------|-------------|----------------|-----------|
| Signal | ↑ | ↓ | | | | | | ↑ |
| Leakage | ↑ | ↑ | ↑ | | | | | |
| Input noise | | ↑ | | ↓ | | ↑ | | ↑ |
| Shot noise | ↑ | ↑ | ↑ | | ↑ | | ↑ | |
| Risetime* | | | | ↑ | | ↑ | | |
| Power | | ↑ | | | ↑ | | | ↑ |
| Required bias | ↑ | ↑ | ↑ | | | | | |

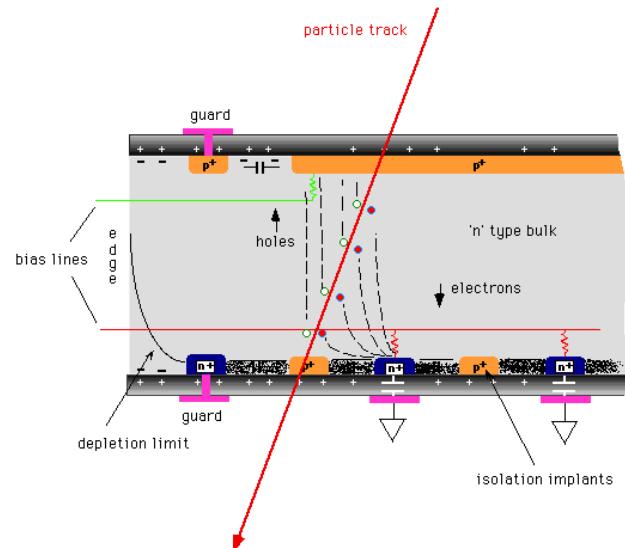
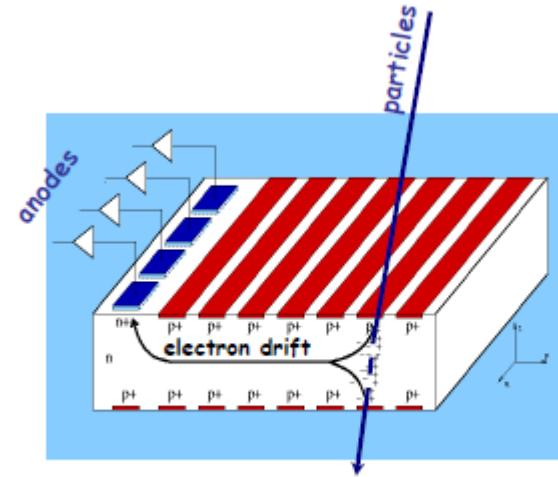
* Up means faster

Consider this as representative. The point is that a signal processing optimization should always be performed

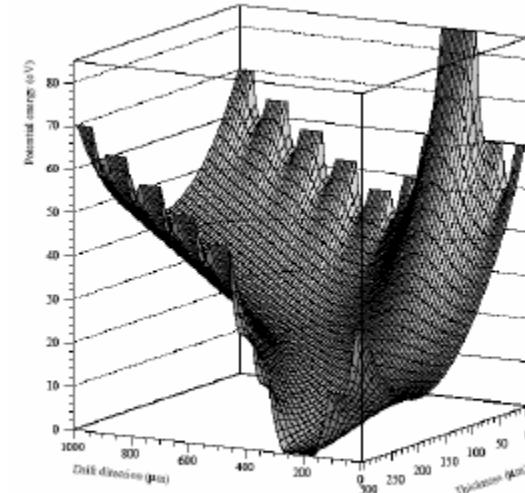
Variations on the Strip Detector



Double sided detector

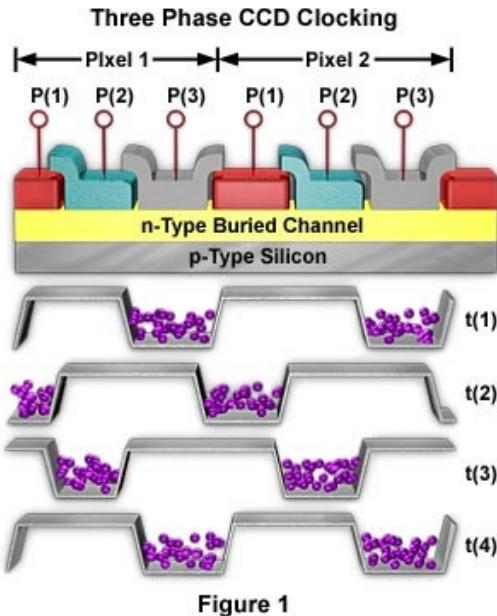


p+ in n
n+ in p
n+ in n

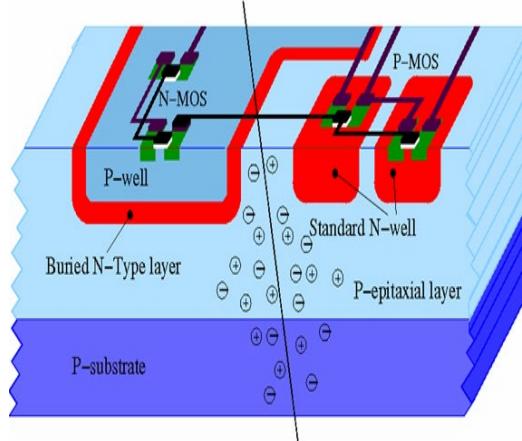


Silicon drift detector

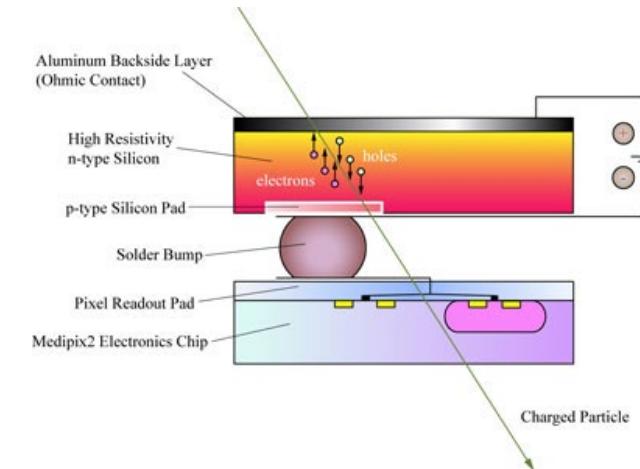
Pixel Detectors



CCD
Charge Coupled Device
Relatively slow
Low noise, Low mass

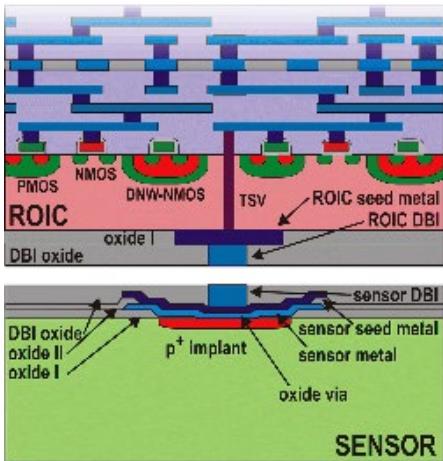


Monolithic Active Pixel
electronics and charge
formation/collection in a
thin epitaxial layer, diffusion
Moderate speed
Low noise, Low mass



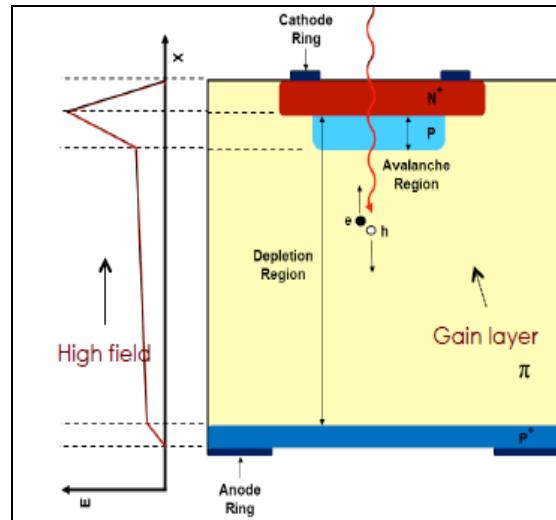
Hybrid pixel
FE IC and sensor joined
by a bump bond
Fast, Radiation Hard
Most widely used now

Extended Structures



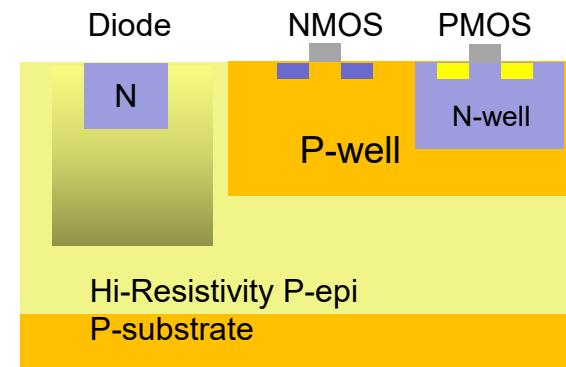
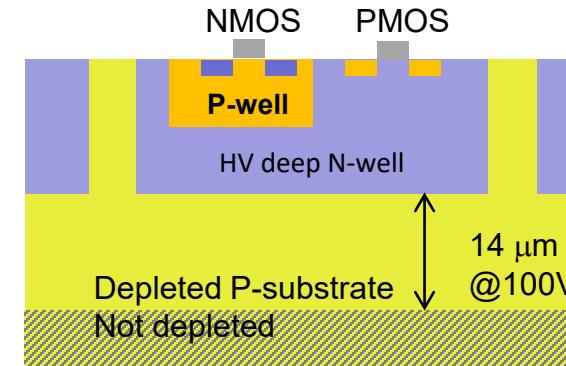
Vertical Integration
Sensor die and
electronics die are
directly bonded
Advanced packaging
Process

R.Lipton FNAL



Ultra Fast Silicon Detector
Uses n-in-p sensor, add
p+ implant below n+ to
small charge gain, increase
signal so that rising current
edge can be used for timing
with resolutions of ~20 ps

H.Sadrozinski UCSC



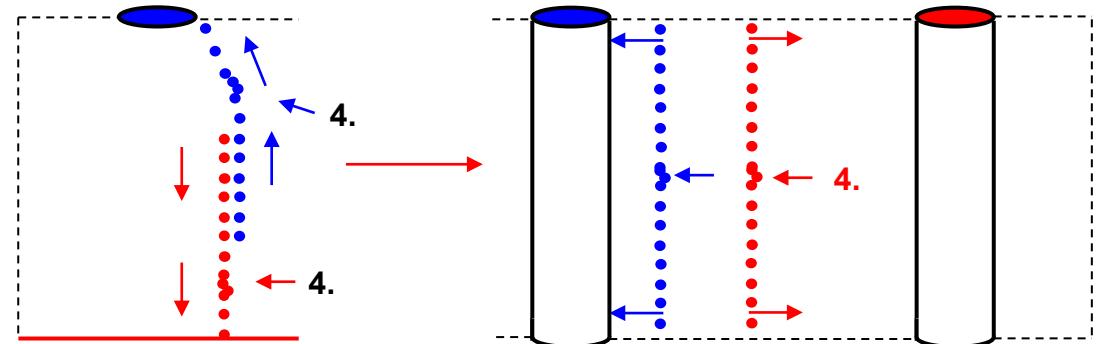
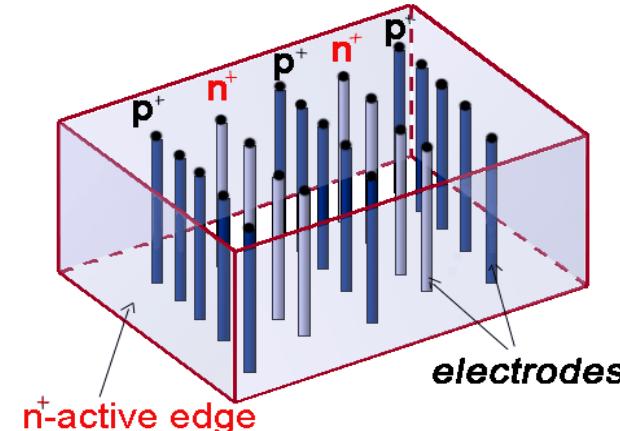
HV CMOS

HR CMOS

HV/HR CMOS – MAPS
concept made compatible
with LHC like operating
conditions using drift from
depleted zones, cheap?

3D Sensors (S.Parker)

- Implants are vertical
 - Larger capacitance/pixel
 - Requires special processing including MEMS technology
- Collection distance is reduced
 - Faster signal
 - More rad-hard for CCE
- Current applications to inner layers, beam monitors, timing



Alternate Materials

- Very active R&D effort for >20 years
 - <http://rd48.web.cern.ch/RD48/>
- Most work has been on pCVD diamond material
 - Significant improvement in charge collection
- New results on single crystal materials
 - but small samples
- Issue of industrial capacity vs silicon
- New interest in energy technologies (batteries, electric transportation) has grown industrial focus on the large bandgap materials

| Property | Diamond | 4H-SiC | Si |
|---|-------------|-----------------|----------------------|
| Band Gap [eV] | 5.5 | 3.3 | 1.12 |
| Breakdown field [V/cm] | 10^7 | 4×10^6 | 3×10^5 |
| Resistivity [$\Omega\text{-cm}$] | $> 10^{11}$ | 10^{11} | 2.3×10^5 |
| Intrinsic Carrier Density [cm^{-3}] | $< 10^3$ | | 1.5×10^{10} |
| Electron Mobility [$\text{cm}^2\text{V}^{-1}\text{s}^{-1}$] | 1800 | 800 | 1350 |
| Hole Mobility [$\text{cm}^2\text{V}^{-1}\text{s}^{-1}$] | 1200 | 115 | 480 |
| Saturation Velocity [km/s] | 220 | 200 | 82 |
| Mass Density [g cm^{-3}] | 3.52 | 3.21 | 2.33 |
| Atomic Charge | 6 | 14/6 | 14 |
| Dielectric Constant | 5.7 | 9.7 | 11.9 |
| Displacement Energy [eV/atom] | 43 | 25 | 13-20 |
| Energy to create e-h pair [eV] | 13 | 8.4 | 3.6 |
| Radiation Length [cm] | 12.2 | 8.7 | 9.4 |
| Spec. Ionization Loss [MeV/cm] | 4.69 | 4.28 | 3.21 |
| Ave. Signal Created/100 μm [e] | 3600 | 5100 | 8900 |
| Ave. Signal Created/0.1% X_0 [e] | 4400 | 4400 | 8400 |

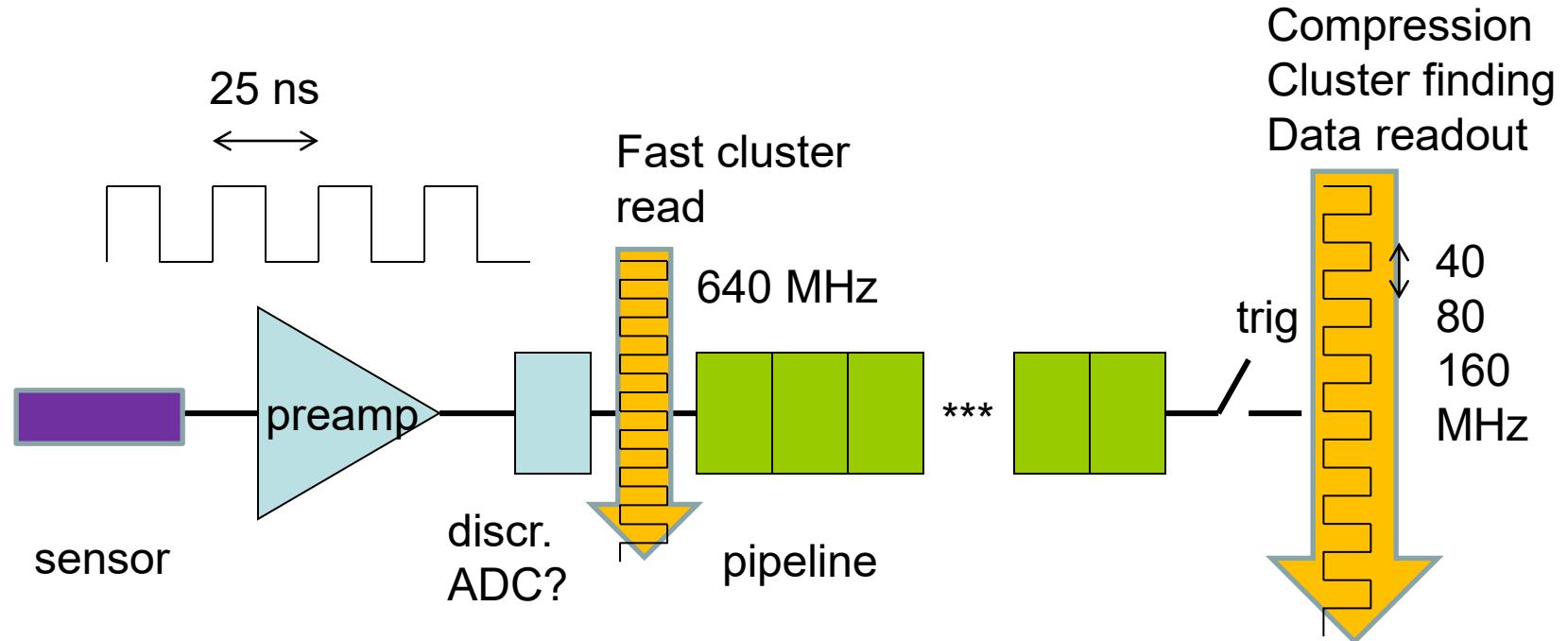
- Low dielectric constant - low capacitance
- Large bandgap - low leakage current
- Large energy to create an eh pair - small signal

| Type | D | Timing | Fab | Cost | Application/Limitations/Comments |
|-------------------------|----|------------|----------------|--------|--|
| Silicon Strip p in n | 1 | ns | standard | \$ | Basic, rad hard, outer tracking layers |
| n in p | 1 | ns | standard | \$ | More rad hard, outer tracking layers |
| n in n | 1 | ns | double side | \$\$ | Partial depletion |
| Double sided | 2 | ns | double side | \$\$ | Radiation hardness issues with biasing |
| Silicon drift | 2 | Drift time | special | \$\$\$ | Niche application to high multiplicity |
| CCD | 2 | Readout | boutique | \$\$\$ | Slow, linear collider vertex |
| Monolithic Active Pixel | 2 | ns | commercial | \$ | Large area, low cost, low mass |
| Hybrid Pixel | 2 | ns | combined | \$\$ | Hadron collider inner layers, bump bonded |
| Vertical Integration | 2 | ns | Sp. commercial | \$\$ | Advanced comm IC process, low mass |
| LGAD | 2* | ~20 ps | special | \$\$ | Fast timing by not yet high spatial resolution |
| 3D Sensor | 2 | ~100 ps | very special | \$\$ | Fast, very rad hard, inner layers |
| HVCMOS | 2 | ns | commercial | \$ | Fast, large area, in development, rad hard |
| High Resistivity CMOS | 2 | ns | commercial | \$ | Fast, large area, in development, rad hard |
| Non-silicon | | ns | boutique | \$\$ | Diamond, SiC, etc, see DOE BRN report |

Readout Architectures

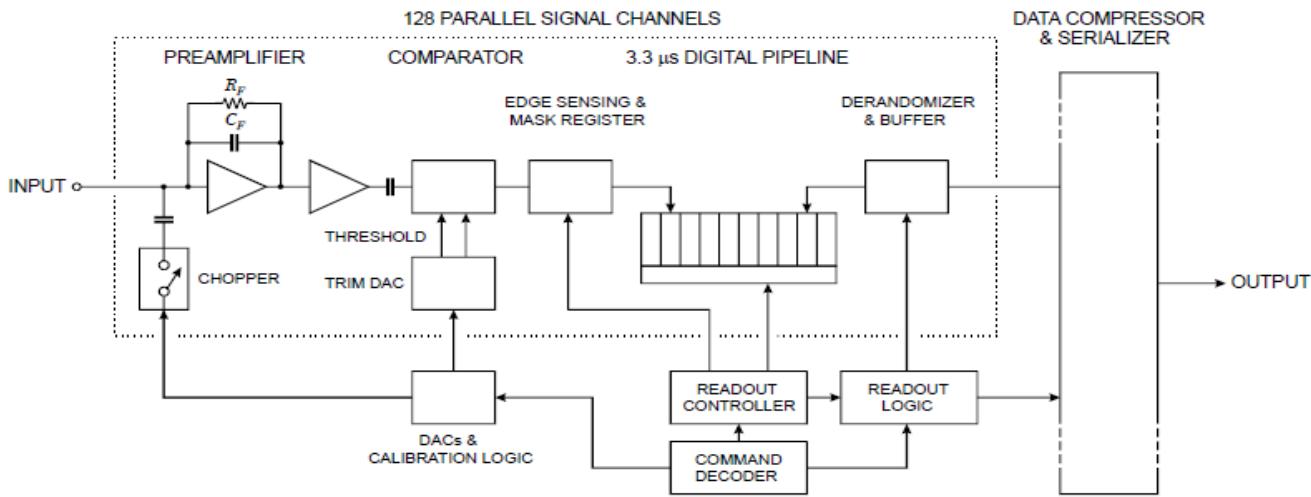
- Experimental conditions, have, to some extent driven the development of a variety of readout architectures (see also backup slides)
- Accommodate properties and limitations of available IC processes, a moving target
- Subjective aspects have entered as well
- Analog: process analog pulse heights off detector, full resolution, diagnostics, example is CMS APV25 series
- Digital: digitize on detector, full resolution, examples are CDF SVX2-4 series, ATLAS pixel TOT system
- Binary: on detector threshold, simplify readout, example is ATLAS ABC
- Fast Timing is an emerging capability (few 10's of ps)

A Basic Collider Readout Architecture



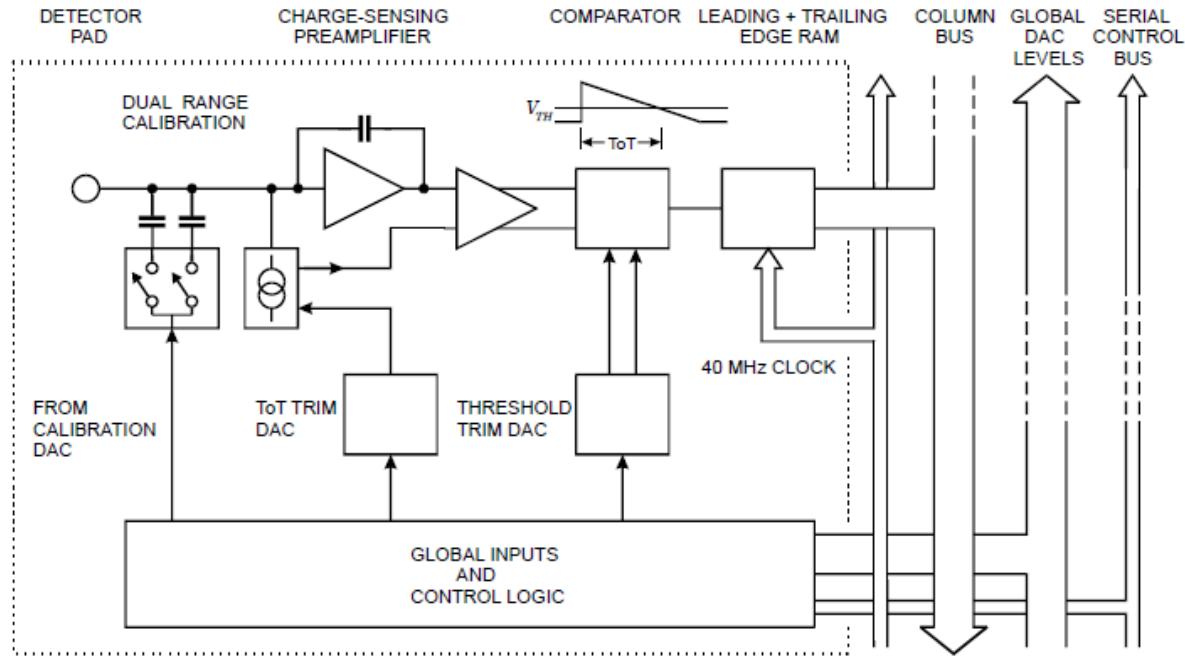
- Beam clock (BC) runs at collision rate, advances pipeline
- Pipeline length determined by required latency
- Trigger determines whether last cell will be read
- Fast cluster read enables access to prompt data

Binary



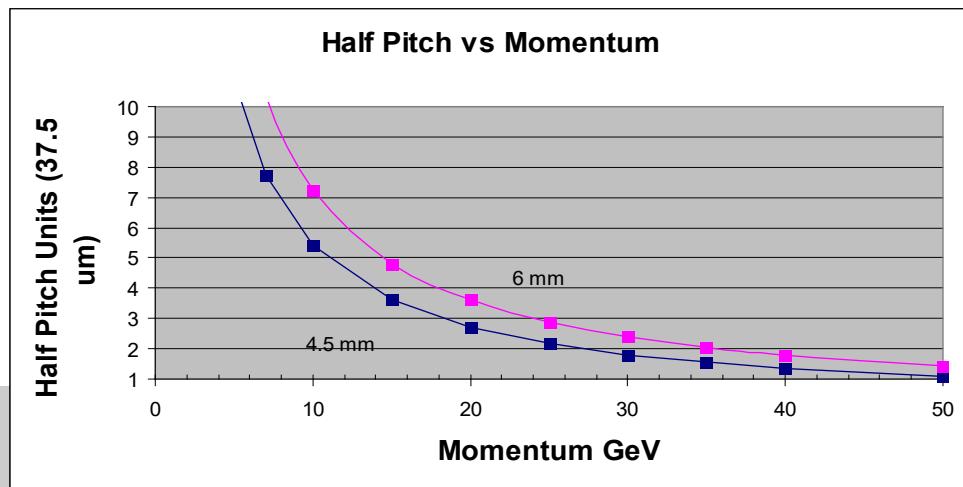
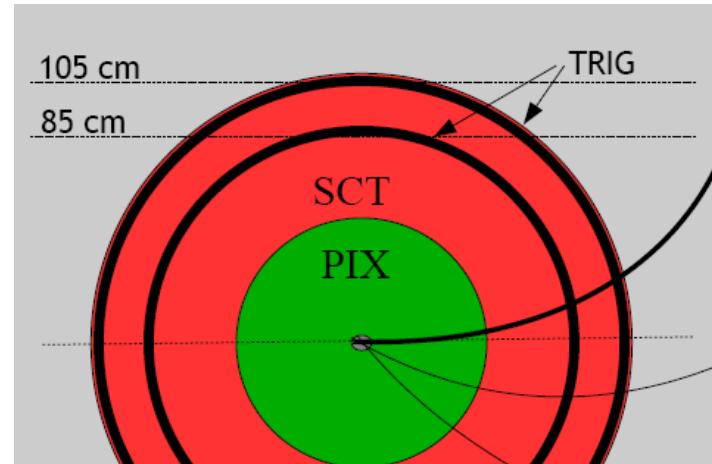
- Example is the ABC chip developed for ATLAS, BiCMOS
- AC coupled pre-amplifier shaper for 25 ns collisions
- Comparator + trim DAC per channel
- 1 bit pipeline clocked at 40 MHz, L1 buffer
- Data compression
- Control and configuration protocol
- DSM CMOS version exists as well, 130 nm underway

ATLAS Pixel

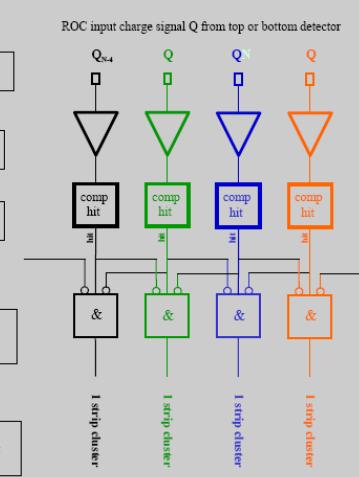
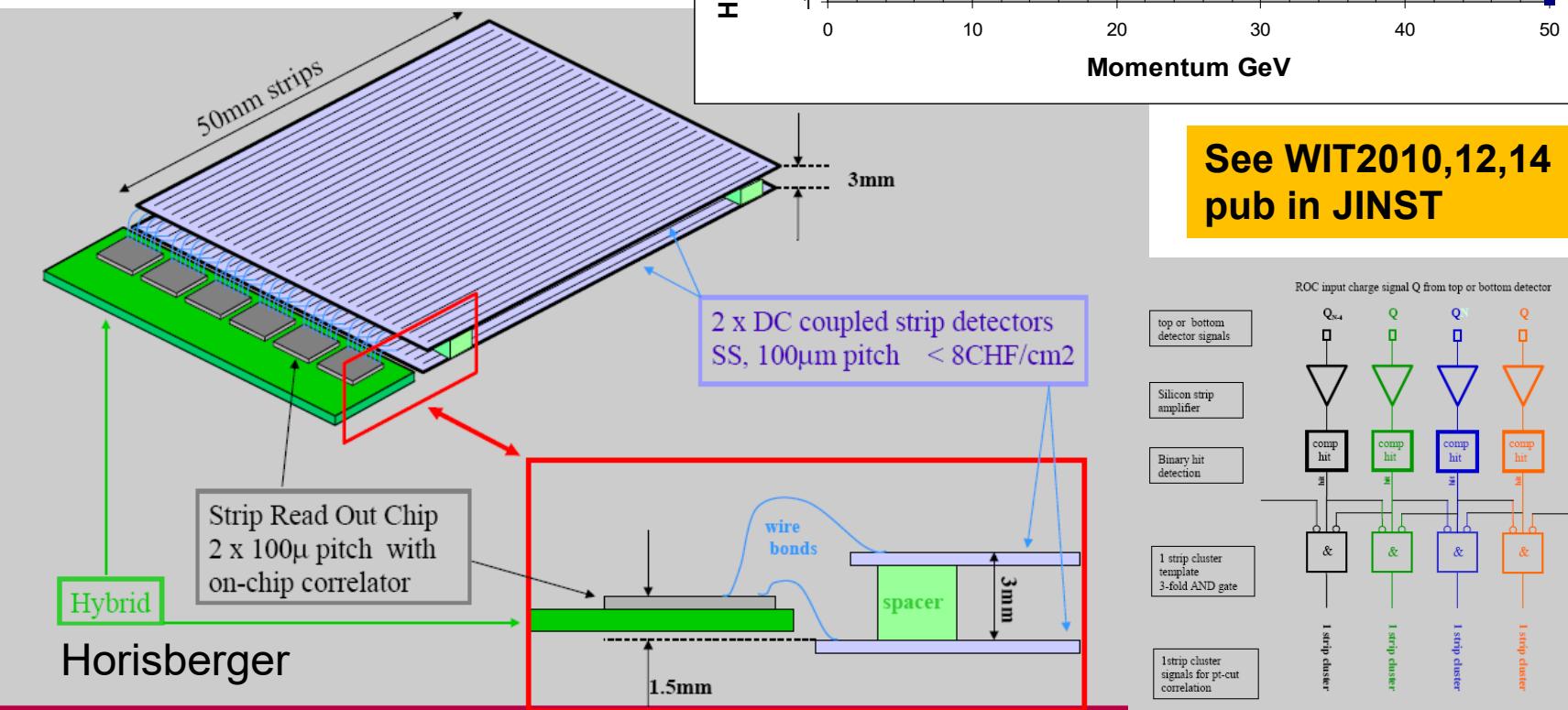


- Example is ATLAS FEI3 pixel cell
- DC couple preamp with leakage current compensation
- Pulse height is measured by “Time over Threshold”
- Additional architecture organizes the data in columns for readout

Real time momentum trigger



See WIT2010,12,14
pub in JINST



This concept has been developed into a full scale tracker architecture by the CMS collaboration for the HL-LHC. See their TDR

<https://cds.cern.ch/record/2272264/files/CMS-TDR-014.pdf>

The ATLAS collaboration has studied, but will not use, a more limited version of this

Radiation Environment

- Primary source are collision products
 - High energy charged particles + neutrals
- Additional component due to “accidents”
- Primary field falls with radius as $\sim r^{-(1-2)}$
- Each interaction yields ~ 7 particles/angular unit: sum crossings and interactions
- Fluence and dose have increased $>10^4$ since mid-80's
 - Near future expect unprecedented dose due to increased luminosity and energy
 - 100 Mrad absorbed energy (units)
 - 10^{15} - 10^{16} particles/cm²
 - Compare to: space (~ 1 MRad), nuclear weapons ($\sim 10^{13}$)

Radiation Effects: Ionizing

- Incident particle interacts with atomic electrons
- Measure in energy absorbed (rads (Si))
- e/h pairs created, recombine or trap
- Transient effect
 - Actual signal formation
 - Single event upset condition in circuits
- Electronics: charge trapping at Si/SiO₂ interface (largely controlled by rad-hard circuit designs or thinner oxides)
- Detectors: surface effects, oxides

Electronics

- For presently operating systems commercial rad-hard CMOS has provided sufficient resistance.
- New chips use commercial deep submicron CMOS
 - Thin oxides provide automatic hardness, verified in test
 - Augment design rules with enclosed gate geometries to block radiation induced leakage paths
- Certain bipolar technologies are also rad-hard (analog)

Radiation Effects: Non-ionizing

- Incident particle interacts with nucleus
 - Displacement damage – permanent or slow to reverse
 - 2nd order effects as defects interact over time
- Depends upon particle type and energy
- Measure in particles/cm²

Radiation Effects: Detectors

- Damage to the periodic lattice creates mid-gap states
- Increased leakage
 - Shot noise
 - Power
 - Heat

$$I_L = \frac{en_i(\sigma v_{thermal} N_T)WA}{2}$$

n_i = intrinsic carrier concentration

σ = recombination cross section

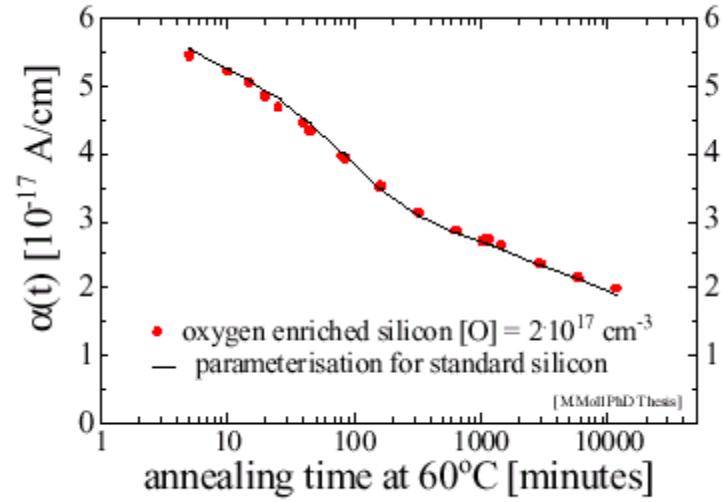
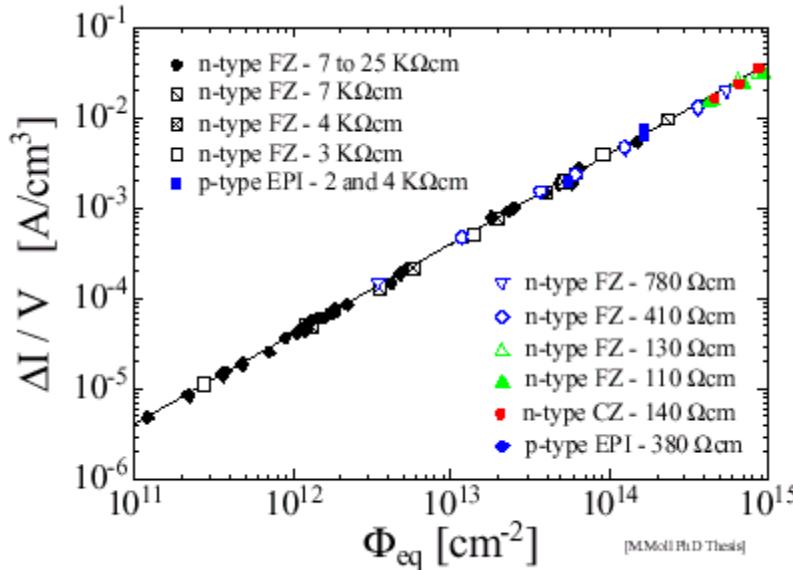
$v_{thermal}$ = carrier thermal velocity

N_T = trap density

A = junction area

$$I_L(T) \propto T^2 e^{-E_a/2kT}$$

Reverse current with fluence and time



$$\Delta I = \alpha V \Phi$$

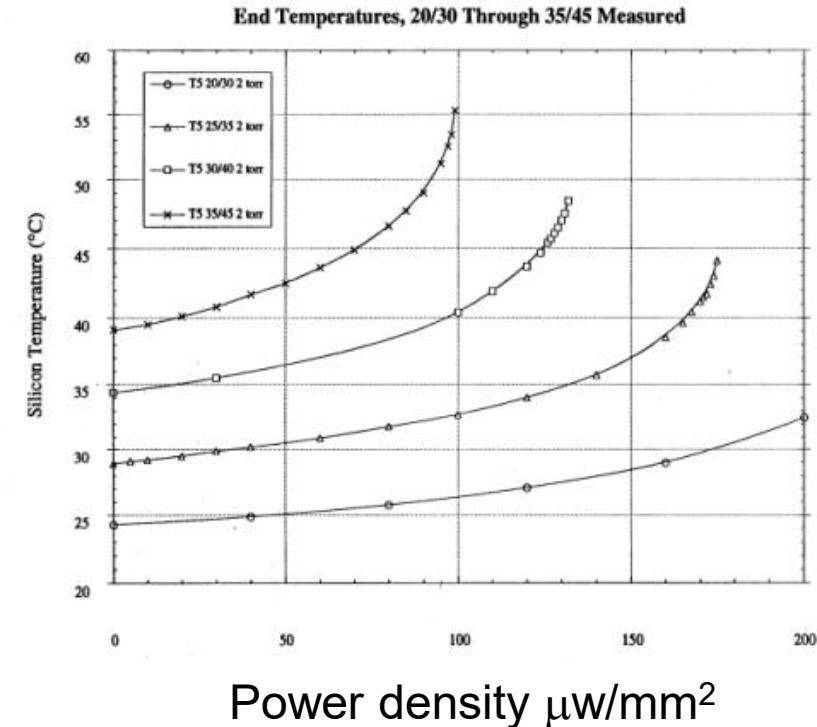
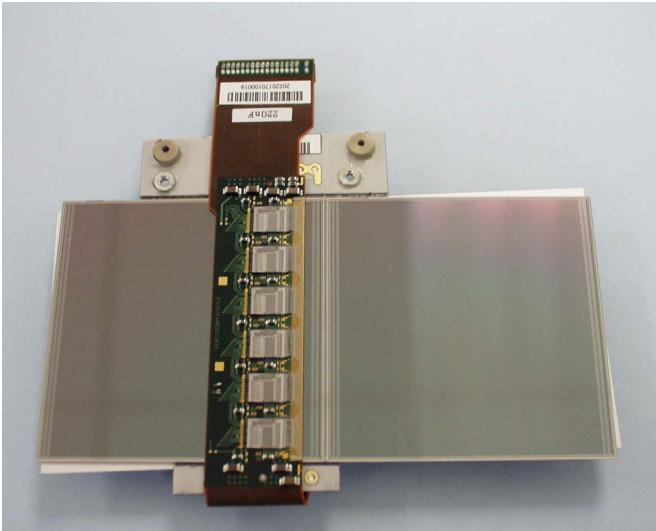
Damage constant $\alpha \approx 2 - 3 \times 10^{-17} \frac{\text{Amp}}{\text{cm}}$

Volume $V \approx 2 \times 10^{-3} \text{ cm}^3$

Incident Flux $\Phi \approx 10^{14} - 10^{15} \text{ particles/cm}^2 @ \text{LHC}$

$\Rightarrow \Delta I \approx 2 \mu\text{A} @ 0^\circ \text{C}$ (current doubles every 7 degrees)

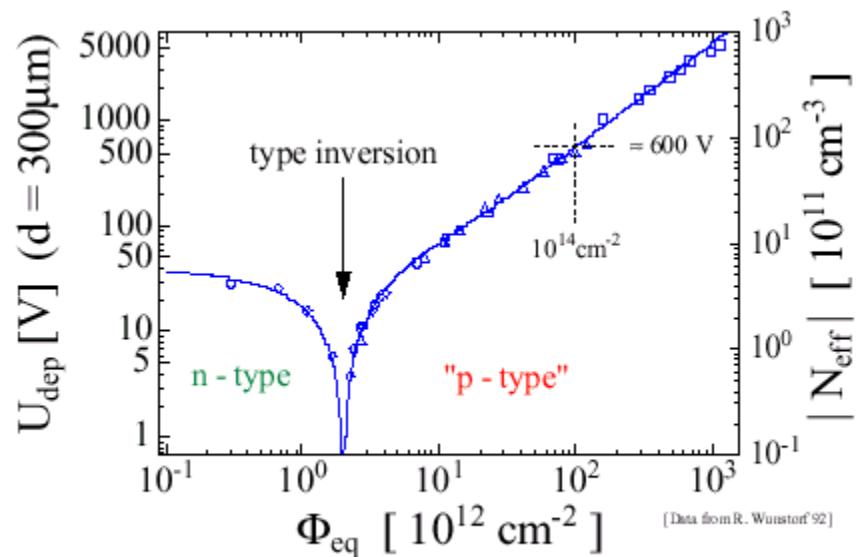
Thermal Run-away



Increased current → Power dissipation → Increased temperature → Increased current

Change in effective acceptor concentration

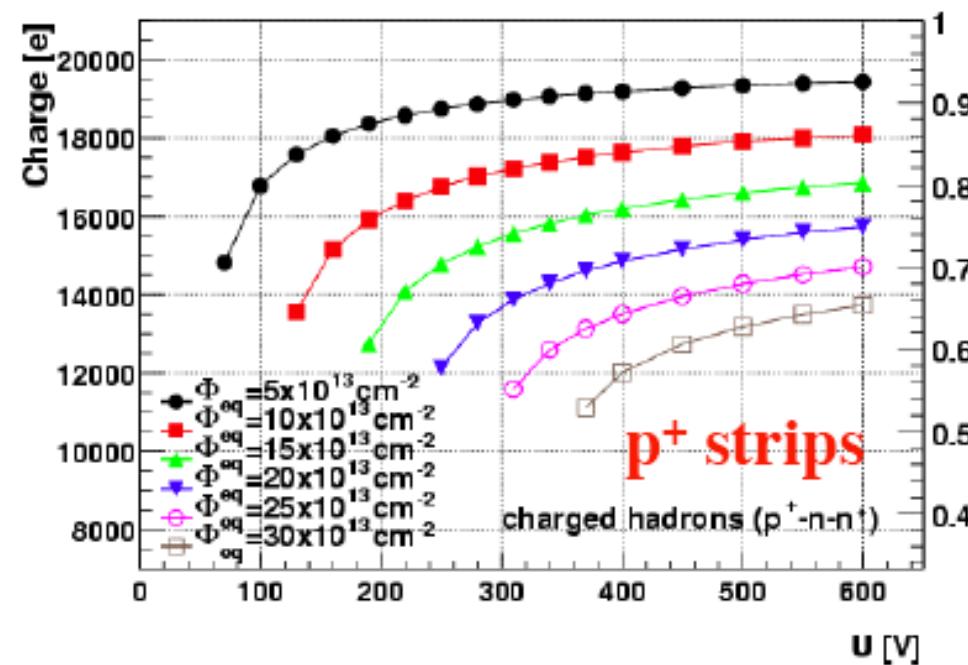
Effective space charge ($N_{\text{eff}} \Rightarrow V_{\text{fd}}$) with fluence and time



- Creation of acceptor states or removal of donor states
 - Effective change of resistivity
 - Type inversion: $n \rightarrow p$
 - Depletion voltage changes in proportion to $|N_{\text{eff}}|$ 'higher voltage operation required'
 - Dramatic time and temperature dependence

Charge Collection

- Reduction in charge collection efficiency (CCE)
 - $N_{e,h}(t) = N_0 \exp(-t/\tau_{trap})$
 - Ratio of collection and charge trapping time constants evolves with fluence



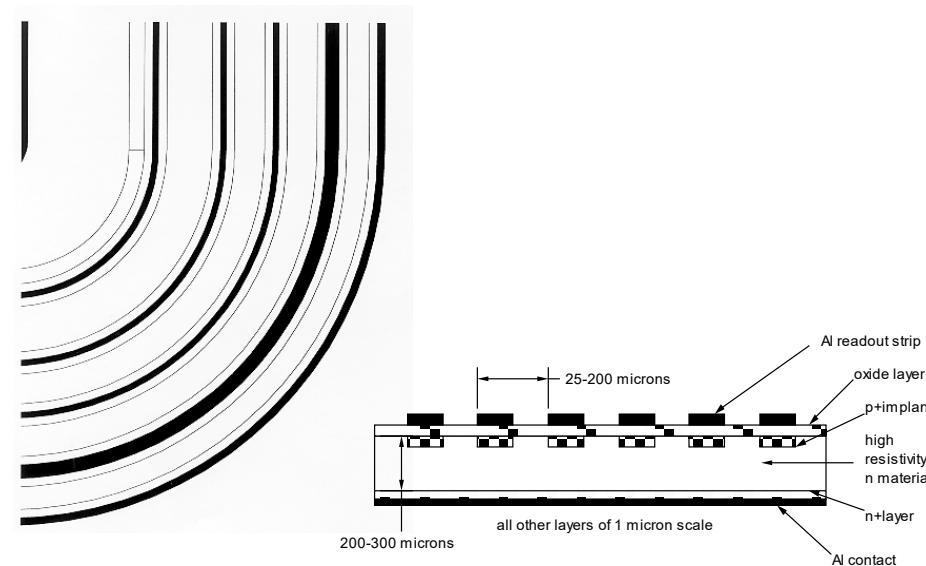
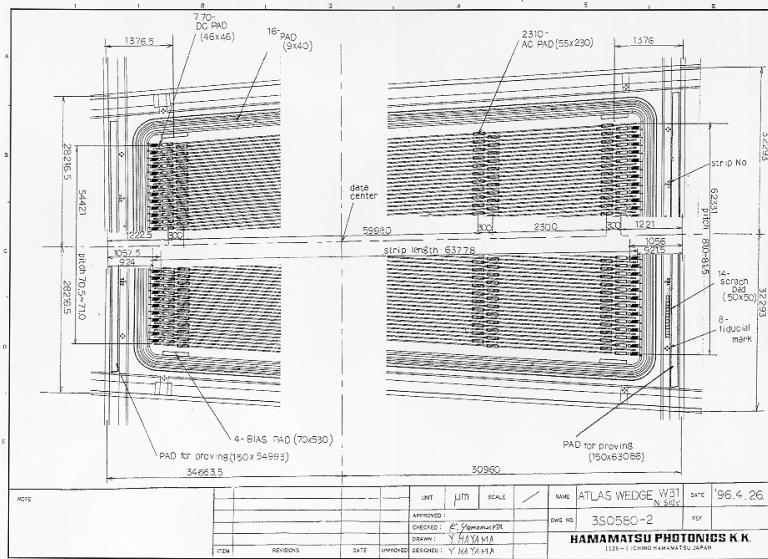
Gregor
Kramberger,
Ljubljana

Methods to Control Radiation Effects

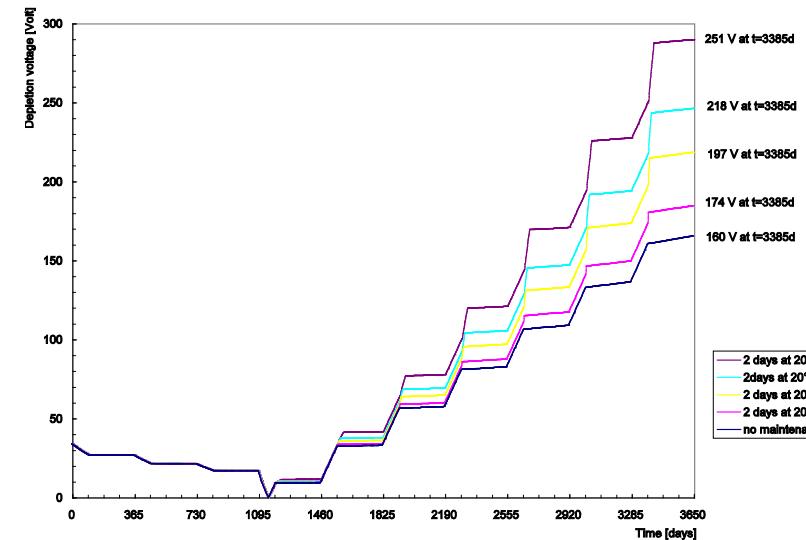
- Most represent some tradeoff
- Size matters
 - Smaller volumes generate less leakage current (but require more channels, power, heat...)
 - Thinner detectors deplete at lower voltage (usually means less signal)
- Temperature
 - Low temperature (-10 C) operation can “stabilize” reverse annealing for $< 10^{14}$
 - Reduce leakage current effects
- Integration time
 - Current noise is reduced for short shaping times at the expense of increased pre-amp noise, power.

- Biasing schemes
 - Reduce value of parallel biasing resistor to reduce voltage drop due to $I_{\text{Leak}}R_{\text{bias}}$ at the expense of increased thermal noise
- HV operation
 - Configure detectors to withstand higher voltage operation
 - Tolerate increased depletion voltage
 - Operate in partial depletion (collection issues)
- Low noise electronics
 - Tolerate reduced signal due to CCE and partial depletion
- Configuration
 - p in n substrate – simple, type inverts
 - n in n substrate – 2 sided process, can be operated in partial depletion after inversion
 - n in p – non-traditional process, does not invert

Strip detectors with multiple guard ringstructures to tolerate HV=500 V operation



Simulation of 10 year operating scenarios
for silicon tracking at the LHC
 $L = 10^{33}-10^{34}$

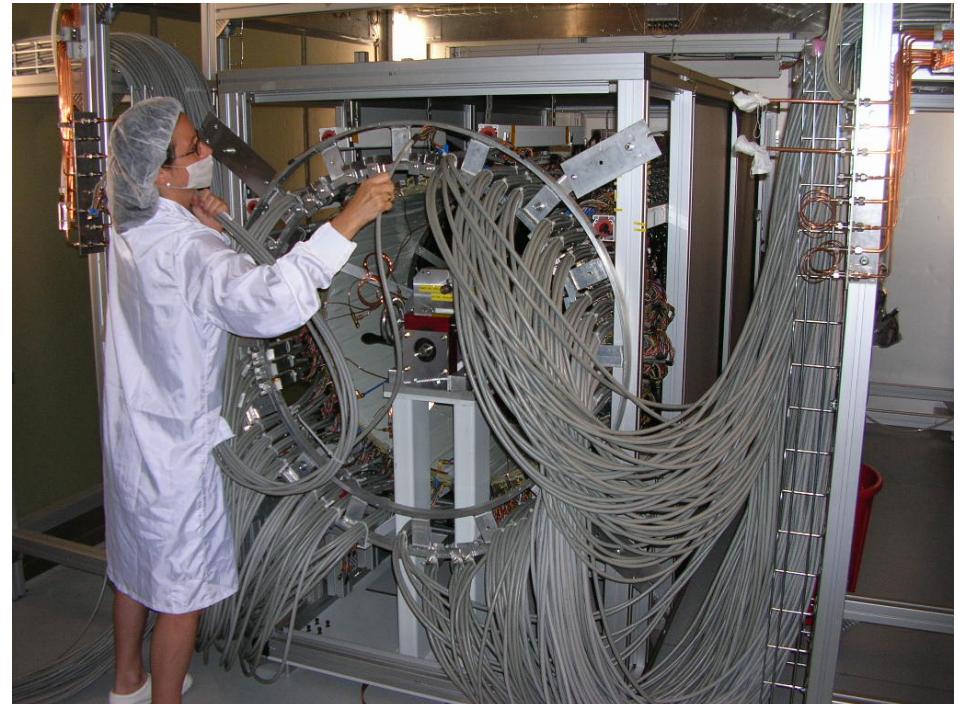


Issues for Large Systems

- Grounding and Shielding
- Powering
- Bias
- Control and Data Transmission
 - Cables
 - AC Coupling
- Monitoring and fast/slow control
 - Interlocks, safety

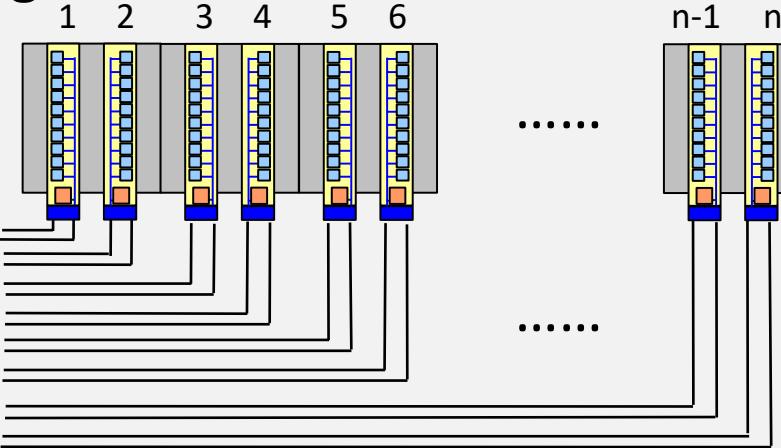
Power Distribution

- Conventional wisdom stated that each “module” of tracker should be serviced independently
 - isolate single point failures
 - Avoid electrical interference and ensure low noise
- For large trackers this has led to a cabling (mass and access) limitation
- Future trackers are larger by x5 or more
- An active R&D effort in alternative powering approaches resulted in a major revision of this orthodoxy
- Now alternative powering schemes are in wide use with significant material and cabling reductions as a result
- Also HV multiplexing with rad hard switches
- Sophisticated monitoring and control ASICs – ATLAS AMAC, PSPP



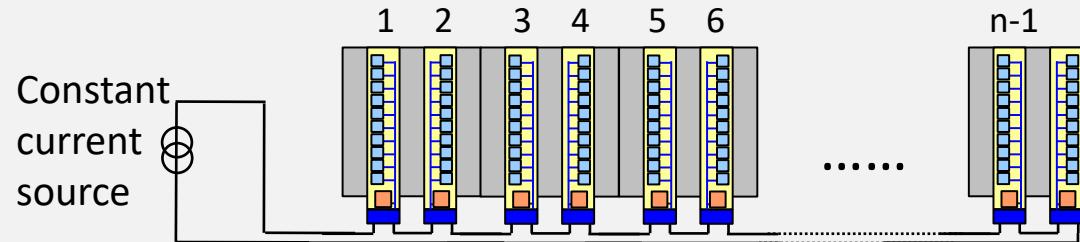
- Independent powering

Hybrid current = I
 Number of hybrids = n
Total current = nl
Power lines = n



- Serial powering

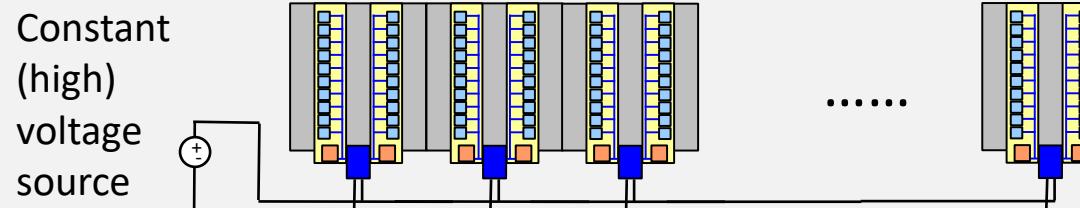
Hybrid current = I
 Number of hybrids = n
Total current = I
Power lines = 1



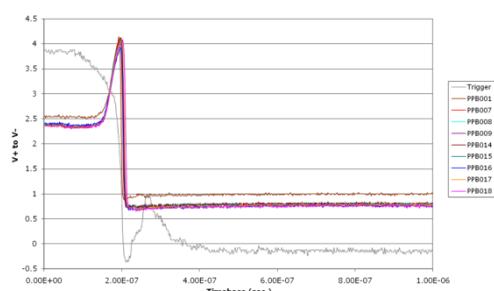
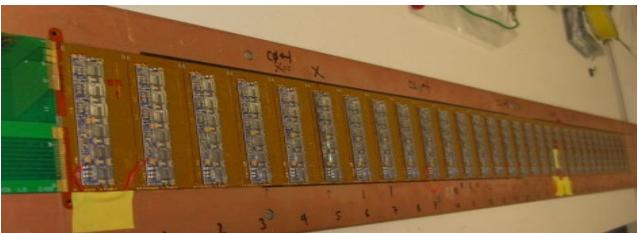
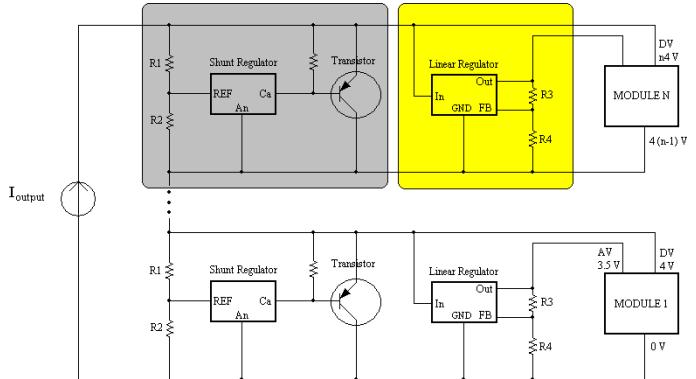
Requires AC coupling
 $V_{tot} = N \cdot V_{mod}$
 Shunt regulation
 Equal I per module

- DC-DC powering

Hybrid current = I
 Number of hybrids = n
Total current = $n(I/R)$
Power lines = 1

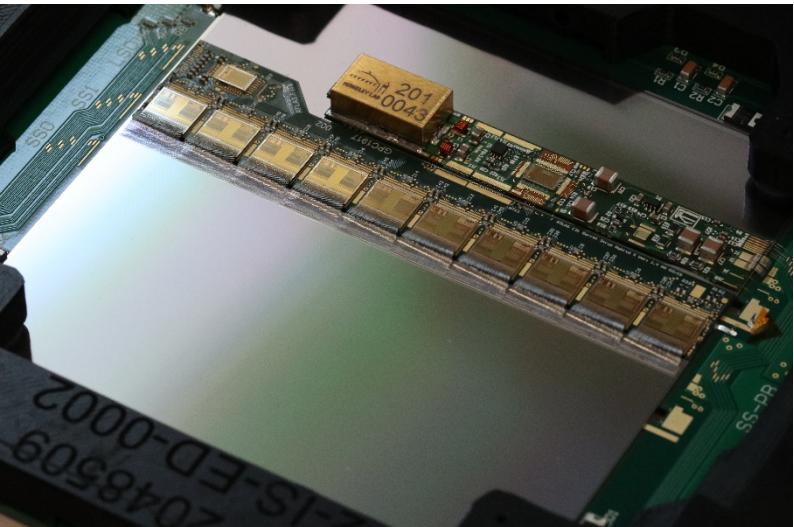


Requires clocked
 stepdown converter
 per module
 Inductor
 $V_{in} = V_{mod} \cdot R$

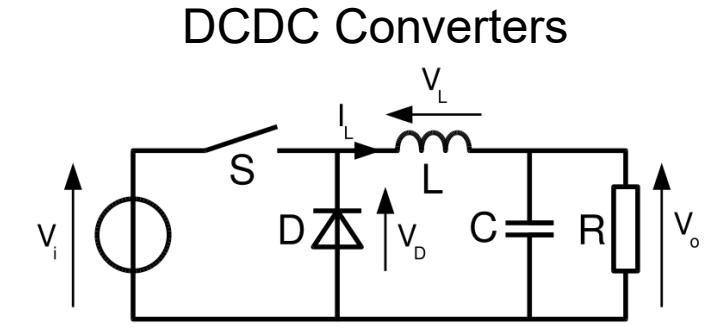


30 drop
Serial powered
Stave

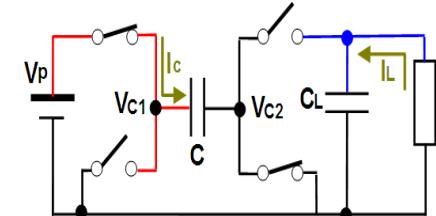
Implementations



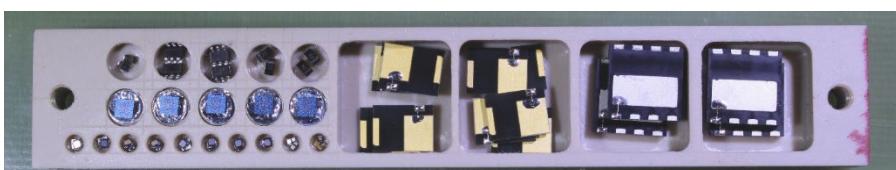
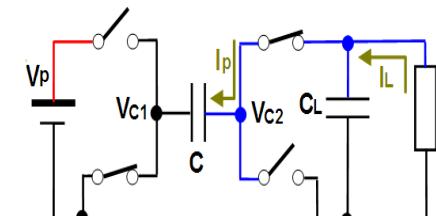
ATLAS HL-LHC Module with DCDC,
HV-mux, monitoring and control ASIC



1. Charge



2. Pumping



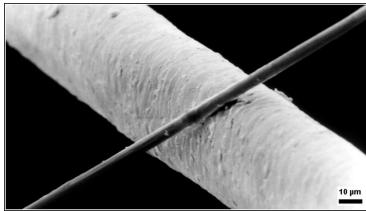
HV multiplexers

Mechanical and Thermal Aspects

- Precision tracker requires support structure which is stable, can be efficiently cooled, and is low in mass (X_0).
- There are two key materials/classes which come into consideration here
 - Beryllium: structural grade metal, low Z , metallic CTE, expensive, and hazardous to machine, probably impractical for very large structures
 - Carbon composites: tremendously flexible class of materials, reasonable X_0 , good thermal properties, variable CTE
- Many advanced implementations now favor integrated carbon composite structures ie: staves, I-beams, tubes...
- Flow of liquid coolants – initially fluorocarbons, now CO_2 , air cooling for very low mass systems - MAPs

Mechanical Grade Materials

| material | Density (gr/cc) | Xo (cm) | Young's Mod (GPa) | CTE (ppm/ $^{\circ}$ K) | TC: W/m $^{\circ}$ K |
|-----------------------------|--------------------|---------|------------------------|----------------------------|-------------------------|
| Silicon | 2.33 | 9.37 | 130-185 | 2.8-7.3 | 149 |
| Beryllium | 1.85 | 35.27 | 255 | 12.4 | 201 |
| Aluminum | 2.70 | 8.9 | 69 | 23.9 | 237 |
| Stainless Steel | 7.9 | 1.76 | 193 | 11.7 | 95 |
| Titanium | 4.54 | 3.56 | 116 | 8.5 | |
| Carbon | 2.21 | 19.32 | | 0.6-4.3 | |
| Carbon fiber frac 70-40% | ~1.7-2 | 23-27 | 180-125 along fibre | Varies with layup | 10's – several 100's |
| CF: K13D2U | 2.2 | | 135 Msi | | 800 |
| POCO Graphite foam | 0.5 | ~100 | low | 0.7 | 45/135 in/out |
| Boron Nitride | 2.25 | 20.8 | | <1 | 250-300 |



Carbon Composites

- Carbon fiber “sheets” consist of filaments or woven layers impregnated with epoxy.
- By arranging layers in various “lay-ups” and configurations, a great variety of components can be created with enhanced mechanical and thermal properties.
- Importance of symmetry and stress balance
- Other advanced carbon based materials can be combined in structure as well
- Multiple shapes and materials can be simultaneously co-cured

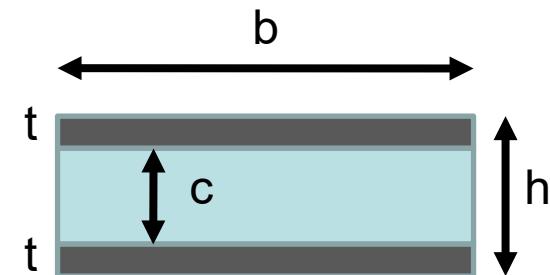
Basic Issues

- Sag in a uniform composite beam

$$\delta(\text{bending}) = \frac{wL^4}{384EI}$$

$$I = 2\frac{bt^3}{12} + 2bt\left(\frac{c+t}{2}\right)^2 = \frac{bt^3}{6} + \frac{btc^2 + 2bct^2 + bt^3}{2} \approx btc\left(\frac{c}{2} + t\right)$$

$$\delta = \frac{wL^4}{384Ebtc\left(\frac{c}{2} + t\right)}$$



- Stress in the “bi-material” strip

$$\kappa = \frac{6E_1 E_2 (h_1 + h_2) h_1 h_2 \epsilon}{E_1^2 h_1^4 + 4E_1 E_2 h_1^3 h_2 + 6E_1 E_2 h_1^2 h_2^2 + 4E_1 E_2 h_2^3 h_1 + E_2^2 h_2^4}$$

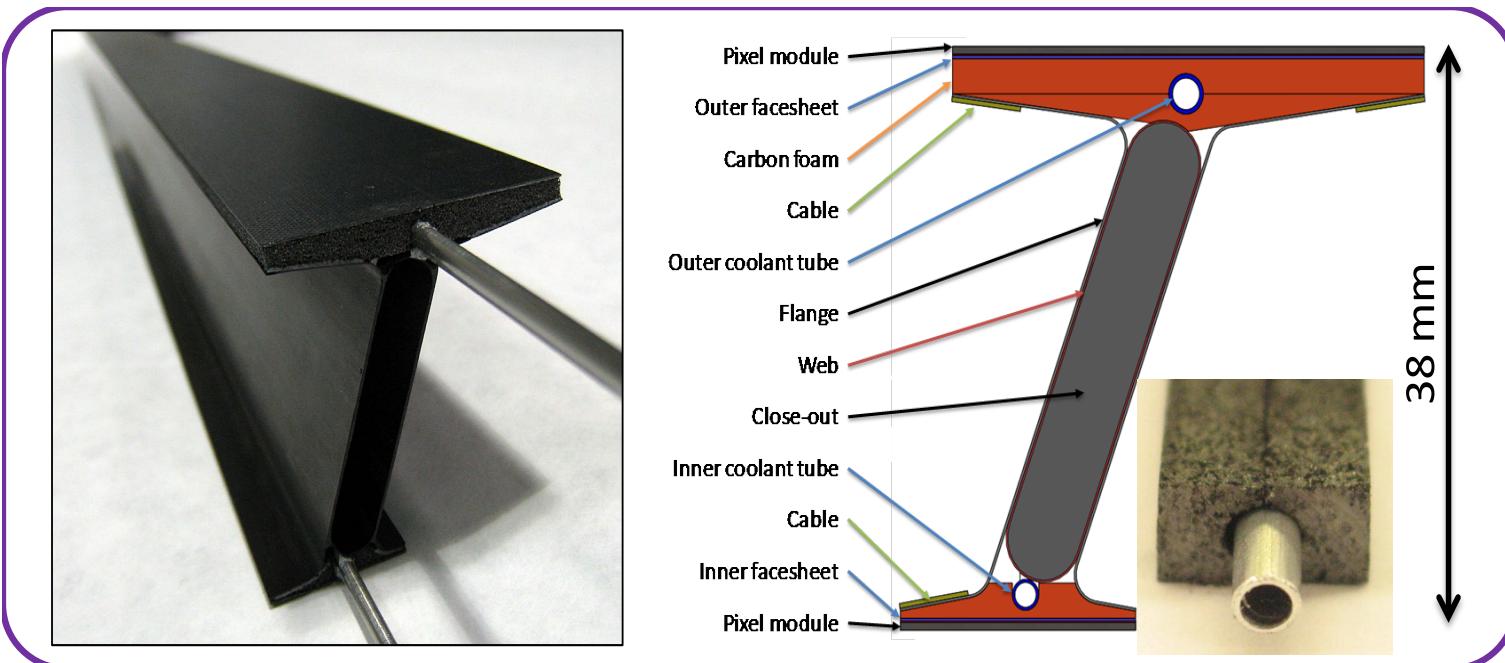
$$\epsilon = (\alpha_1 - \alpha_2) \Delta T$$



Example: Carbon Fiber Beam

- Structure consists of 2 CF facings laminated on either side of a “soft” core w. embedded metal cooling lines: sandwich beam
- Symmetry keeps the structure flat
- Facing contains multiple sheets in order to tune mechanical and/or thermal properties
- Core may have enhanced thermal properties to improve cooling efficiency
- Subsequent (or co-)lamination of electrical circuitry and sensors
- Issue of stress between carbon and other unlike materials as composite is cooled from lamination temperature to RT and to operating temperature

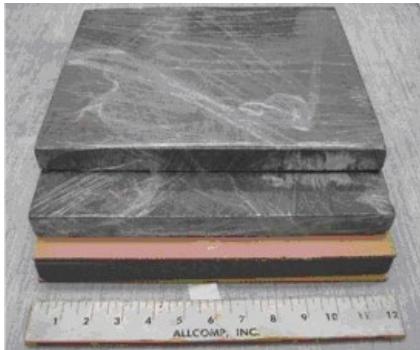
ATLAS I-beam Structures



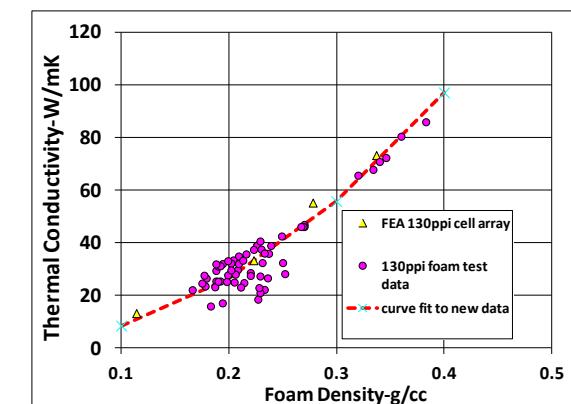
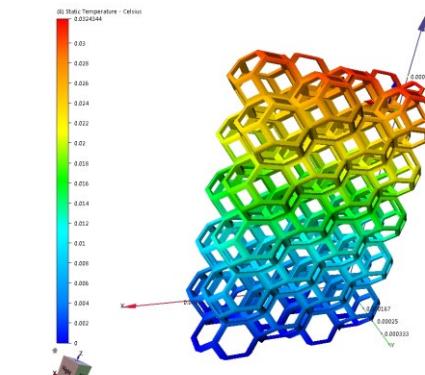
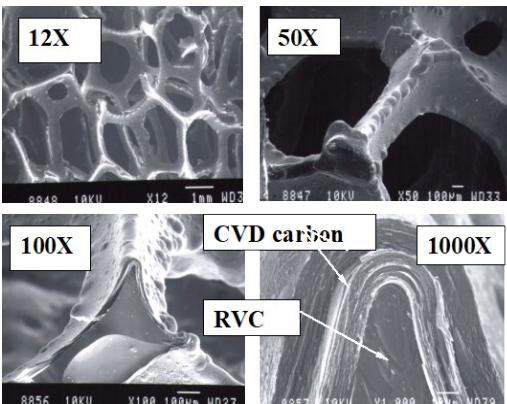
- Typically a cured (or co-cured) structure composed of fibers, a polymer matrix, additional elements such as foam, honeycomb, embedded cooling channels, electrical interconnects
- Low mass CF structure/specialized materials
- Embedded thermal aspect, thin walled pipes, engineered interfaces
- Embedded electrical functions

Materials: Carbon Foams: Low density, hi conductivity

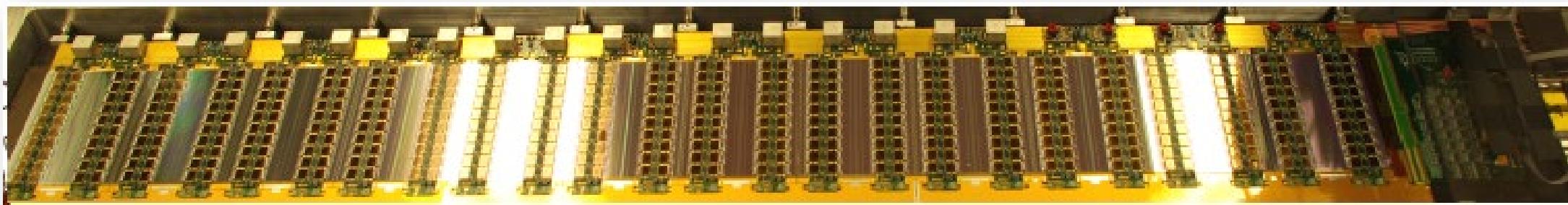
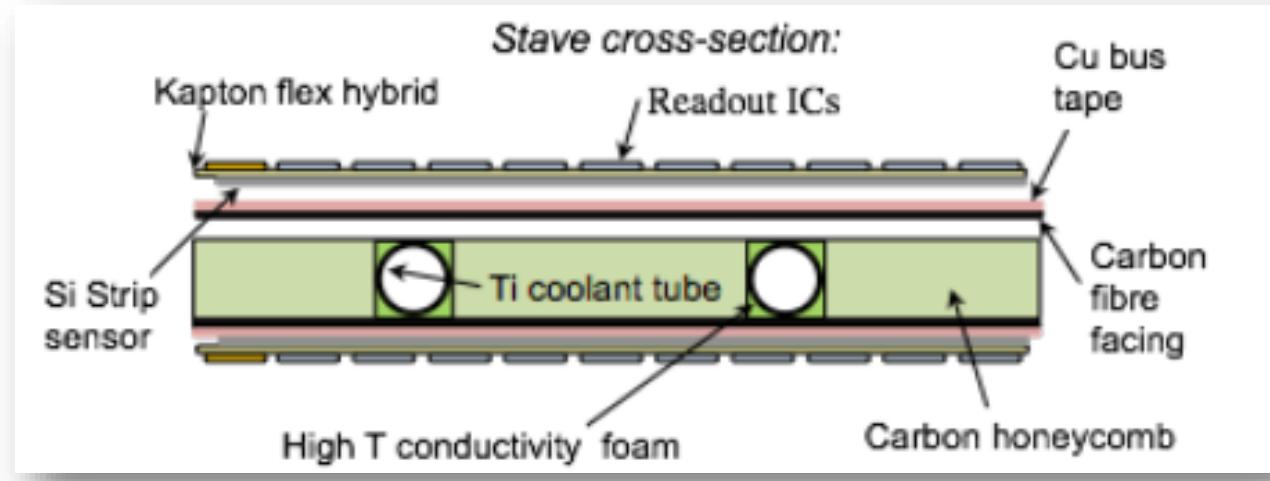
- Developed in collaboration with industry through SBIR
- Qualified for radiation tolerance and thermal/mechanical performance, in use.
- FEA modeling of thermal and mechanical properties.



| Property | Value(Unit) |
|----------------------|----------------------|
| Density | ~ 0.23 g/cc |
| Initial porosity | 130 pores/inch |
| Thermal conductivity | 30-40 W/m-K |
| CTE | <2 ppm/ $^{\circ}$ C |
| Tensile modulus | 35ksi |
| Tensile strength | 515psi |
| Compressive modulus | 50ksi |
| Compressive strength | 280psi |



ATLAS ITk Strip Tracker Stave Structure

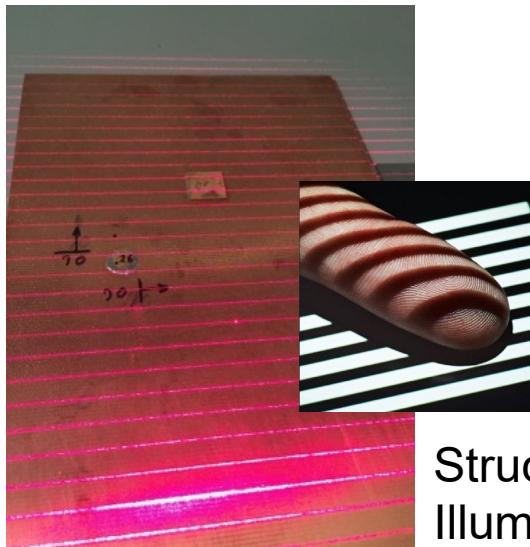


400 staves, 1.4 meter, 28 10x10cm silicon modules, DCDC power

Metrology Tools for Survey

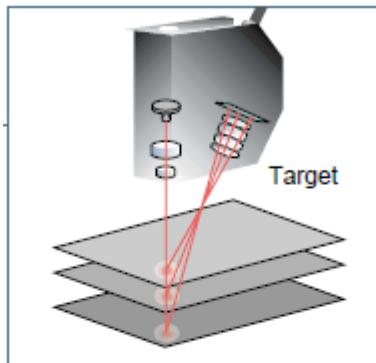
| Technology | Application | Resolution | Interface | Ease/Speed |
|----------------------------|------------------------------------|--------------------------|--------------------------|-------------------------------|
| CMM-touch | Large objects | x/y/z ~ μm 's | commercial | Teach mode |
| CMM-optical | In plane location Small heights | x/y/z ~ μm 's | commercial | same |
| ESPI | Dynamics | x/y/z ~ μm 's | commercial | R&D tool |
| FSI | In-situ alignment Stability | One axis | custom | System design |
| Laser Displacement | Flexible heights R&D tests | z ~ μm 's | User defined | User defined, 1 kHz |
| Structured Illumination | Fast large area 3D | x/y ~ mm z ~ 0.2 mm | Video or still camera | Typical frame rates |
| Confocal | Precision heights Small area | 10-100 nm | User or commercial | User defined, 100 Hz–2 kHz |

Touch/Optical Coordinate Measuring Machines Image analysis



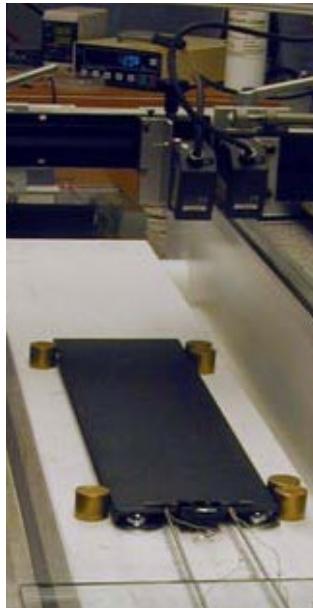
Structured Illumination

Examples

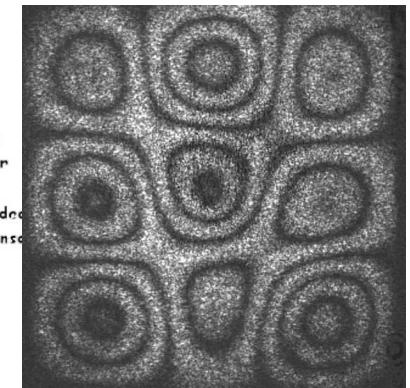
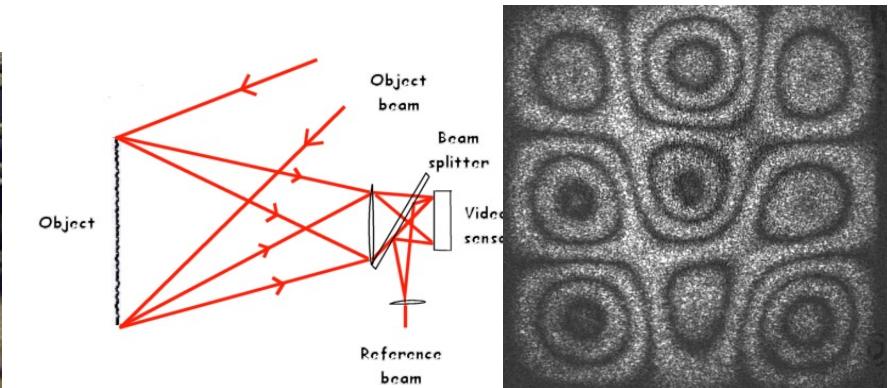


The measurement principle uses triangulation. The position of the reflected light on the Li-CCD moves as the position of the target changes. The displacement amount of the target is measured by detecting this change.

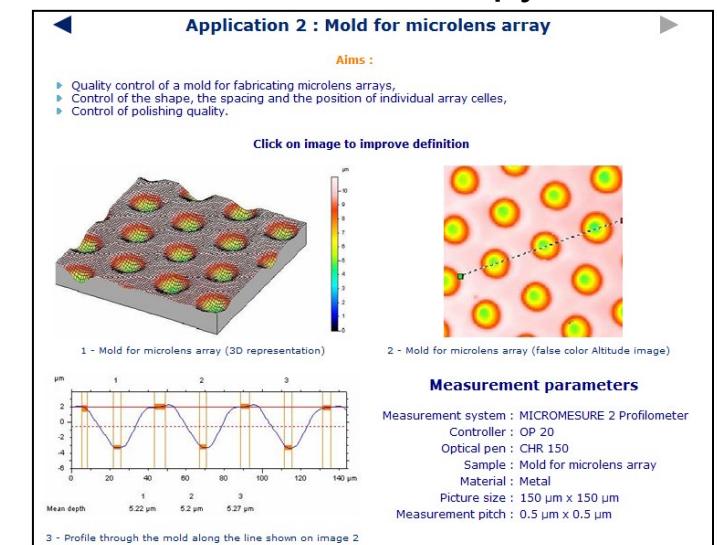
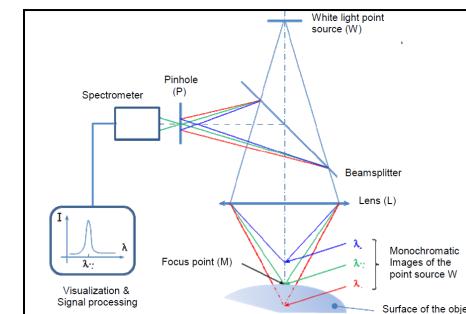
Scanning Laser Rangefinding Triangulation



Electronic Speckle Pattern Interferometry



Color Coded or Laser Confocal Microscopy



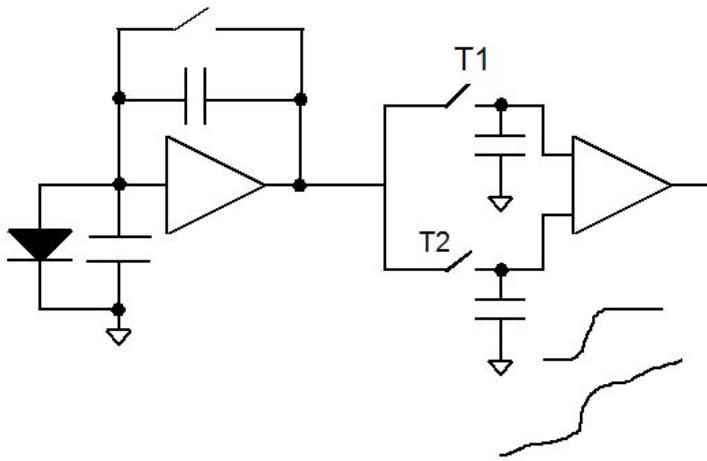
Conclusions

- Huge progress ~30 years to build silicon trackers using a broad suite of advanced technologies
- Much significant science done, and to be done, with these devices
- R&D underway for the next generation

Back Up Slides

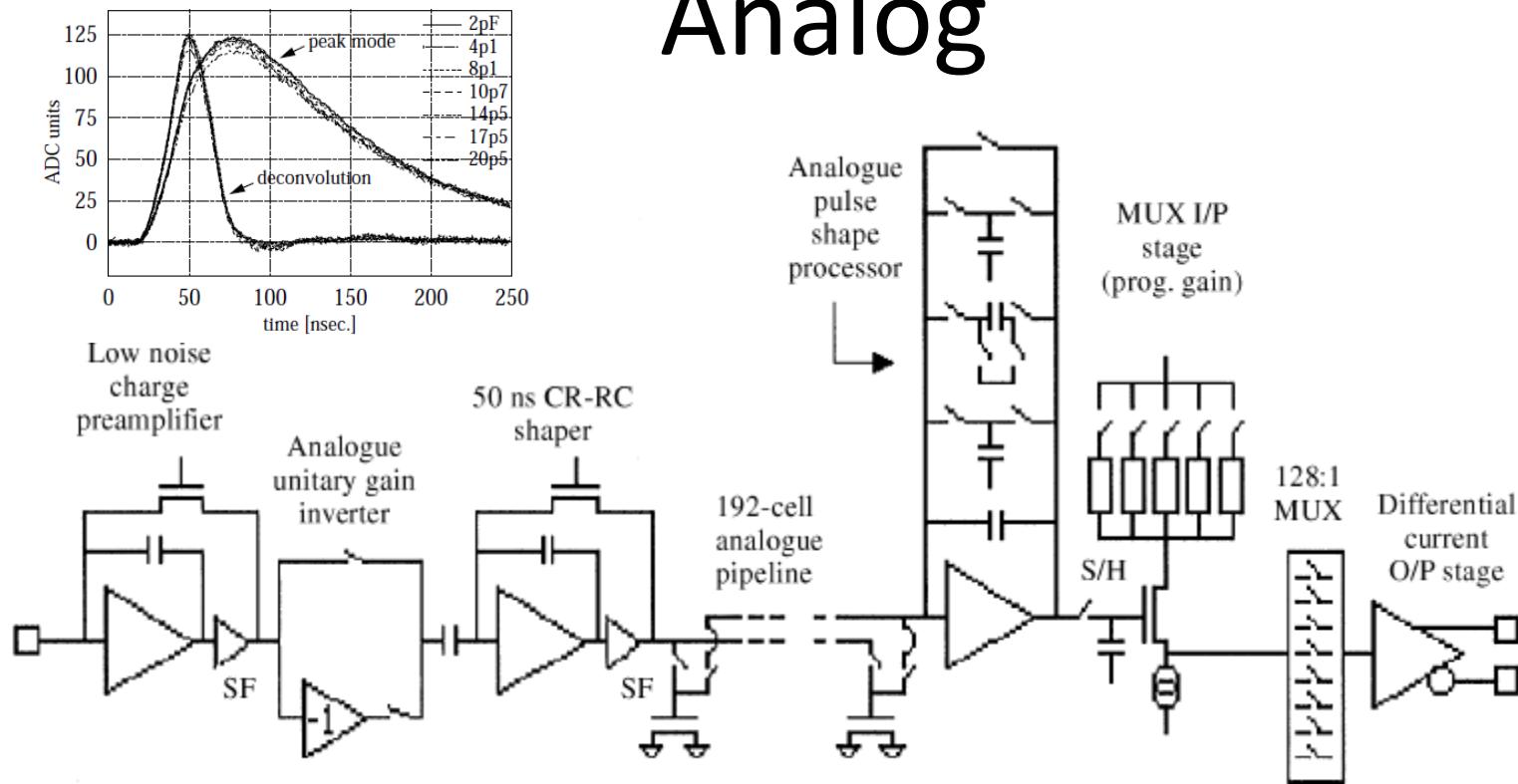
- Front End Architectures
- Fast Cluster Finding Architecture
- Thermally enhanced materials
- Newer processes
- Electronic Packaging
- Production Lines

Double Correlated Sample and Hold



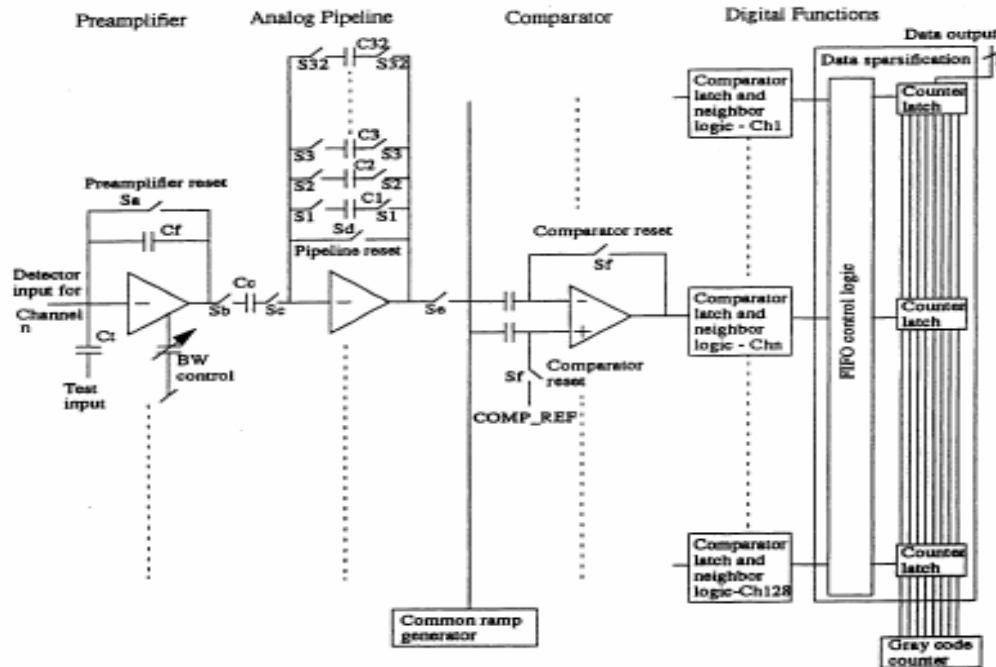
- Original MOS monolithic architecture, no resistors
- High frequency bandwidth limited by pre-amp
- Low frequency limited by $\Delta T = T_2 - T_1$
- Can be generalized to N samples but incurs a noise penalty factor of $\sqrt{2}$ for each pair

Analog



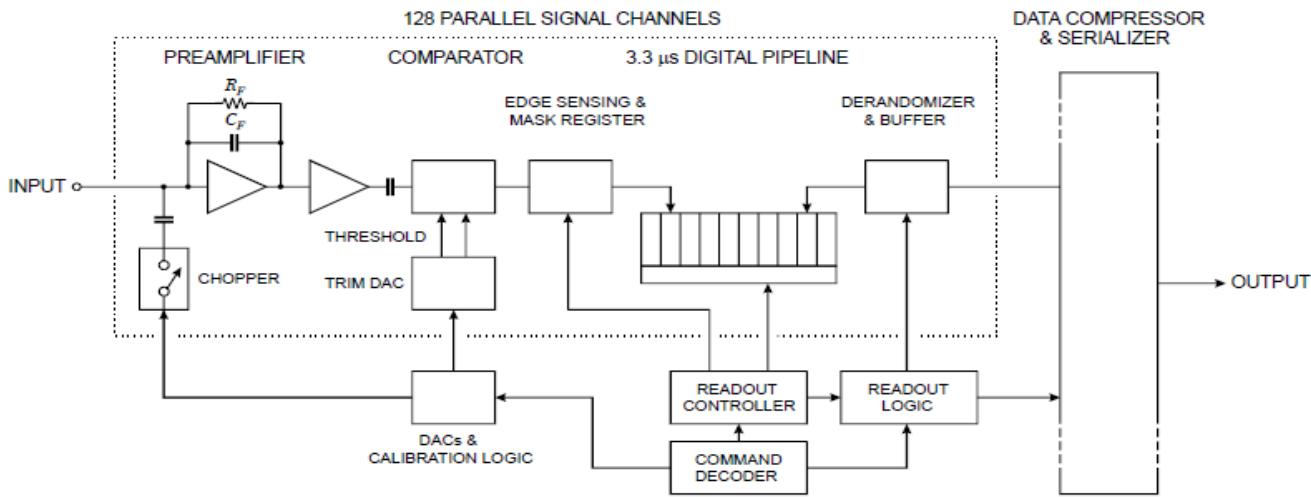
- Example is the APV25 chip developed for CMS
- Readout all analog pulse heights, no sparsification
- Dual function: fast time mode, slow low noise mode
- Utilize analog signal processing on-chip to measure pulse time

Digital



- Example is the SVX4 chip developed for CDF
- Switched capacitor analog pipeline
- Combined analog threshold + 8 bit digitization
- Sparse readout

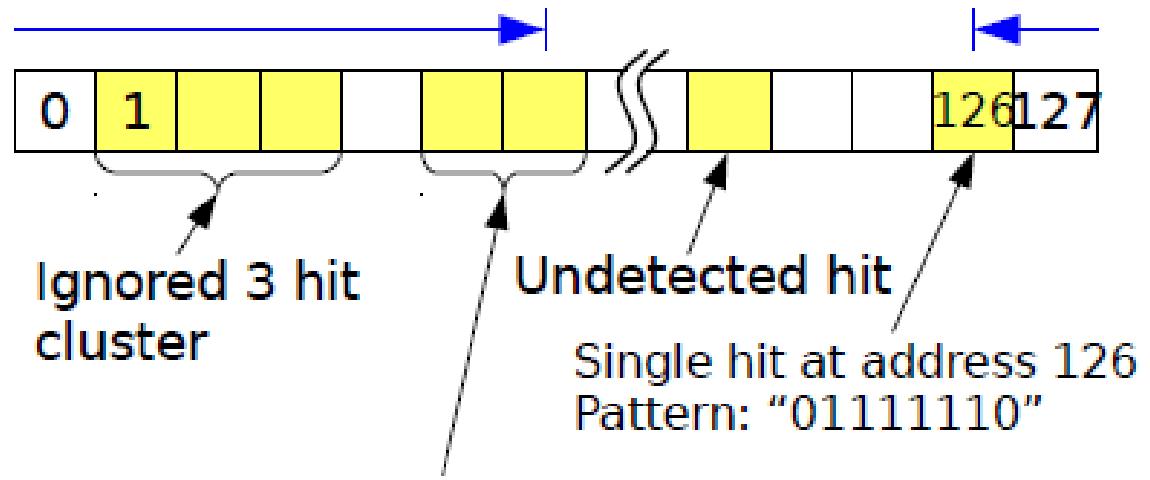
Binary



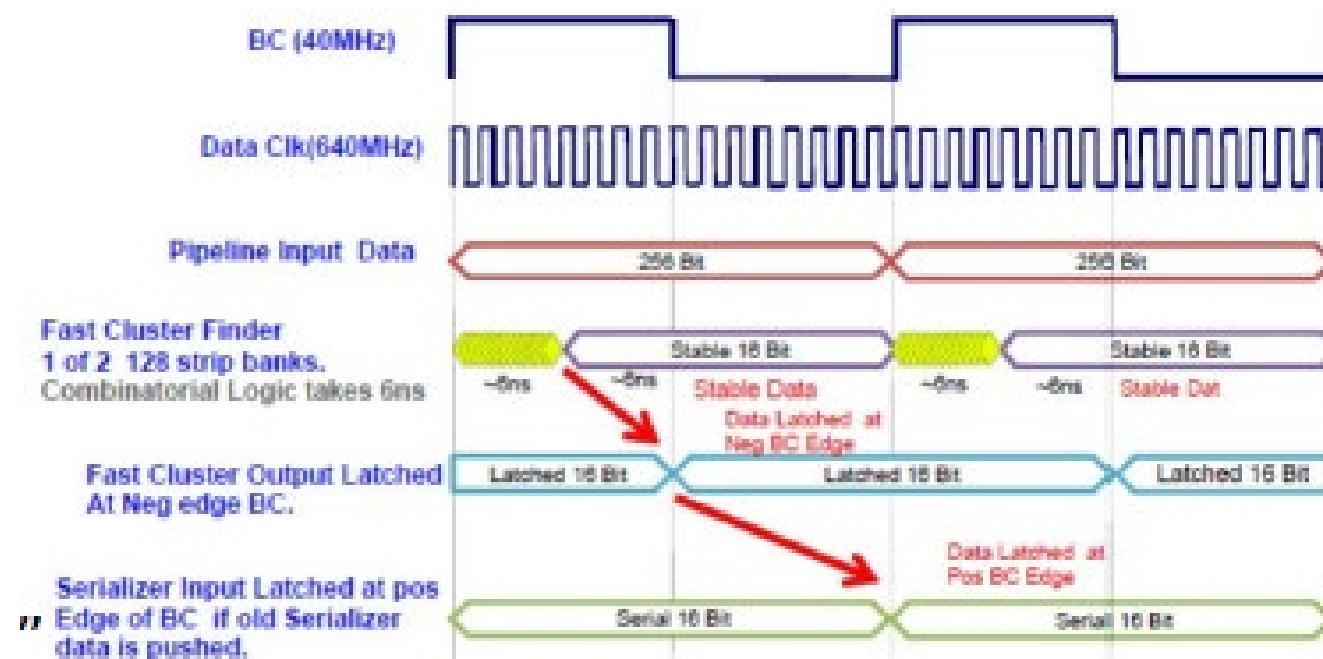
- Example is the ABC chip developed for ATLAS, BiCMOS
- AC coupled pre-amplifier shaper for 25 ns collisions
- Comparator + trim DAC per channel
- 1 bit pipeline clocked at 40 MHz, L1 buffer
- Data compression
- Control and configuration protocol
- DSM CMOS version exists as well, 130 nm underway

Fast Cluster Finder

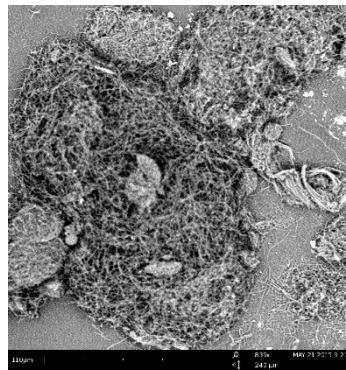
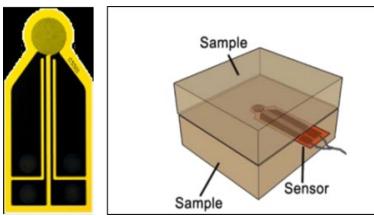
- Normal operation
 - Beam clock advances FE pipeline
 - Readout clock at beam clock rate or more pushes data out for full readout
- Possible to do a fast internal search for a limited number of clusters (hits)
- Read these out on dedicated lines at hundreds of MHz
- Sufficient to supply 2x16 bit addresses per BC which is OK for <1% occupancy, more for



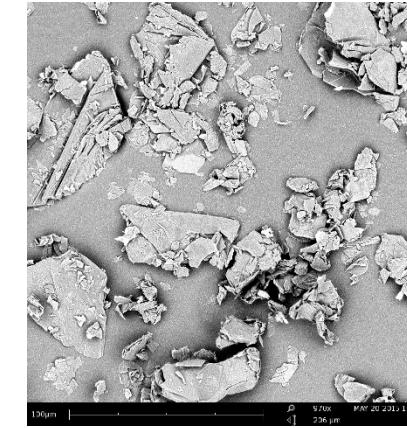
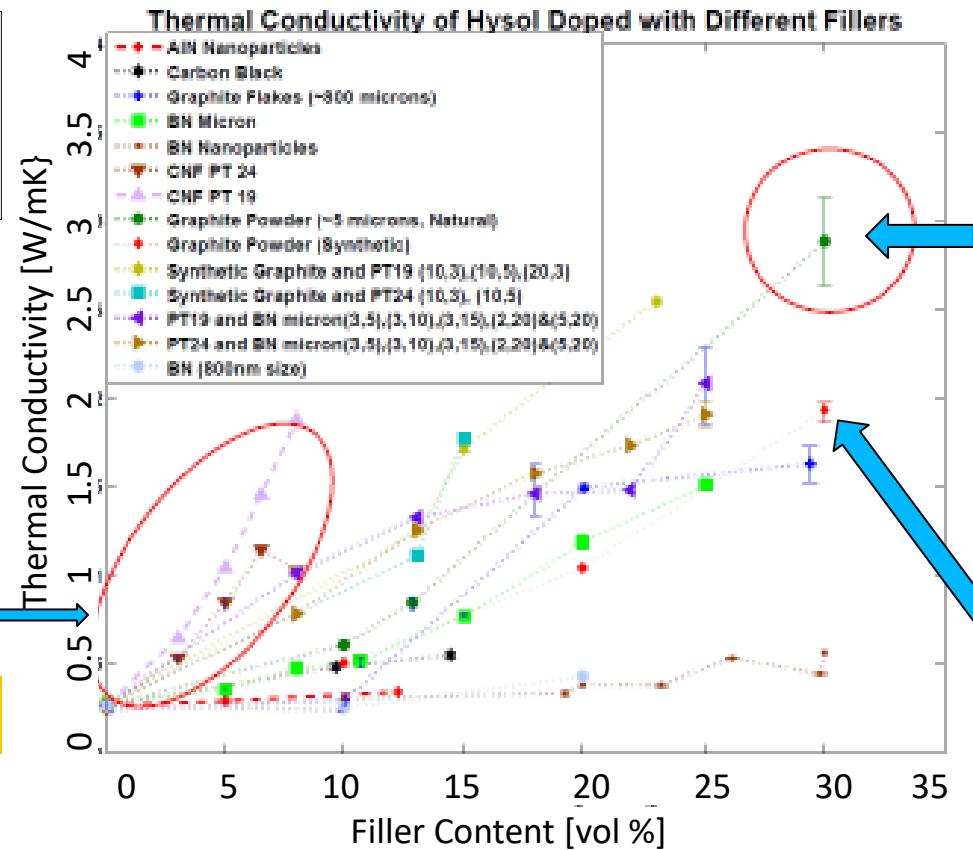
Double hit at address 5, Pattern: "10000101"



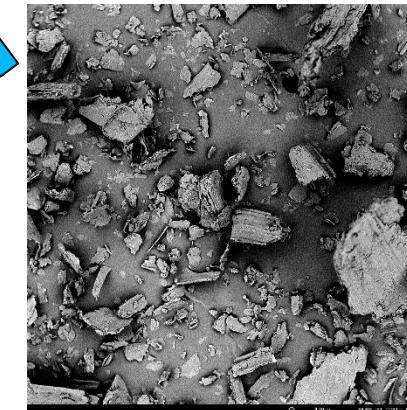
Example: Thermally Enhanced Materials Survey



Carbon NanoFiber



Natural graphite



Synthetic graphite

Loading of epoxy or other adhesives

Typical materials in present use for HEP: 1-1.25 W/mK

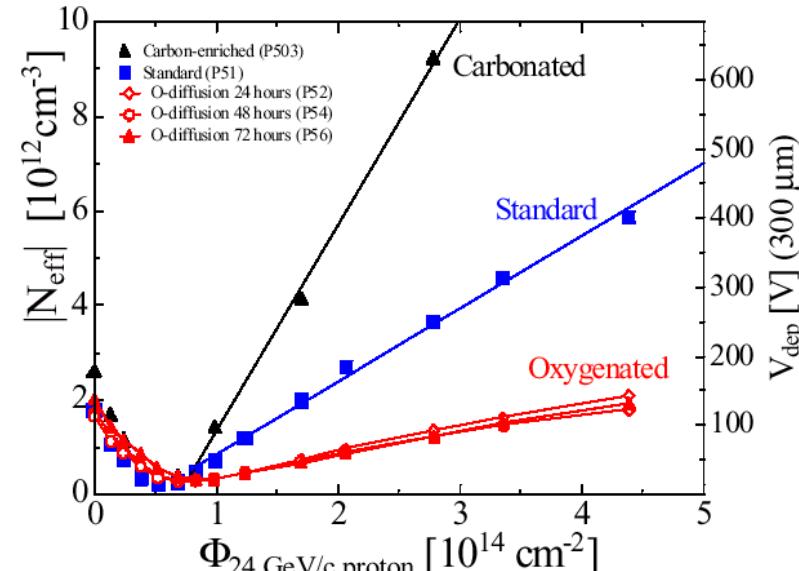
Can improve by $x > 2$...

New developments

- Engineered materials
- New configurations, 3D electrodes, interleaved strips
- Cryogenics
- Alternate materials: Diamond, SiC,...
- RD efforts organized at CERN
 - RD42: development of diamond as detector
 - RD48: radiation damage to silicon
 - RD50: development of radiation resistant detectors
 - RD39: cryogenic detectors and systems
 - <http://rdXY.web.cern.ch/rdXY>

Engineered Silicon

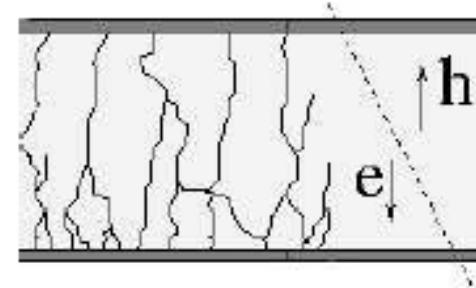
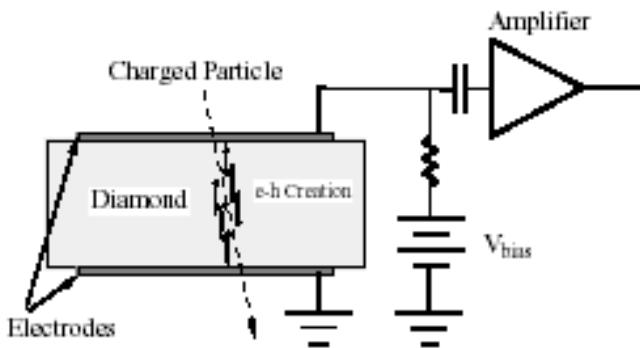
- Microscopic understanding of damage mechanisms, defects, and kinetics
 - Modeling
 - Measurements
 - Time and temperature dependence
- Engineer the silicon for greater radiation resistance



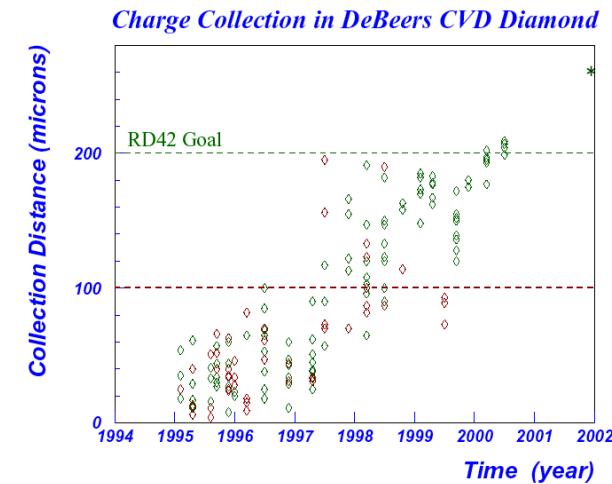
[RD48-NIMA 465(2001) 60]

Characterization of Diamond:

Signal formation

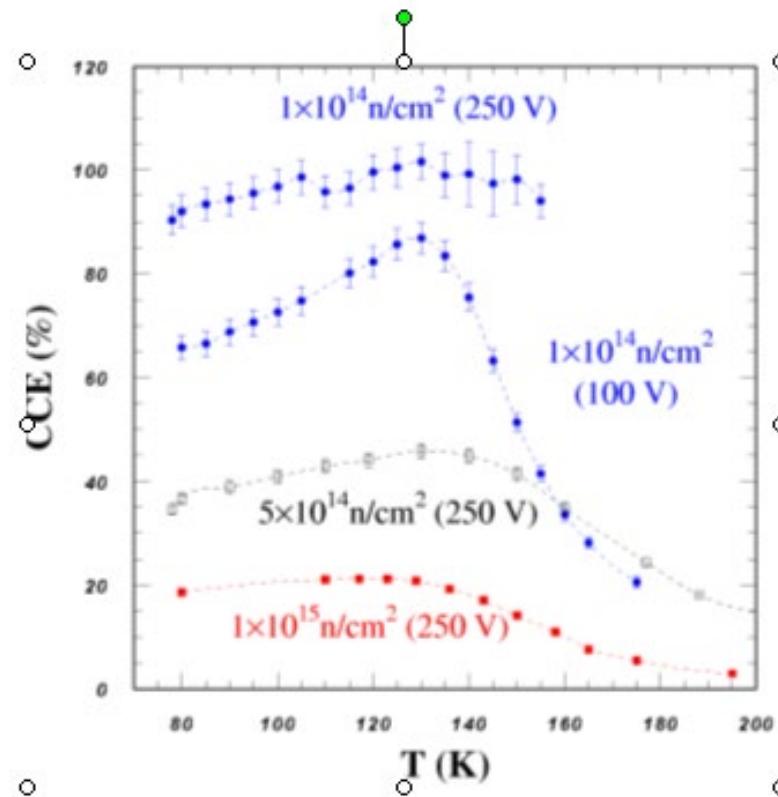


- $Q = \frac{d}{t} Q_0$ where d = collection distance = distance e-h pair move apart
- $d = (\mu_e \tau_e + \mu_h \tau_h) E$
- $d = \mu E \tau$
with $\mu = \mu_e + \mu_h$
and $\tau = \frac{\mu_e \tau_e + \mu_h \tau_h}{\mu_e + \mu_h}$



Cryogenic operation

- Palmieri et al (1998) recovery of lost CCE at cryogenic temperatures
- “Lazarus Effect” due to freeze-out of traps
- R&D activity centered at CERN (RD39)
- Practical difficulty for “low mass” tracker if substantial cryogenic engineering and infrastructure is required.



High Density Packaging

- Electronic packaging is often the only “reducible” part of the detector mass
- Advances in packaging have allowed us to integrate increasing complexity into denser footprints
- Maintain necessary thermal performance with minimized mass and high reliability
- Key technologies are based upon commercial processes
- Avoid the homemade syndrome

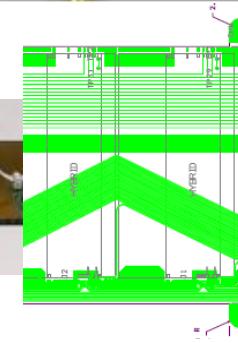
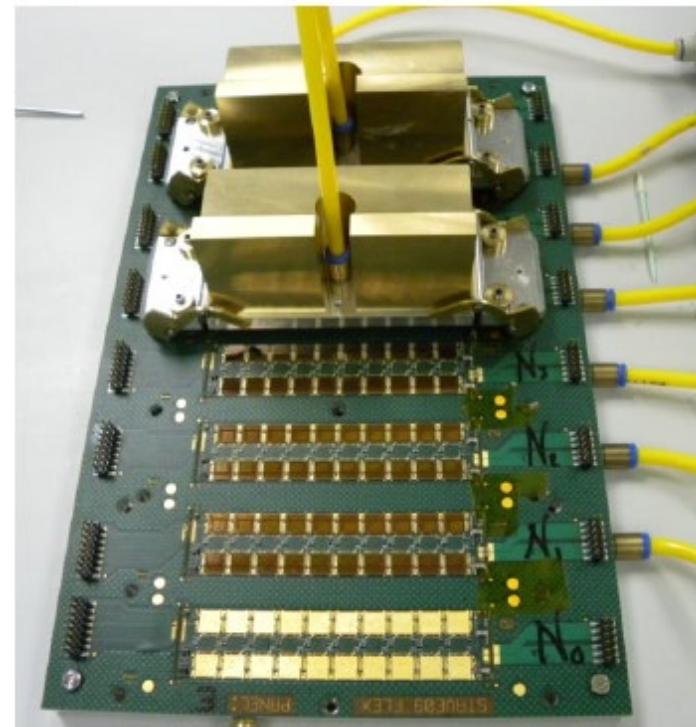
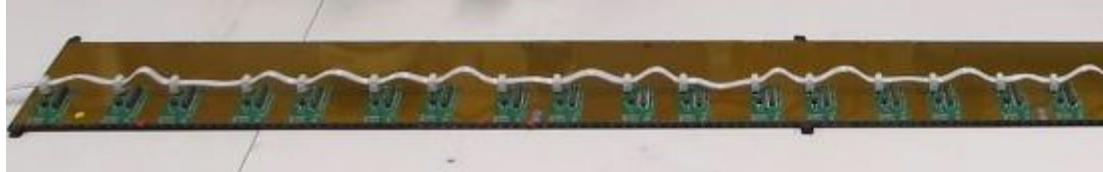
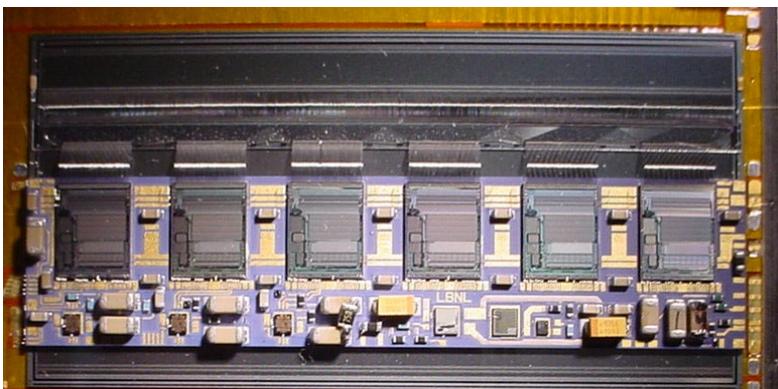
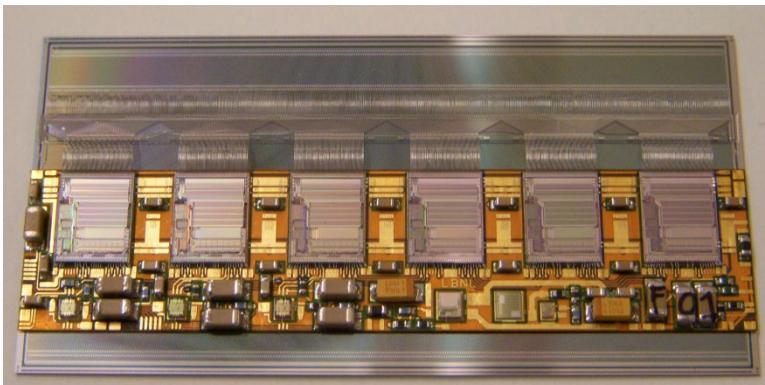
Key Technologies

- Surface mount technology (SMT), pick & place
- Flexible circuits
- High density multilayer PCB and flex
 - Trace widths/space approaching 25 μm
- Large area flexible circuits > 1 meter length
- Chip on Board (COB) and Chip on Flex
- Thin film on ceramic, glass, and polyimide
- Thick film on ceramic, BeO and AlN substrates
- Lamination onto high-TC carbon substrates

Electrical Materials

| material | Resistivity ($\mu\Omega\text{cm}$) | dielectric constant | Xo(cm) | Thermal C. (W/m $^{\circ}\text{K}$) | CTE (ppm) |
|-------------------------|---|------------------------|--------|---|-----------|
| Silicon | | 11.9 | 9.37 | 149 | 2.6 |
| Aluminum | 2.65 | | 8.9 | 237 | 23.9 |
| Copper | 1.67 | | 1.43 | 398 | 16.6 |
| Gold | 2.44 | | 0.335 | 297 | 14.2 |
| Carbon | 1375 | | 19.32 | varies | |
| Kapton | | 3.4 | 28.4 | 0.2 | \sim 20 |
| SiO_2 | | 3.9 | 10 | 1.1 | |
| BeO | 10^{21} | 6.6 | 14.4 | 230 | 8.3 |
| AlN | $>10^{20}$ | 9 | 8.4 | 170 | 4.3 |
| Al_2O_3 | $>10^{20}$ | 9.0 | 7.55 | 24 | 7.2 |
| G-10 | | 4.7 | 19.4 | 0.2 | |

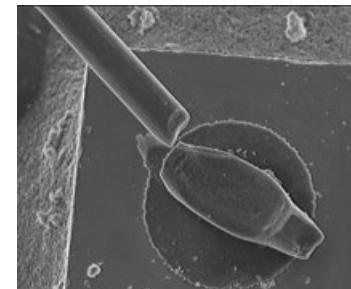
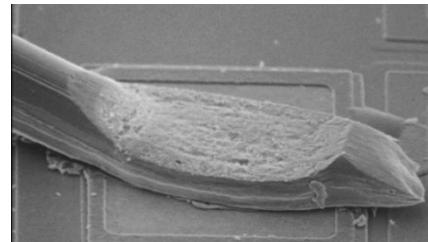
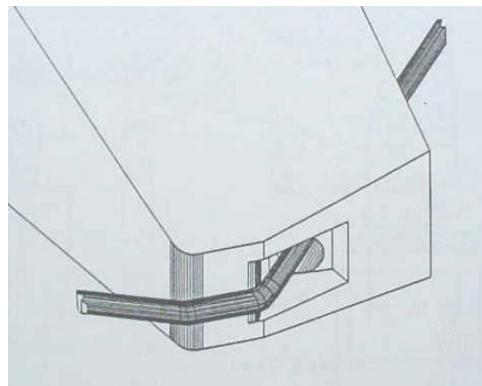
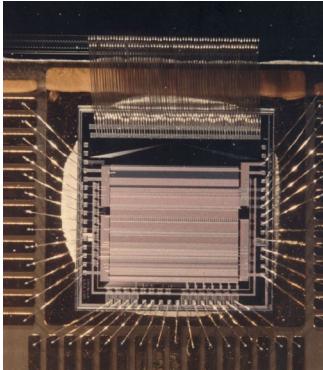
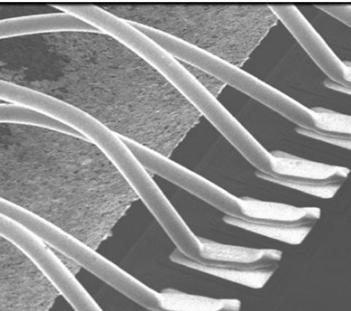
Technology examples



Emerging Interconnects

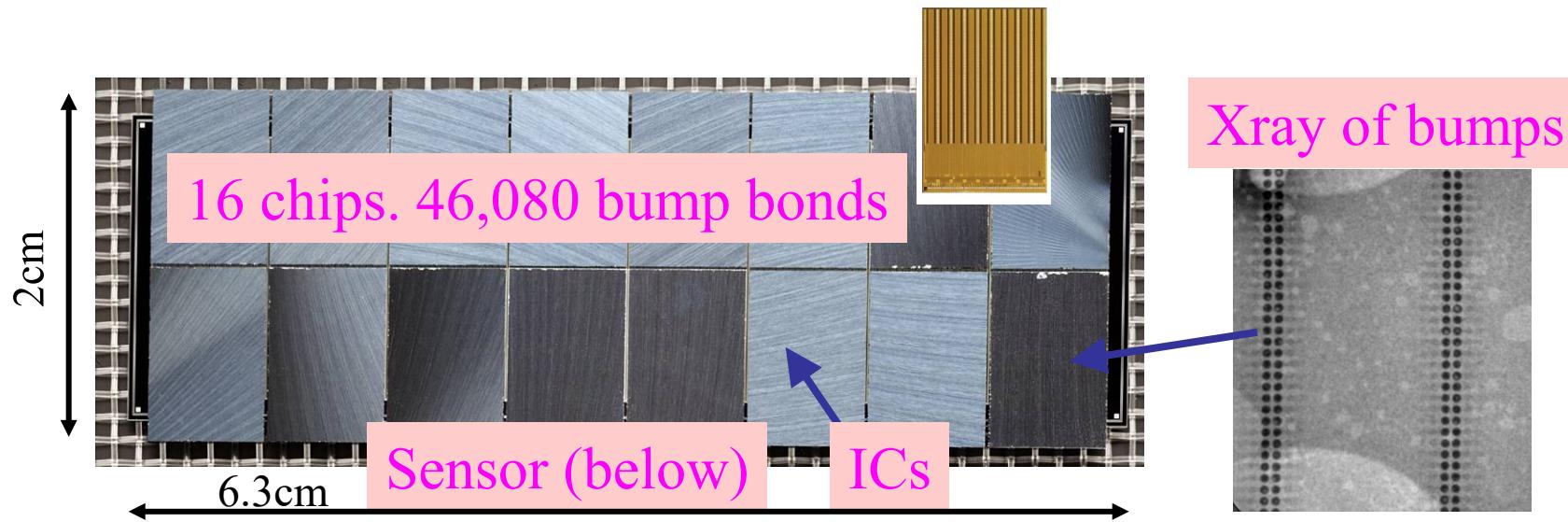
| Attribute | Standard (Epoxy Glass or Polyimide) | HDI: Dense (Particle Filled Epoxy) | HDI: LCP (liquid crystal polymer) | HDI: PTFE (PTFE) |
|-------------------------|---|--|---|---------------------|
| Line width | 75 microns | 25 microns | 37.5 microns | 25 microns |
| Line space | 75 microns | 25 microns | 37.5 microns | 33 microns |
| Via type | mechanical | laser | Laser | laser |
| Via diameter | 200 microns | 50 microns | 50 microns | 50 microns |
| Stacked vias | Build up only | Build up only | In 2010 | In 2010 |
| Capture pad diameter | 400 microns | 100 microns | 110 microns | 110 microns |
| Surface finish | E-less Ni / I Au, ENEPIG | Same | Same | Same |
| Solder mask | yes | yes | yes | no |
| Thickness | <1mm | 0.4 - .7mm | 0.5mm | 0.5mm |
| Layers | 10 | 12 | 4, 6 in 1 st article | 11 |

Wirebonding



- Mainstay of microelectronic interconnection
- Typically uses $25 \mu\text{m}$ Al or Au wire, ultrasonic welding process
- Requires particular control of materials, cleanliness, and process
- Automated (5 bonds/sec) machines are commercially available and in widespread use in the HEP and related communities
- $75 \mu\text{m}$ pitch is achievable with good process control, a typical HEP “module” might contain ~ 5000 bonds

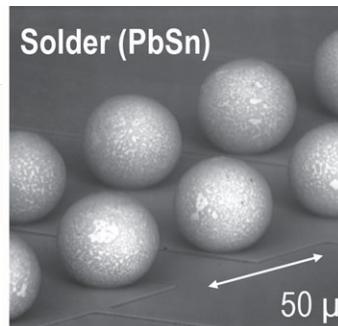
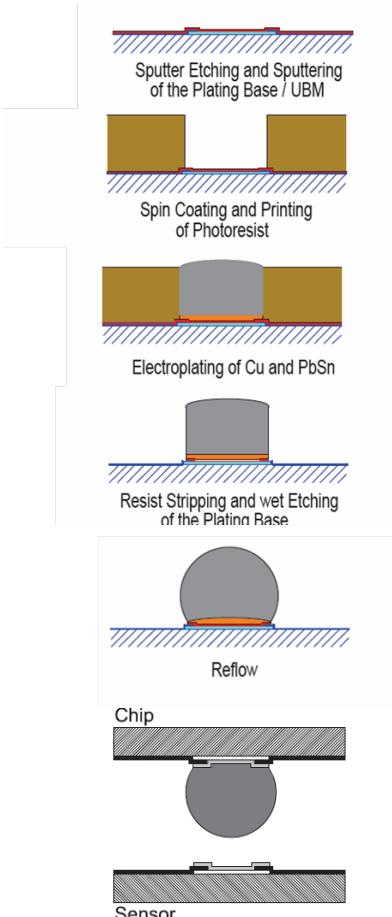
Bump or Flip Chip Bonding



- Wirebonding is impractical for large 2D arrays
- ATLAS pixel cell is $50 \times 250 \mu\text{m}$
- At this density FE interconnect is made with a conductive “bump”
- This is an industrial process and requires expensive technology, therefore has not become “in-house”

Bump Bonding Processes

SOLDER BUMPING



INDIUM BUMPING

